

INTERNATIONAL STANDARD

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62014-1

First edition
2001-05

Electronic design automation libraries –

Part 1: Input/output buffer information specifications (IBIS version 3.2)



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International Electrotechnical Commission
Международная Электротехническая Комиссия

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INTERNATIONAL ELECTROTECHNICAL COMMISSION

ELECTRONIC DESIGN AUTOMATION LIBRARIES-**Part 1: Input/output buffer information specifications
(IBIS version 3.2)**

FOREWORD

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International Standard IEC 62014-1 has been prepared by IEC technical committee 93: Design Automation

This standard is based on ANSI-EIA-656-A (September 1999): I/O buffer information specifications (IBIS) version 3.2

The text of this standard is based on the following documents:

FDIS	Report on voting
93/129/FDIS	93/136/RVD

Full information on the voting for the approval of this standard can be found in the report on voting indicated in the above table.

This standard does not follow the rules for the structure of international standards given in Part 3 of the ISO/IEC Directives.

IEC 62014 consists of the following parts:

IEC 62014-1, *Electronic design automation libraries – Part 1: Input/Output buffer information specifications (IBIS version 3.2)*

IEC 62014-2, *Electronic design automation libraries – Part 2: Library standard architectures (TR)(under consideration)*

IEC 62014-3, *Electronic design automation libraries – Part 3: Modules of integrated circuits for EMI Behavioural simulation (under consideration)*

The committee has decided that the contents of this publication will remain unchanged until 2004. At this date, the publication will be

- reconfirmed;
- withdrawn;
- replaced by a revised edition, or
- amended.

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INTRODUCTION

Background of IBIS

IBIS was first developed at Intel Corporation and has been expanded to its current form (Version 3.2) through the cooperative efforts of additional analog simulator vendors, computer manufacturers, IC vendors, commercial users, and universities. In May 1993, the group formed itself into the IBIS Open Forum, an open, voluntary, cooperative association. In March 1995, the group affiliated with the EIA (now the Electronic Industries Alliance) as the EIA IBIS Open Forum.

The Forum has been and continues to meet via teleconference approximately every third week to propose updates to the IBIS standard, to help new participants, and to advance the standard. The Forum also meets in person about four times a year to exchange ideas and conduct official business.

Most of the Forum activities are handled through e-mail discussions using a reflector "ibis@eda.org." A users group reflector "ibis-users@eda.org" is also supported for users of IBIS. One can get more information on subscribing to the reflectors and to other ongoing Forum activities through the official web page: "<http://www.eigroup.org/ibis/ibis.htm>". The process of making changes and improvements to IBIS is through a "BIRD" (Buffer Issue Resolution

Document) process involving approval by the Forum voting members. Over the years the Forum has grown to over thirty voting members (requiring a modest yearly fee for administrative support), but the Forum also maintains an open, public communications policy and welcomes all interested participants regardless of membership status.

Through official EIA and ANSI (American National Standards Institution) public letter ballot processes, IBIS Version 2.1 was ratified as ANSI/EIA-656 in December 13, 1995. Version 1.1 of IBIS focused on TTL and CMOS logic components. Although never officially ratified as a national standard, IBIS Version 1.1 served as a basis for advances in Version 2.1 to increase its accuracy and number of device types that are supported.

Version 2.1 contains the following advances:

- Controlled slew rate devices
- ECL and PECL technologies
- Independent control over power rails so RS232 and other types of devices with multiple rails can be modeled
- Differential drivers and devices
- Open-drain I/O devices such as open drain and open collector devices
- Expanded package model definitions to include coupling between pins.

The Forum also voluntarily funded a parser development activity through the sale of source code licenses of "ibischk2" and has made executables of the parser code freely and publicly available to enable IBIS model checking.

Industrial advances associated with new semiconductor topologies, package design and measurement needs kept the Forum busy proposing new capabilities, eventually leading to IBIS Version 3.2. Again through official EIA and ANSI public letter ballot processes, IBIS Version 3.2 was ratified as ANSI/EIA-656-A on September 21, 1999.

Its advances include the following:

- Series and series switch models
- Multi-stage driver capability for phased stages

- Submodel capability supporting dynamic clamps and bus hold functions for active and dynamic terminations
- More specification values for overshoot and pulse immunity
- Uncoupled packages with sections and forks
- Uncoupled advanced packages known as electrical board descriptions with sections, forks and on-board components.

IBIS Version 3.2 has complied with an original Forum objective that all subsequent versions of IBIS be backward compatible with previous versions.

The Forum funded through voluntary source code license purchases the corresponding "ibischk3" parser and has made its executables freely available.

The IBIS Standard has achieved wide spread national and international support and recognition as indicated by over 40 semiconductor vendors providing IBIS models freely from their web sites. Many more IBIS models and libraries are available from commercial vendors and directly through IC vendor sales organizations. While IBIS models can be of value in all phases of a design and analysis process, they are particularly suitable for printed circuit board design tools used in conjunction with the corresponding physical and mechanical data bases describing the boards.

Future IBIS Directions

Technology continues to advance, forcing more stringent electrical requirements and newer ways of doing things. The Forum is keeping up with such advances. However, its strategy has shifted. Up to now the Forum has been adding to the existing fixed-format IBIS document. Such a process is slow and subject to unexpected interactions with existing capability. The newer approach is to create a compatible macro-language that allows more rapid reconfiguration and response to changing needs.

While the Forum has not yet ratified any of these approaches, it is pursuing these projects:

- A macro-language that fully supports IBIS Version 3.2 but can also support more advanced features and nodal component structures
- A separate Connector Specification with advanced coupled stages to support key component used to connect printed circuit boards (and possibly be used for more advanced package models)
- Some further advances in specification details beyond IBIS Version 3.2.

These projects advance the capability of IBIS in a manner that supports the existing IBIS Version 3.2 functionality, but also allows for much more rapid implementation of new requirements.

References

ANSI/EIA-656: IBIS Version 2.1 released December 13, 1995

ANSI/EIA-656-A: IBIS Version 3.2 released September 21, 1999

ELECTRONIC DESIGN AUTOMATION LIBRARIES –**Part 1: Input/output buffer information specifications
(IBIS version 3.2)****Scope and object**

This standard gives specifications for electronic behavioral of digital integrated circuit input/ output analog characteristics. It specifies a consistent software-parsable format for essential behavioral information.

The goal of this standard is to support all simulators of all degrees of sophistication.

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Section 1

GENERAL INTRODUCTION

This section gives a general overview of the remainder of this document.

Sections 2 and 3 contain general information about the IBIS versions and the general rules and guidelines. Several progressions of IBIS documents are referenced in Section 2 and in the discussion below. They are IBIS Version 1.1 (ratified August, 1993), IBIS Version 2.1 (ratified as ANSI/EIA-656 in December, 1995), and IBIS Version 3.2 (this document ratified in August, 1999).

The functionality of IBIS follows in Sections 4 through 8. Sections 4 through 6 describe the format of the core functionality of IBIS Version 1.1 and the extensions in later versions. The data in these sections are contained in .ibs files. Section 7 describes the package model format of IBIS Version 2.1 and a subsequent extension. Package models can be formatted within .ibs files or can be formatted (along with the Section 4 file header keywords) as .pkg files. Section 8 contains the Electrical Board Description format of IBIS Version 3.2. Along with Section 4 header information, electrical board descriptions must be described in separate .ebd files.

Section 9 contains some notes regarding the extraction conditions and data requirements for IBIS files. This section focuses on implementation conditions based on measurement or simulation for gathering the IBIS compliant data.

Section 2

S T A T E M E N T O F I N T E N T

In order to enable an industry standard method to electronically transport IBIS Modeling Data between semiconductor vendors, simulation vendors, and end customers, this template is proposed. The intention of this template is to specify a consistent format that can be parsed by software, allowing simulation vendors to derive models compatible with their own products.

One goal of this template is to represent the current state of IBIS data, while allowing a growth path to more complex models / methods (when deemed appropriate). This would be accomplished by a revision of the base template, and possibly the addition of new keywords or categories.

Another goal of this template is to ensure that it is simple enough for semiconductor vendors and customers to use and modify, while ensuring that it is rigid enough for simulation vendors to write reliable parsers.

Finally, this template is meant to contain a complete description of the I/O elements on an entire component. Consequently, several models will need to be defined in each file, as well as a table that equates the appropriate buffer to the correct pin and signal name.

Version 3.2 of this electronic template was finalized by an industry-wide group of experts representing various companies and interests. Regular "EIA IBIS Open Forum" meetings were held to accomplish this task.

Commitment to Backward Compatibility. Version 1.0 is the first valid IBIS ASCII file format. It represents the minimum amount of I/O buffer information required to create an accurate IBIS model of common CMOS and bipolar I/O structures. Future revisions of the ASCII file will add items considered to be "enhancements" to Version 1.0 to allow accurate modeling of new, or other I/O buffer structures. Consequently, all future revisions will be considered supersets of Version 1.0, allowing backward compatibility. In addition, as modeling platforms develop support for revisions of the IBIS ASCII template, all previous revisions of the template must also be supported.

Version 1.1 update. The file "ver1_1.ibs" is conceptually the same as the 1.0 version of the IBIS ASCII format (ver1_0.ibs). However, various comments have been added for further clarification.

Version 2.0 update. The file "ver2_0.ibs" maintains backward compatibility with Versions 1.0 and 1.1. All new keywords and elements added in Version 2.0 are optional. A complete list of changes to the specification is in the IBIS Version 2.0 Release Notes document ("ver2_0.rn").

Version 2.1 update. The file "ver2_1.ibs" contains clarification text changes, corrections, and two additional waveform parameters beyond Version 2.0.

Version 3.0 update. The file "ver3_0.ibs" adds a number of new keywords and functionality. A complete list of functions can be found on eda.org under /pub/ibis/birds/birddir.txt showing the approved Buffer Issue Resolution Documents (BIRDS) that have been approved for Version 3.0.

Version 3.1 update. The file "ver3_1.ibs" contains a major reformatting of the document and a simplification of the wording. It also contains some new technical enhancements that were unresolved when Version 3.0 was approved.

Version 3.2 update. The file "ver3_2.ibs" adds more technical advances and also a number of editorial changes documented in 12 BIRDS and also in responses to public letter ballot comments.

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Section 3

GENERAL SYNTAX RULES AND GUIDELINES

This section contains general syntax rules and guidelines for ASCII IBIS files:

- 1) The content of the files is case sensitive, except for reserved words and keywords.
- 2) The following words are reserved words and must not be used for any other purposes in the document:
 - POWER - reserved model name, used with power supply pins,
 - GND - reserved model name, used with ground pins,
 - NC - reserved model name, used with no-connect pins,
 - NA - used where data not available.
- 3) To facilitate portability between operating systems, file names used in the IBIS file must only have lower case characters. File names should have a basename of no more than twenty characters followed by a period ('.'), followed by a file name extension of no more than three characters. The file name and extension must use characters from the set (space, ' ', 0x20 is not included):

```
a b c d e f g h i j k l m n o p q r s t u v w x y z
0 1 2 3 4 5 6 7 8 9 _ ^ $ % & ' { } ) ( @ ' `
```

The file name and extension are recommended to be lower case on systems that support such names.

- 4) A line of the file may have at most 80 characters, followed by a line termination sequence. The line termination sequence must be one of the following two sequences: a linefeed character, or a carriage return followed by linefeed character.
- 5) Anything following the comment character is ignored and considered a comment on that line. The default "|" (pipe) character can be changed by the keyword [Comment Char] to any other character. The [Comment Char] keyword can be used throughout the file as desired.
- 6) Keywords must be enclosed in square brackets, [], and must start in column 1 of the line. No space or tab is allowed immediately after the opening bracket '[' or immediately before the closing bracket ']'. If used, only one space (' ') or underscore ('_') character separates the parts of a multi-word keyword.
- 7) Underscores and spaces are equivalent in keywords. Spaces are not allowed in subparameter names.

8) Valid scaling factors are:

T = tera	k = kilo	n = nano
G = giga	m = milli	p = pico
M = mega	u = micro	f = femto

When no scaling factors are specified, the appropriate base units are assumed. (These are volts, amperes, ohms, farads, henries, and seconds.) The parser looks at only one alphabetic character after a numerical entry, therefore it is enough to use only the prefixes to scale the parameters. However, for clarity, it is allowed to use full abbreviations for the units, (e.g., pF, nH, mA, mOhm). In addition, scientific notation IS allowed (e.g., 1.2345e-12).

- 9) The I-V data tables should use enough data points around sharply curved areas of the I-V curves to describe the curvature accurately. In linear regions there is no need to define unnecessary data points.
- 10) The use of tab characters is legal, but they should be avoided as much as possible. This is to eliminate possible complications that might arise in situations when tab characters are automatically converted to multiple spaces by text editing, file transferring and similar software. In cases like that, lines might become longer than 80 characters, which is illegal in IBIS files.
- 11) Currents are considered positive when their direction is into the component.
- 12) All temperatures are represented in degrees Celsius.
- 13) Important supplemental information is contained in the last section, "NOTES ON DATA DERIVATION METHOD", concerning how data values are derived.
- 14) Only ASCII characters, as defined in ANSI Standard X3.4-1986, may be used in an IBIS file. The use of characters with codes greater than hexadecimal 07E is not allowed. Also, ASCII control characters (those numerically less than hexadecimal 20) are not allowed, except for tabs or in a line termination sequence. As mentioned in item 10 above, the use of tab characters is discouraged.

=====

Section 4

FILE HEADER INFORMATION

Keyword: [IBIS Ver]		
Required: Yes		
Description: Specifies the IBIS template version. This keyword informs electronic parsers of the kinds of data types that are present in the file.		
Usage Rules: [IBIS Ver] must be the first keyword in any IBIS file. It is normally on the first line of the file, but can be preceded by comment lines that must begin with a " ".		

[IBIS Ver]	3.2	Used for template variations
=====		
Keyword: [Comment Char]		
Required: No		
Description: Defines a new comment character to replace the default " " (pipe) character, if desired.		
Usage Rules: The new comment character to be defined must be followed by the underscore character and the letters "char". For example: " _char" redundantly redefines the comment character to be the pipe character. The new comment character is in effect only following the [Comment Char] keyword. The following characters MAY be used:		
! " # \$ % & ' () * , . : ; < > ? @ \ ^ ` { } ~		
Other Notes: The [Comment Char] keyword can be used throughout the file, as desired.		

[Comment Char]	_char	
=====		
Keyword: [File Name]		
Required: Yes		
Description: Specifies the name of the IBIS file.		
Usage Rules: The file name must conform to the rules in paragraph 3 of Section 3, "GENERAL SYNTAX RULES AND GUIDELINES". In addition, the file name must use the extension ".ibs", ".pkg", or ".ebd". The file name must be the actual name of the file.		

[File Name]	ver3_2.ibs	
=====		
Keyword: [File Rev]		
Required: Yes		
Description: Tracks the revision level of a particular .ibs file.		
Usage Rules: Revision level is set at the discretion of the engineer defining the file. The following guidelines are recommended:		

	0.x	silicon and file in development
	1.x	pre-silicon file data from silicon model only
	2.x	file correlated to actual silicon measurements
	3.x	mature product, no more changes likely

[File Rev]	1.0	Used for .ibs file variations
=====		
Keywords:	[Date], [Source], [Notes], [Disclaimer], [Copyright]	
Required:	No	
Description:	Optionally clarifies the file.	
Usage Rules:	The keyword arguments can contain blanks, and be of any format. The [Date] keyword argument is limited to a maximum of 40 characters, and the month should be spelled out for clarity.	
	Because IBIS model writers may consider the information in these keywords essential to users, and sometimes legally required, design automation tools should make this information available. Derivative models should include this text verbatim. Any text following the [Copyright] keyword must be included in any derivative models verbatim.	

[Date]	August 20, 1999	The latest file revision date
[Source]	Put originator and the source of information here. For example: From silicon level SPICE model at Intel. From lab measurement at IEI. Compiled from manufacturer's data book at Quad Design, etc.	
[Notes]	Use this section for any special notes related to the file.	
[Disclaimer]	This information is for modeling purposes only, and is not guaranteed. May vary by component	
[Copyright]	Copyright 1999, XYZ Corp., All Rights Reserved	
=====		

Section 5

C O M P O N E N T D E S C R I P T I O N

Keyword:	[Component]	
Required:	Yes	
Description:	Marks the beginning of the IBIS description of the integrated circuit named after the keyword.	
Sub-Params:	Si_location, Timing_location	
Usage Rules:	If the .ibs file contains data for more than one component, each section must begin with a new [Component] keyword. The length of the component name must not exceed 40 characters, and blank characters are allowed.	
	NOTE: Blank characters are not recommended due to usability issues.	
	Si_location and Timing_location are optional and specify where the Signal Integrity and Timing measurements are made for the component. Allowed values for either subparameter are 'Die' or 'Pin'. The default location is at the 'Pin'.	

[Component]	7403398 MC452	
Si_location	Pin	Optional subparameters to give measurement location positions
Timing_location	Die	
=====		
Keyword:	[Manufacturer]	
Required:	Yes	
Description:	Specifies the manufacturer's name of the component.	
Usage Rules:	The length of the manufacturer's name must not exceed 40 characters (blank characters are allowed, e.g., Texas Instruments). In addition, each manufacturer must use a consistent name in all .ibs files.	

[Manufacturer]	Intel Corp.	
=====		
Keyword:	[Package]	
Required:	Yes	
Description:	Defines a range of values for the default packaging resistance, inductance, and capacitance of the component pins.	
Sub-Params:	R_pkg, L_pkg, C_pkg	
Usage Rules:	The typical (typ) column must be specified. If data for the other columns are not available, they must be noted with "NA".	
Other Notes:	If RLC parameters are available for individual pins, they can be listed in columns 4-6 under keyword [Pin]. The values listed in the [Pin] description section override the default values defined here. Use the [Package Model] keyword for more complex package descriptions. If defined, the [Package Model] data overrides the values in the [Package] keyword.	

Regardless, the data listed under the [Package] keyword must still contain valid data.

[Package]

variable	typ	min	max
R_pkg	250.0m	225.0m	275.0m
L_pkg	15.0nH	12.0nH	18.0nH
C_pkg	18.0pF	15.0pF	20.0pF

Keyword: [Pin]

Required: Yes

Description: Associates the component's I/O models to its various external pin names and signal names.

Sub-Params: signal_name, model_name, R_pin, L_pin, C_pin

Usage Rules: All pins on a component must be specified. The first column must contain the pin name. The second column, signal_name, gives the data book name for the signal on that pin. The third column, model_name, maps a pin to a specific I/O buffer model or model selector name. Each model_name must have a corresponding model or model selector name listed in a [Model] or [Model Selector] keyword below, unless it is a reserved model name (POWER, GND, or NC).

Each line must contain either three or six columns. A pin line with three columns only associates the pin's signal and model. Six columns can be used to override the default package values (specified under [Package]) FOR THAT PIN ONLY. When using six columns, the headers R_pin, L_pin, and C_pin must be listed. If "NA" is in columns 4 through 6, the default packaging values must be used. The headers R_pin, L_pin, and C_pin may be listed in any order.

Column length limits are:

[Pin]	5 characters max
model_name	20 characters max
signal_name	20 characters max
R_pin	9 characters max
L_pin	9 characters max
C_pin	9 characters max

[Pin]	signal_name	model_name	R_pin	L_pin	C_pin
1	RAS0#	Buffer1	200.0m	5.0nH	2.0pF
2	RAS1#	Buffer2	209.0m	NA	2.5pF
3	EN1#	Input1	NA	6.3nH	NA
4	A0	3-state			
5	D0	I/O1			
6	RD#	Input2	310.0m	3.0nH	2.0pF
7	WR#	Input2			
8	A1	I/O2			
9	D1	I/O2			
10	GND	GND	297.0m	6.7nH	3.4pF
11	RDY#	Input2			
12	GND	GND	270.0m	5.3nH	4.0pF

18	Vcc3	POWER			
19	NC	NC			
20	Vcc5	POWER	226.0m	NA	1.0pF

Keyword: [Package Model]

Required: No

Description: Indicates the name of the package model to be used for the component

Usage Rules: The package model name is limited to 40 characters. Spaces are allowed in the name. The name should include the company name or initials to help ensure uniqueness. The simulator will search for a matching package model name as an argument to a [Define Package Model] keyword in the current IBIS file first. If a match is not found, the simulator will next look for a match in an external .pkg file. If the matching package model is in an external .pkg file, it must be located in the same directory as the .ibs file. The file names of .pkg files must follow the rules for file names given in section 3, General Syntax Rules and Guidelines.

Other Notes: Use the [Package Model] keyword within a [Component] to indicate which package model should be used for that component. The specification permits .ibs files to contain [Define Package Model] keywords as well. These are described in the "Package Modeling" section near the end of this specification. When package model definitions occur within a .ibs file, their scope is "local"--they are known only within that .ibs file and no other. In addition, within that .ibs file, they override any globally defined package models that have the same name.

[Package Model] QS-SMT-cer-8-pin-pkgs

Keyword: [Pin Mapping]

Required: No

Description: Used to indicate which power and ground buses a given driver, receiver, or terminator is connected to.

Sub-Params: pulldown_ref, pullup_ref, gnd_clamp_ref, power_clamp_ref

Usage Rules: Each power and ground bus is given a unique name that must not exceed 15 characters. The first column contains a pin name. Each pin name must match one of the pin names declared previously in the [Pin] section of the IBIS file. The second column, pulldown_ref, designates the ground bus connections for that pin. Here the term ground bus can also mean another power bus. The third column pullup_ref designates the power bus connection. The fourth and fifth columns gnd_clamp_ref and power_clamp_ref contain entries, if needed, to specify different ground bus and power bus connections than those previously specified.

If the [Pin Mapping] keyword is present, then the bus connections for EVERY pin listed in the [Pin] section must be given.

Each line must contain either three or five columns. Use the

NC reserved word for entries that are not needed or that follow the conditions below:

All entries with identical labels are assumed to be connected. Each unique entry label must connect to at least one pin whose model_name is POWER or GND.

If a pin has no connection, then both the pulldown_ref and pullup_ref subparameters for it will be NC.

GND and POWER pin entries and buses are designated by entries in either the pulldown_ref or pullup_ref columns. There is no implied association to any column other than through explicit designations in other pins.

For any other type of pin, the pulldown_ref column contains the power connection for the [Pulldown] table for non-ECL type [Model]s. This is also the power connection for the [GND Clamp] table and the [Rgnd] model unless overridden by a specification in the gnd_clamp_ref column.

Also, the pullup_ref column contains the power connection for the [Pullup] table and, for ECL type models, the [Pulldown] table. This is also the power connection for the [POWER Clamp] table and the [Rpower] model unless overridden by a specification in the power_clamp_ref column.

The column length limits are:

[Pin Mapping]	5 characters max
pulldown_ref	15 characters max
pullup_ref	15 characters max
gnd_clamp_ref	15 characters max
power_clamp_ref	15 characters max

When 5 columns are specified, the headings gnd_clamp_ref and power_clamp_ref must be used. Otherwise, these headings can be omitted.

[Pin Mapping]	pulldown_ref	pullup_ref	gnd_clamp_ref	power_clamp_ref
1	GNDBUS1	PWRBUS1	Signal pins and their associated ground and power connections	
2	GNDBUS2	PWRBUS2		
3	GNDBUS1	PWRBUS1	GNDCLMP	PWRCLAMP
4	GNDBUS2	PWRBUS2	GNDCLMP	PWRCLAMP
5	GNDBUS2	PWRBUS2	NC	PWRCLAMP
6	GNDBUS2	PWRBUS2	GNDCLMP	NC
			Some possible clamping connections are shown above for illustration purposes	
11	GNDBUS1	NC	One set of ground connections. NC indicates no connection to power bus.	
12	GNDBUS1	NC		
13	GNDBUS1	NC		
21	GNDBUS2	NC	Second set of ground connections	
22	GNDBUS2	NC		
23	GNDBUS2	NC		

31	NC	PWRBUS1	One set of power connections.
32	NC	PWRBUS1	NC indicates no connection to
33	NC	PWRBUS1	ground bus.
41	NC	PWRBUS2	Second set of power connections
42	NC	PWRBUS2	
43	NC	PWRBUS2	
51	GNDCLMP	NC	Additional power connections
52	NC	PWRCLMP	for clamps

Keyword: [Diff Pin]

Required: No

Description: Associates differential pins, their differential threshold voltages, and differential timing delays.

Sub-Params: inv_pin, vdiff, tdelay_typ, tdelay_min, tdelay_max

Usage Rules: Enter only differential pin pairs. The first column, [Diff Pin], contains a non-inverting pin name. The second column, inv_pin, contains the corresponding inverting pin name for I/O output. Each pin name must match the pin names declared previously in the [Pin] section of the IBIS file. The third column, vdiff, contains the specified output and differential threshold voltage between pins if the pins are Input or I/O model types. For output only differential pins, the vdiff entry is 0 V. The fourth, fifth, and sixth columns, tdelay_typ, tdelay_min, and tdelay_max, contain launch delays of the non-inverting pins relative to the inverting pins. The values can be of either polarity.

If a pin is a differential input pin, the differential input threshold (vdif) overrides and supersedes the need for Vinh and Vinl.

If vdiff is not defined for a pin that is defined as requiring a Vinh by its [Model] type, vdiff is set to the default value of 200 mV.

Other Notes: The output pin polarity specification in the table overrides the [Model] Polarity specification such that the pin in the [Diff Pin] column is Non-Inverting and the pin in the inv_pin column is Inverting. This convention enables one [Model] to be used for both pins.

Column length limits are:

[Diff Pin]	5 characters max
inv_pin	5 characters max
vdif	9 characters max
tdelay_typ	9 characters max
tdelay_min	9 characters max
tdelay_max	9 characters max

Each line must contain either four or six columns. If "NA" is entered in the vdiff, tdelay_typ, or tdelay_min columns, its entry is interpreted as 0 V or 0 ns. If "NA" appears in the tdelay_max column, its value is interpreted as the tdelay_typ

value. When using six columns, the headers tdelay_min and tdelay_max must be listed. Entries for the tdelay_min column are based on minimum magnitudes; and tdelay_max column, maximum magnitudes. One entry of vdiff, regardless of its polarity, is used for difference magnitudes.

[Diff Pin]	inv_pin	vdiff	tdelay_typ	tdelay_min	tdelay_max	
3	4	150mV	-1ns	0ns	-2ns	Input or I/O pair
7	8	0V	1ns	NA	NA	Output* pin pair
9	10	NA	NA	NA	NA	Output* pin pair
16	15	200mV	1ns			Input or I/O pin pair
20	19	0V	NA			Output* pin pair, tdelay = 0
22	21	NA	NA			Output*, tdelay = 0
* Could be Input or I/O with vdiff = 0						

Keyword: [Series Pin Mapping]

Required: No

Description: Used to associate two pins joined by a series model.

Sub-Params: pin_2, model_name, function_table_group

Usage Rules: Enter only series pin pairs. The first column, [Series Pin Mapping], contains the series pin for which input impedances are measured. The second column, pin_2, contains the other connection of the series model. Each pin must match the pin names declared previously in the [Pin] section of the IBIS file. The third column, model_name, associates the Series or Series_switch model for the pair of pins in the first two columns. The fourth column, function_table_group, contains an alphanumeric designator string to associate those sets of Series_switch pins that are switched together.

Each line must contain either three or four columns. When using four columns, the header function_table_group must be listed.

One possible application is to model crossbar switches where the straight through On paths are indicated by one designator and the cross over On paths are indicated by another designator. If the model referenced is a Series model, then the function_table_group entry is omitted.

Column length limits are:

[Series Pin Mapping]	5 characters max
pin_2	5 characters max
model_name	20 characters max
function_table_group	20 characters max

Other Notes: If the model_name is for a non-symmetrical series model, then the order of the pins is important. The [Series Pin Mapping] and pin_2 entries must be in the columns that correspond with Pin 1 and Pin 2 of the referenced model.

This mapping covers only the series paths between pins. The package parasitics and any other elements such as additional capacitance or clamping circuitry are defined by the model_name that is referenced in the [Pin] keyword. The

model_names under the [Pin] keyword that are also referenced by the [Series Pin Mapping] keyword may include any legal model or reserved model except for Series and Series_switch models. Normally the pins will reference a [Model] whose Model_type is 'Terminator'. For example, a Series_switch model may contain Terminator models on EACH of the pins to describe both the capacitance on each pin and some clamping circuitry that may exist on each pin. In a similar manner, Input, I/O or Output models may exist on each pin of a Series model that is serving as a differential termination.

[Series Pin Mapping]	pin_2	model_name	function_table_group
2	3	CBTSeries	1 Four independent groups
5	6	CBTSeries	2
9	8	CBTSeries	3
12	11	CBTSeries	4
22	23	CBTSeries	5 Straight through path
25	26	CBTSeries	5
22	26	CBTSeries	6 Cross over path
25	23	CBTSeries	6
32	33	Fixed_series	No group needed

Keyword: [Series Switch Groups]

Required: No

Description: Used to define allowable switching combinations of series switches described using the names of the groups in the [Series Pin Mapping] keyword function_table_group column

Sub-Params: On, Off

Usage Rules: Each state line contains an allowable configuration. A typical state line will start with 'On' followed by all of the on-state group names or an 'Off' followed by all of the off-state group names. Only one of 'On' or 'Off' is required since the undefined states are presumed to be opposite of the explicitly defined states. The state line is terminated with the slash '/', even if it extends over several lines to fit within the 80 character column width restriction.

The group names in the function_table_group are used to associate switches whose switching action is synchronized by a common control function. The first line defines the assumed (default) state of the set of series switches. Other sets of states are listed and can be selected through a user interface or through automatic control.

[Series Switch Groups]

Function Group States

On 1 2 3 4 / | Default setting is all switched On.

Off 1 2 3 4 / | All Off setting.

On 1 /

| Other possible combinations below.

On 2 /

On 3 /

```

On 4 /
On 1 2 /
On 1 3 /
On 1 4 /
On 2 3 /
On 2 4 /
On 3 4 /
On 1 2 3 /
On 1 2 4 /
On 1 3 4 /
On 2 3 4 /
| Off 4 /           | The last four lines above could have been replaced
| Off 3 /           | with these four lines with the same meaning.
| Off 2 /
| Off 1 /

On 5 /           | Crossbar switch straight through connection
On 6 /           | Crossbar cross over connection
Off 5 6 /        | Crossbar open switches

```

```

=====
| Keyword: [Model Selector]
| Required: No.
| Description: Used to pick a [Model] from a list of [Model]s for a pin which
|                 uses a programmable buffer.
| Usage Rules: A programmable buffer must have an individual [Model] section
|                 for each one of its modes used in the .ibs file. The names of
|                 these [Model]s must be unique and can be listed under the
|                 [Model Selector] keyword and/or pin list. The name of the
|                 [Model Selector] keyword must match the corresponding model
|                 name listed under the [Pin] or [Series Pin Mapping] keyword
|                 and must not contain more than 20 characters. A .ibs file
|                 must contain enough [Model Selector] keywords to cover all of
|                 the model selector names specified under the [Pin] and [Series
|                 Pin Mapping] keywords.
|
|                 The section under the [Model Selector] keyword must have two
|                 fields. The two fields must be separated by at least one
|                 white space. The first field lists the [Model] name (up to 20
|                 characters long). The second field contains a short
|                 description of the [Model] shown in the first field. The
|                 contents and format of this description is not standardized,
|                 however it shall be limited in length so that none of the
|                 descriptions exceed the 80-character length of the line that
|                 it started on. The purpose of the descriptions is to aid the
|                 user of the simulator tool in making intelligent buffer mode
|                 selections and it can be used by the simulator tool in a user
|                 interface dialog box as the basis of an interactive buffer
|                 selection mechanism.
|
|                 The first entry under the [Model Selector] keyword shall be
|                 considered the default by the simulator tool for all those
|                 pins which call this [Model Selector].
|
|                 The operation of this selection mechanism implies that a group
|                 of pins which use the same programmable buffer (i.e. model
|                 selector name) will be switched together from one [Model] to

```

another. Therefore, if two groups of pins, for example an address bus and a data bus, use the same programmable buffer, and the user must have the capability to configure them independently, one can use two [Model Selector] keywords with unique names and the same list of [Model] keywords; however, the usage of the [Model Selector] is not limited to these examples. Many other combinations are possible.

[Pin]	signal_name	model_name	R_pin	L_pin	C_pin
1	RAS0#	Progbuffer1	200.0m	5.0nH	2.0pF
2	EN1#	Input1	NA	6.3nH	NA
3	A0	3-state			
4	D0	Progbuffer2			
5	D1	Progbuffer2	320.0m	3.1nH	2.2pF
6	D2	Progbuffer2			
7	RD#	Input2	310.0m	3.0nH	2.0pF
.					
.					
.					
18	Vcc3	POWER			

[Model Selector] Progbuffer1

OUT_2 2 mA buffer without slew rate control
 OUT_4 4 mA buffer without slew rate control
 OUT_6 6 mA buffer without slew rate control
 OUT_4S 4 mA buffer with slew rate control
 OUT_6S 6 mA buffer with slew rate control

[Model Selector] Progbuffer2

OUT_2 2 mA buffer without slew rate control
 OUT_6 6 mA buffer without slew rate control
 OUT_6S 6 mA buffer with slew rate control
 OUT_8S 8 mA buffer with slew rate control
 OUT_10S 10 mA buffer with slew rate control

Section 6

M O D E L S T A T E M E N T

Keyword: [Model]

Required: Yes

Description: Used to define a model, and its attributes.

Sub-Params: Model_type, Polarity, Enable, Vinl, Vinh, C_comp, Vmeas, Cref, Rref, Vref

Usage Rules: Each model type must begin with the keyword [Model]. The model name must match the one that is listed under a [Pin], [Model Selector] or [Series Pin Mapping] keyword and must not contain more than 20 characters. A .ibs file must contain enough [Model] keywords to cover all of the model names specified under the [Pin], [Model Selector] and [Series Pin Mapping] keywords, except for those model names that use reserved words (POWER, GND and NC).

Model_type must be one of the following:

Input, Output, I/O, 3-state, Open_drain, I/O_open_drain, Open_sink, I/O_open_sink, Open_source, I/O_open_source, Input_ECL, Output_ECL, I/O_ECL, 3-state_ECL, Terminator, Series, and Series_switch.

Special usage rules apply to the following. Some definitions are included for clarification:

Input	These model types must have Vinl and Vinh defined. If they are not defined, the
I/O	parser issues a warning and the default
I/O_open_drain	values of Vinl = 0.8 V and Vinh = 2.0 V are
I/O_open_sink	assumed.
I/O_open_source	

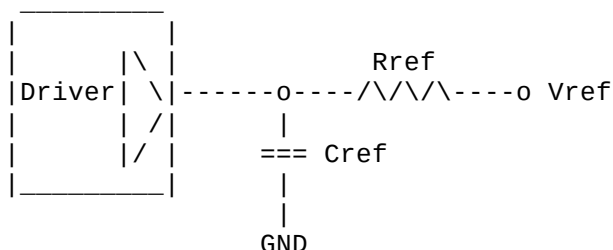
Input_ECL	These model types must have Vinl and Vinh
I/O_ECL	defined. If they are not defined, the
	parser issues a warning and the default
	values of Vinl = -1.475 V and Vinh =
	-1.165 V are assumed.

Terminator	This model type is an input-only model that can have analog loading effects on the circuit being simulated but has no digital logic thresholds. Examples of Terminators are: capacitors, termination diodes, and pullup resistors.
------------	--

Output	This model type indicates that an output always sources and/or sinks current and cannot be disabled.
--------	--

3-state	This model type indicates that an output
---------	--

	can be disabled, i.e. put into a high impedance state.
Open_sink Open_drain	These model types indicate that the output has an OPEN side (do not use the [Pullup] keyword, or if it must be used, set I = 0 mA for all voltages specified) and the output SINKS current. Open_drain model type is retained for backward compatibility.
Open_source	This model type indicates that the output has an OPEN side (do not use the [Pulldown] keyword, or if it must be used, set I = 0 mA for all voltages specified) and the output SOURCES current.
Input_ECL Output_ECL I/O_ECL 3-state_ECL	These model types specify that the model represents an ECL type logic that follows different conventions for the [Pulldown] keyword.
Series	This model type is for series models that can be described by [R Series], [L Series], [RL Series], [C Series], [Lc Series], [Rc Series], [Series Current] and [Series MOSFET] keywords
Series_switch	This model type is for series switch models that can be described by [On], [Off], [R Series], [L Series], [RL Series], [C Series], [Lc Series], [Rc Series], [Series Current] and [Series MOSFET] keywords
The Model_type and C_comp subparameters are required. The Polarity, Enable, Vinl, Vinh, Vmeas, Cref, Rref, and Vref subparameters are optional. C_comp defines the silicon die capacitance. This value should not include the capacitance of the package. C_comp is allowed to use "NA" for the min and max values only. The Polarity subparameter can be defined as either Non-Inverting or Inverting, and the Enable subparameter can be defined as either Active-High or Active-Low. The Cref and Rref subparameters correspond to the test load that the semiconductor vendor uses when specifying the propagation delay and/or output switching time of the model. The Vmeas subparameter is the reference voltage level that the semiconductor vendor uses for the model. Include Cref, Rref, Vref, and Vmeas information to facilitate board-level timing simulation. The assumed connections for Cref, Rref, and Vref are shown in the following diagram:	



Other Notes: A complete [Model] description normally contains the following keywords: [Voltage Range], [Pullup], [Pulldown], [GND Clamp], [POWER Clamp], and [Ramp]. A Terminator model uses one or more of the [Rgnd], [Rpower], [Rac], and [Cac]. However, some models may have only a subset of these keywords. For example, an input structure normally only needs the [Voltage Range], [GND Clamp], and possibly the [POWER Clamp] keywords. If one or more of [Rgnd], [Rpower], [Rac], and [Cac] keywords are used, then the Model_type must be Terminator.

Signals	CLK1, CLK2, ...	Optional signal list, if desired	
[Model]	Clockbuffer		
Model_type	I/O		
Polarity	Non-Inverting		
Enable	Active-High		
Vinl = 0.8V		input logic "low" DC voltage, if any	
Vinh = 2.0V		input logic "high" DC voltage, if any	
Vmeas = 1.5V		Reference voltage for timing measurements	
Cref = 50pF		Timing specification test load capacitance value	
Rref = 500		Timing specification test load resistance value	
Vref = 0		Timing specification test load voltage	
variable	typ	min	max
C_comp	12.0pF	10.0pF	15.0pF

Keyword: [Model Spec]

Required: No

Sub-Params: Vinh, Vinl, Vinh+, Vinh-, Vinl+, Vinl-, S_overshoot_high, S_overshoot_low, D_overshoot_high, D_overshoot_low, D_overshoot_time, Pulse_high, Pulse_low, Pulse_time, Vmeas

Description: The [Model Spec] keyword defines four columns under which specification subparameters are defined.

The following subparameters are defined:

Vinh	Input voltage threshold high
Vinl	Input voltage threshold low
Vinh+	Hysteresis threshold high max Vt+
Vinh-	Hysteresis threshold high min Vt+
Vinl+	Hysteresis threshold low max Vt-
Vinl-	Hysteresis threshold low min Vt-
S_overshoot_high	Static overshoot high voltage
S_overshoot_low	Static overshoot low voltage
D_overshoot_high	Dynamic overshoot high voltage
D_overshoot_low	Dynamic overshoot low voltage
D_overshoot_time	Dynamic overshoot time
Pulse_high	Pulse immunity high voltage
Pulse_low	Pulse immunity low voltage

Pulse_time	Pulse immunity time
Vmeas	Measurement voltage for timing measurements

Usage Rules: [Model Spec] must follow all other subparameters under the [Model] keyword.

For each subparameter contained in the first column, the remaining three hold its typical, minimum and maximum values. The entries of typical, minimum and maximum must be placed on a single line and must be separated by at least one white space. All four columns are required under the [Model Spec] keyword. However, data is required only in the typical column. If minimum and/or maximum values are not available, the reserved word "NA" must be used indicating the typical value by default.

The minimum and maximum values are used for specifications subparameter values that may track the min and max operation conditions of the [Model]. Usually it is related to the Voltage Range settings.

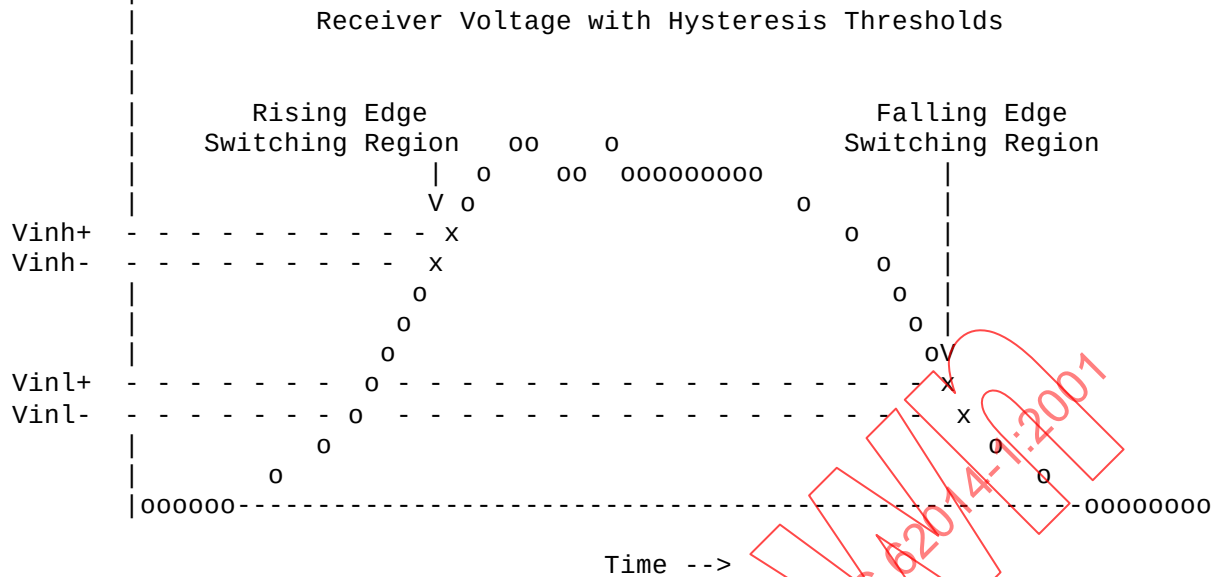
Unless noted below, no subparameter requires having present any other subparameter.

Vinh, Vinl rules:

The threshold subparameter lines provide additional min and max column values, if needed. The typ column values are still required and would be expected to override the Vinh and Vinl subparameter values specified elsewhere. Note: the syntax rule that require inserting Vinh and Vinl under models remains unchanged even if the values are defined under the [Model Spec] keyword.

Vinh+, Vinh-, Vinl+, Vinl- rules:

The four hysteresis subparameters (used for Schmitt trigger inputs for defining two thresholds for the rising edges and two thresholds for falling edges) must all be defined before independent input thresholds for rising and falling edges of the hysteresis threshold rules become effective. Otherwise the standard threshold subparameters remain in effect. The hysteresis thresholds shall be at the Vinh+ and Vinh- values for a low-to-high transition, and at the Vinl+ and Vinl- values for a high-to-low transition.

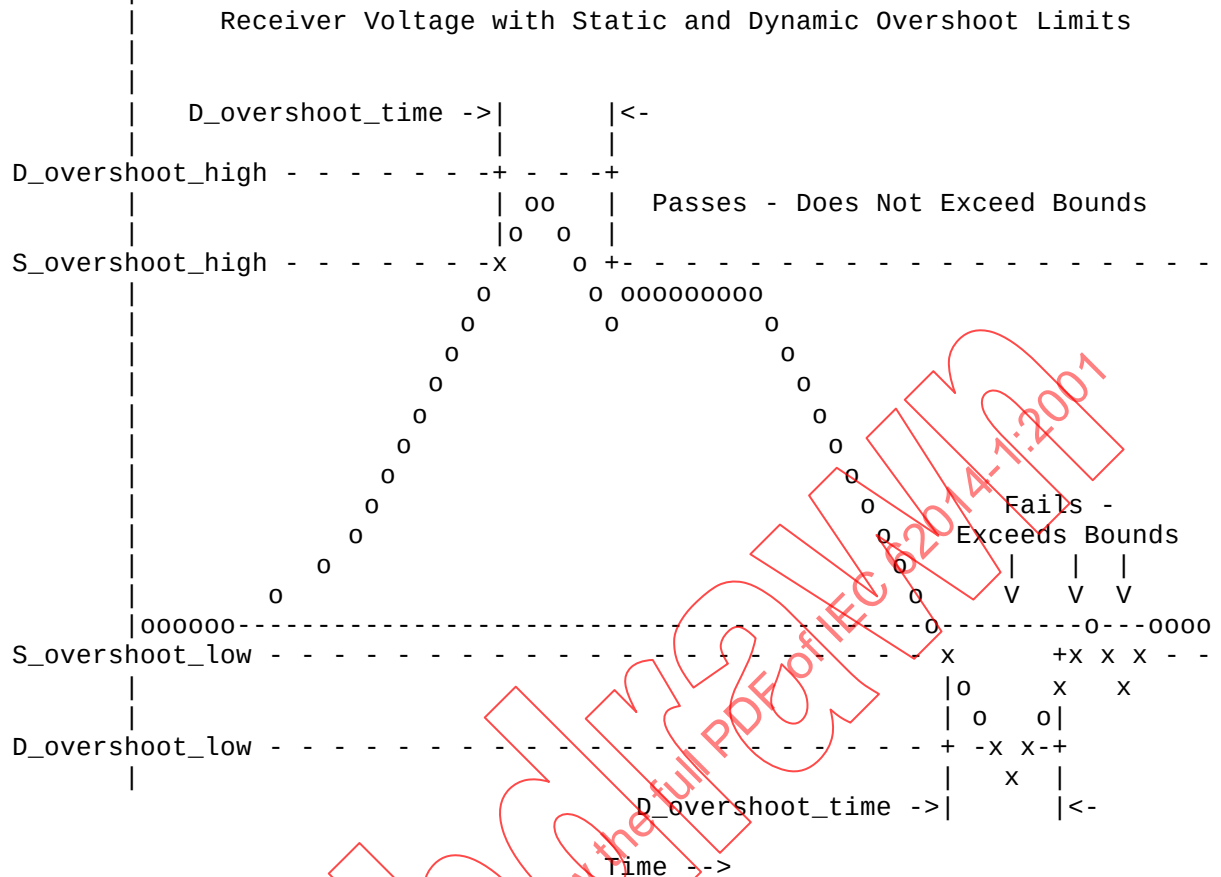


$S_{overshoot_high}$, $S_{overshoot_low}$ rules:

The static overshoot subparameters provide the DC voltage values for which the model is no longer guaranteed to function correctly. Typically these are voltages that would cause the physical component to be destroyed.

$D_{overshoot_high}$, $D_{overshoot_low}$, $D_{overshoot_time}$ rules:

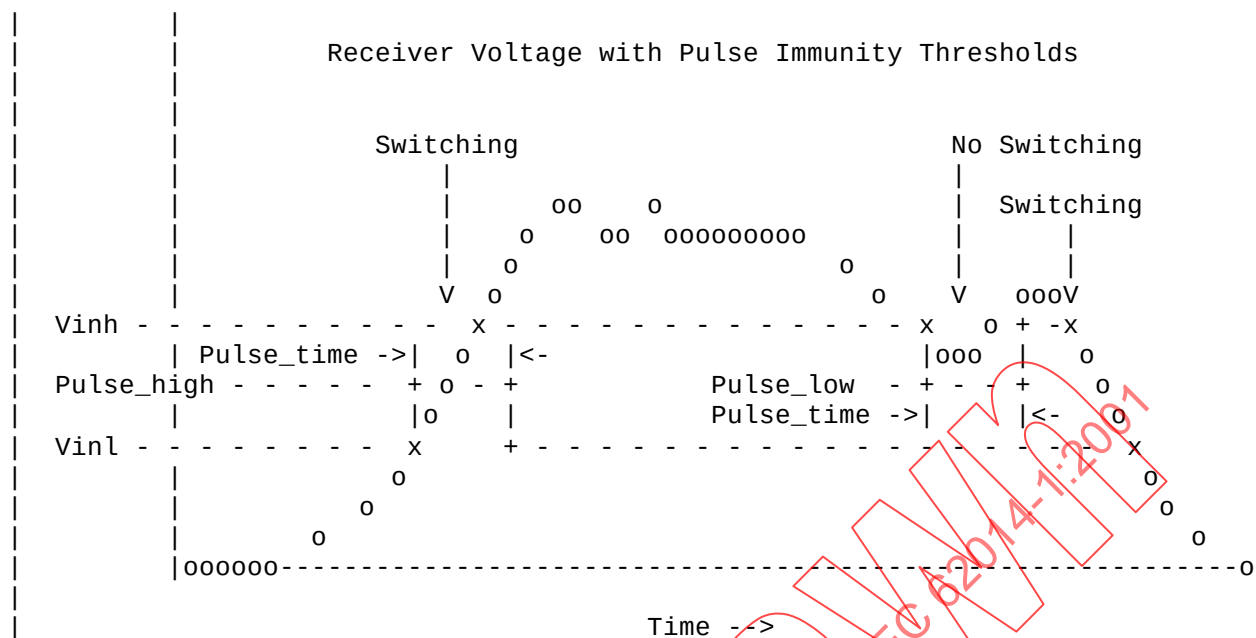
The dynamic overshoot values provide a time window during which the overshoot may exceed the static overshoot limits but be below the dynamic overshoot limits. $D_{overshoot_time}$ is required for dynamic overshoot testing. In addition, if $D_{overshoot_high}$ is specified, then $S_{overshoot_high}$ is necessary for testing beyond the static limit. Similarly, if $D_{overshoot_low}$ is specified, then $S_{overshoot_low}$ is necessary for testing beyond the static limit.



Pulse_high, Pulse_low, Pulse_time rules:

The pulse immunity values provide a time window during which a rising pulse may exceed the nearest threshold value but be below the pulse voltage value and still not cause the input to switch. Pulse_time is required for pulse immunity testing. A rising response is tested only if Pulse_high is specified. Similarly, a falling response is tested only if Pulse_low is specified. The rising response may exceed the V_{inl} value, but remain below the Pulse_high value.

Similarly, the falling response may drop below the V_{inh} value, but remain above the Pulse_low value. In either case the input is regarded as immune to switching if the responses are within these extended windows. If the hysteresis thresholds are defined, then the rising response shall use V_{inh-} as the reference voltage, and the falling response shall use V_{inl+} as the reference voltage.



Vmeas rules:

The Vmeas values under the [Model Spec] keyword override the Vmeas entry elsewhere.

[Model Spec]				
Subparameter	typ	min	max	
Thresholds				
Vinh	3.5	3.15	3.85	70% of Vcc
Vinl	1.5	1.35	1.65	30% of Vcc
Vinh	3.835	3.335	4.335	Offset from Vcc
Vinl	3.525	3.025	4.025	for PECL
Hysteresis				
Vinh+	2.0	NA	NA	Overrides the
Vinh-	1.6	NA	NA	thresholds
Vinl+	1.1	NA	NA	
Vinl-	0.6	NA	NA	All 4 are required
Overshoot				
S_overshoot_high	5.5	5.0	6.0	Static overshoot
S_overshoot_low	-0.5	NA	NA	
D_overshoot_high	6.0	5.5	6.5	Dynamic overshoot
D_overshoot_low	-1.0	-1.0	-1.0	requires
D_overshoot_time	20n	20n	20n	D_overshoot_time & static overshoot
Pulse Immunity				
Pulse_high	3V	NA	NA	Pulse immunity

Pulse_low	0	NA	NA	requires
Pulse_time	3n	NA	NA	Pulse_time

Timing Thresholds

Vmeas	3.68	3.18	4.68	A 5 volt PECL example
-------	------	------	------	----------------------------

Keyword: [Add Submodel]

Required: No

Description: References a submodel to be added to an existing model.

Usage Rules: The [Add Submodel] keyword is invoked within a model to add the functionality that is contained in the submodel or list of submodels in each line that follows. The first column contains the submodel name. The second column contains a submodel mode under which the submodel is used.

If the top-level model type is one of the I/O or 3-state models, the submodel mode may be Driving, Non-Driving, or All. For example, if the submodel mode is Non-Driving, then the submodel is used only in the high-Z state of a 3-state model. Set the submodel mode to All if the submodel is to be used for all modes of operation.

The submodel mode cannot conflict with the top-level model type. For example, if the top-level model type is an Open or Output type, the submodel mode cannot be set to Non-Driving. Similarly, if the top-level model type is Input, the submodel mode cannot be set to Driving.

The [Add Submodel] keyword is not defined for Series or Series_switch model types.

Refer to the Add Submodel Description section in this document for the descriptions of available submodels.

[Add Submodel]

Submodel_name	Mode	
Bus_Hold_1	Non-Driving	Adds the electrical characteristics of [Submodel] Bus_Hold_1 for receiver or high-Z mode only
Dynamic_clamp_1	All	Adds the Dynmanic_clamp_1 model for all modes of operation

Keyword: [Driver Schedule]

Required: No

Description: Describes the relative model switching sequence for referenced models to produce a multi-staged driver.

Usage Rules: The [Driver schedule] keyword establishes a hierarchical order between models and should be placed under the [Model] which acts as the top-level model. The scheduled models are then referenced from the top-level model by the [Driver Schedule] keyword.

When a multi-staged buffer is modeled using the [Driver Schedule] keyword, all of its stages (including the first stage, or normal driver) have to be modeled as scheduled models.

If there is support for this feature in a simulator, the [Driver Schedule] keyword will cause it to use the [Pulldown], [Pulldown Reference], [Pullup], [Pullup Reference], [Voltage Range], [Ramp], [Rising Waveform] and [Falling Waveform] keywords from the scheduled models instead of the top-level model, according to the timing relationships described in the [Driver Schedule] keyword. Consequently, the keywords in the above list will be ignored in the top-level model. Also, all other keywords not shown in the above list will be ignored in the scheduled model(s).

However, both the top-level and the scheduled model(s) have to be complete models, i.e. all of the required keywords must be present and follow the syntactical rules.

For backwards compatibility reasons and for simulators which do not support multi-staged switching, the keywords in the above list can be used in the top-level [Model] to describe the overall characteristics of the buffer as if it was a composite model. It is not guaranteed, however, that such a top-level model will yield the same simulation results as a full multi-stage model. It is recommended that a "golden waveform" for the device consisting of a [Rising Waveform] table and a [Falling Waveform] table be supplied in the top-level model to serve as a reference for validation.

Even though some of the keywords are ignored in the scheduled model, it may still make sense in some cases to supply correct data with them. One such situation would arise when a [Model] is used both as a regular top-level model as well as a scheduled model.

The [Driver Schedule] table consists of five columns. The first column contains the model names of other models that exists in the .ibs file. The remaining four columns describe delays: Rise_on_dly, Rise_off_dly, Fall_on_dly, and Fall_off_dly. The t=0 time of each delay is the event when the simulator's internal pulse initiates a rising or falling transition. All specified delay values must be equal to or greater than 0. There are only five valid combinations in which these delay values can be defined:

- 1) Rise_on_dly with Fall_on_dly
- 2) Rise_off_dly with Fall_off_dly
- 3) Rise_on_dly with Rise_off_dly
- 4) Fall_on_dly with Fall_off_dly
- 5) All four delays defined
(be careful about correct sequencing)

The four delay parameters have the meaning as described below. (Note that this description applies to buffer types which have both pullup and pulldown structures. For those

buffer types which have only a pullup or pulldown structure, the description for the missing structure can be omitted.)

Rise_on_dly is the amount of time that elapses from the internal simulator pulse initiating a RISING edge to the t=0 time of the waveform or ramp that turns the I-V table of the PULLUP device ON, and the t=0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device OFF (if they were not already turned ON and OFF, respectively, by another event).

Rise_off_dly is the amount of time that elapses from the internal simulator pulse initiating a RISING edge to the t=0 time of the waveform or ramp that turns the I-V table of the PULLUP device OFF, and the t=0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device ON (if they were not already turned ON and OFF, respectively, by another event).

Fall_on_dly is the amount of time that elapses from the internal simulator pulse initiating a FALLING edge to the t=0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device ON, and the t=0 time of the waveform or ramp that turns the I-V table of the PULLUP device OFF (if they were not already turned ON and OFF, respectively, by another event).

Fall_off_dly is the amount of time that elapses from the internal simulator pulse initiating a FALLING edge to the t=0 time of the waveform or ramp that turns the I-V table of the PULLDOWN device OFF, and the t=0 time of the waveform or ramp that turns the I-V table of the PULLUP device ON (if they were not already turned ON and OFF, respectively, by another event).

Note that some timing combinations may only be possible if the two halves of a complementary buffer are modeled separately as two open_* models.

Use 'NA' when no delay value is applicable. For each scheduled model the transition sequence must be complete, i.e., the scheduled model must return to its initial state.

No [Driver Schedule] table may reference a model which itself has within it a [Driver Schedule] keyword.

Other Notes: The added models typically consist of Open_sink (Open_drain) or Open_source models to provide sequentially increased drive strengths. The added drive may be removed within the same transition for a momentary boost or during the opposite transition.

The syntax also allows for reducing the drive strength.

Note that the Rise_on_dly, Rise_off_dly, Fall_on_dly, Fall_off_dly parameters are single value parameters, so typical, minimum and maximum conditions cannot be described

with them directly. In order to account for those effects, one can refer to the fastest waveform table with the delay number and then insert an appropriate amount of horizontal lead in section in those waveforms which need more delay.

Notice that the C_comp parameter of a multi-stage buffer is defined in the top-level model. The value of C_comp therefore includes the total capacitance of the entire buffer, including all of its stages. Since the rising and falling waveform measurements include the effects of C_comp, each of these waveforms must be generated with the total C_comp present, even if the various stages of the buffer are characterized individually.

Note: In a future release, the [Driver Schedule] keyword may be replaced by a newer method of specification that is consistent with some other planned extensions. However, the [Driver Schedule] syntax will continue to be supported.

[Driver Schedule]

Model_name	Rise_on_dly	Rise_off_dly	Fall_on_dly	Fall_off_dly
MODEL_OUT	0.0ns	NA	0.0ns	NA
Examples of added multi-staged transitions				
M_O_SOURCE1	0.5ns	NA	0.5ns	NA
	low (high-Z) to high		high to low (high-Z)	
M_O_SOURCE2	0.5n	1.5n	NA	NA
	low to high to low		low (high-Z)	
M_O_DRAIN1	1.0n	NA	1.5n	NA
	low to high (high-Z)		high (high-Z) to low	
M_O_DRAIN2	NA	NA	1.5n	2.0n
	high (high-Z)		high to low to high	

Keyword: [Temperature Range]

Required: Yes, if other than the preferred 0, 50, 100 degree Celsius range

Description: Defines the temperature range over which the model is to operate.

Usage Rules: List the actual die temperatures (not percentages) in the typ, min, max format. "NA" is allowed for min and max only.

Other Notes: The [Temperature Range] keyword also describes the temperature range over which the various I-V tables and ramp rates were derived.

variable	typ	min	max
[Temperature Range]	27.0	-50	130.0

Keyword: [Voltage Range]

Required: Yes, if [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference], and [GND Clamp Reference] are not present

Description: Defines the power supply voltage tolerance over which the model is intended to operate. It also specifies the default voltage rail to which the [Pullup] and [POWER Clamp] I-V data is referenced.

Usage Rules: Provide actual voltages (not percentages) in the typ, min, max

format. "NA" is allowed for the min and max values only.

Other Notes: If the [Voltage Range] keyword is not present, then all four of the keywords described below must be present: [Pullup Reference], [Pulldown Reference], [POWER Clamp Reference], and [GND Clamp Reference]. If the [Voltage Range] is present, the other keywords are optional and may or may not be used as required. It is legal (although redundant) for an optional keyword to specify the same voltage as specified by the [Voltage Range] keyword.

variable	typ	min	max
[Voltage Range]	5.0V	4.5V	5.5V

Keyword: [Pullup Reference]

Required: Yes, if the [Voltage Range] keyword is not present.

Description: Defines a voltage rail other than that defined by the [Voltage Range] keyword as the reference voltage for the [Pullup] I-V data.

Usage Rules: Provide actual voltages (not percentages) in the typ, min, max format. "NA" is allowed for the min and max values only.

Other Notes: This keyword, if present, also defines the voltage range over which the typ, min, and max dV/dt_r values are derived.

variable	typ	min	max
[Pullup Reference]	5.0V	4.5V	5.5V

Keyword: [Pulldown Reference]

Required: Yes, if the [Voltage Range] keyword is not present.

Description: Defines a power supply rail other than 0 V as the reference voltage for the [Pulldown] I-V data. If this keyword is not present, the voltage data points in the [Pulldown] I-V table are referenced to 0 V.

Usage Rules: Provide actual voltages (not percentages) in the typ, min, max format. "NA" is allowed for the min and max values only.

Other Notes: This keyword, if present, also defines the voltage range over which the typ, min, and max dV/dt_f values are derived.

variable	typ	min	max
[Pulldown Reference]	0V	0V	0V

Keyword: [POWER Clamp Reference]

Required: Yes, if the [Voltage Range] keyword is not present.

Description: Defines a voltage rail other than that defined by the [Voltage Range] keyword as the reference voltage for the [POWER Clamp] I-V data.

Usage Rules: Provide actual voltages (not percentages) in the typ, min, max format. "NA" is allowed for the min and max values only.

Other Notes: Refer to the "Other Notes" section of the [GND Clamp Reference] keyword.

variable	typ	min	max
[POWER Clamp Reference]	5.0V	4.5V	5.5V

Keyword: [GND Clamp Reference]				
Required:	Yes, if the [Voltage Range] keyword is not present.			
Description:	Defines a power supply rail other than 0 V as the reference voltage for the [GND Clamp] I-V data. If this keyword is not present, the voltage data points in the [GND Clamp] I-V table are referenced to 0 V.			
Usage Rules:	Provide actual voltages (not percentages) in the typ, min, max format. "NA" is allowed for the min and max values only.			
Other Notes:	Power Supplies: It is intended that standard TTL and CMOS models be specified using only the [Voltage Range] keyword. However, in cases where the output characteristics of a model depend on more than a single supply and ground, or a [Pullup], [Pulldown], [POWER Clamp], or [GND Clamp] table is referenced to something other than the default supplies, use the additional 'reference' keywords.			

variable	typ	min	max	
[GND Clamp Reference]	0V	0V	0V	
=====				
Keywords: [TTgnd], [TTpower]				
Required:	No			
Description:	These keywords specify the transit time parameters used to estimate the transit time capacitances or develop transit time capacitance tables for the [GND Clamp] and [POWER Clamp] tables.			
Usage Rules:	For each of these keywords, the three columns hold the transit values corresponding to the typical, minimum and maximum [GND Clamp] or [POWER Clamp] tables, respectively. The entries for TT(typ), TT(min), and TT(max) must be placed on a single line and must be separated by at least one white space. All three columns are required under these keywords. However, data is required only in the typical column. If minimum and/or maximum values are not available, the reserved word "NA" must be used indicating the TT(typ) value by default.			
Other Notes:	The transit time capacitance is added to C_comp. It is in a Spice reference model as $C_t = TT * d(I_d)/d(V_d)$ where $d(I_d)/d(V_d)$ defines the DC conductance at the incremental DC operating point of the diode, and TT is the transit time. This expression does not include any internal series resistance. Such a resistance is assumed to be negligible in practice. Assume that the internal diode current (I_d) - voltage (V_d) relationship is $I_d = I_s * (\exp(q(V_d)/kT) - 1)$ where I_s is the saturation current, q is electron charge, k is Boltzmann's constant, and T is temperature in degrees Kelvin. Then $d(I_d)/d(V_d)$ is approximately $(q/kT) * I_d$ when the diode is conducting, and zero otherwise. This yields the simplification $C_t = TT * (q/kT) * I_d$. The I_d is found from the [GND Clamp] and [POWER Clamp] operating points, and the corresponding TTgnd or TTpower is used to calculate the C_t value. If the [Temperature Range] keyword is not defined, then use the default "typ" temperature for all C_t calculations.			
The effective TT parameter values are intended to APPROXIMATE the effects. They may be different from the values found in				

the Spice diode equations. Refer to the NOTES ON DATA DERIVATION METHOD for extracting the effective values.

variable	TT(typ)	TT(min)	TT(max)
[TTgnd]	10n	12n	9n
[TTpower]	12n	NA	NA

Keywords: [Pulldown], [Pullup], [GND Clamp], [POWER Clamp]

Required: Yes, if they exist in the model

Description: The data points under these keywords define the I-V tables of the pulldown and pullup structures of an output buffer and the I-V tables of the clamping diodes connected to the GND and the POWER pins, respectively. Currents are considered positive when their direction is into the component.

Usage Rules: In each of these sections, the first column contains the voltage value, and the three remaining columns hold the typical, minimum, and maximum current values. The four entries, Voltage, I(typ), I(min), and I(max) must be placed on a single line and must be separated by at least one white space.

All four columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum current values are not available, the reserved word "NA" must be used. "NA" can be used for currents in the typical column, but numeric values MUST be specified for the first and last voltage points on any I-V table. Each I-V table must have at least 2, but not more than 100, voltage points.

Other Notes: The I-V table of the [Pullup] and the [POWER Clamp] structures are 'Vcc relative', meaning that the voltage values are referenced to the Vcc pin. (Note: Under these keywords, all references to 'Vcc' refer to the voltage rail defined by the [Voltage Range], [Pullup Reference], or [POWER Clamp Reference] keywords, as appropriate.) The voltages in the data tables are derived from the equation: $V_{table} = V_{cc} - V_{output}$.

Therefore, for a 5 V model, -5 V in the table actually means 5 V above Vcc, which is +10 V with respect to ground; and 10 V means 10 V below Vcc, which is -5 V with respect to ground. Vcc-relative data is necessary to model a pullup structure properly, since the output current of a pullup structure depends on the voltage between the output and Vcc pins and not the voltage between the output and ground pins. Note that the [GND Clamp] I-V table can include quiescent input currents, or the currents of a 3-stated output, if so desired.

When tabulating data for ECL models, the data in the [Pulldown] table is measured with the output in the 'logic low' state. In other words, the data in the table represents the I-V characteristics of the output when the output is at the most negative of its two logic levels. Likewise, the data in the [Pullup] table is measured with the output in the

'logic one' state and represents the I-V characteristics when the output is at the most positive logic level. Note that in BOTH of these cases, the data is referenced to the Vcc supply voltage, using the equation: $V_{table} = V_{cc} - V_{output}$.

Monotonicity Requirements:

To be monotonic, the I-V table data must meet any one of the following 8 criteria:

- 1- The CURRENT axis either increases or remains constant as the voltage axis is increased.
- 2- The CURRENT axis either increases or remains constant as the voltage axis is decreased.
- 3- The CURRENT axis either decreases or remains constant as the voltage axis is increased.
- 4- The CURRENT axis either decreases or remains constant as the voltage axis is decreased.
- 5- The VOLTAGE axis either increases or remains constant as the current axis is increased.
- 6- The VOLTAGE axis either increases or remains constant as the current axis is decreased.
- 7- The VOLTAGE axis either decreases or remains constant as the current axis is increased.
- 8- The VOLTAGE axis either decreases or remains constant as the current axis is decreased.

An IBIS syntax checking program shall test for non-monotonic data and provide a maximum of one warning per I-V table if non-monotonic data is found. For example:

"Warning: Line 300, Pulldown I-V table for model DC040403 is non-monotonic! Most simulators will filter this data to remove the non-monotonic data."

It is also recognized that the data may be monotonic if currents from both the output stage and the clamp diode are added together as most simulators do. To limit the complexity of the IBIS Version 2.x and Version 3.x syntax checking programs, such programs will conduct monotonicity testing only on one I-V table at a time.

It is assumed that the simulator sums the clamp tables together with the appropriate [Pullup] or [Pulldown] table when a buffer is driving high or low, respectively. From this assumption and the nature of 3-statable buffers, it follows that the data in the clamping table sections are handled as constantly present tables and the [Pullup] and [Pulldown] tables are used only when needed in the simulation.

The clamp tables of an Input or I/O buffer can be measured directly with a curve tracer, with the I/O buffer 3-stated. However, sweeping enabled buffers results in tables that are the sum of the clamping tables and the output structures. Based on the assumption outlined above, the [Pullup] and [Pulldown] tables of an IBIS model must represent the difference of the 3-stated and the enabled buffer's tables.

(Note that the resulting difference table can demonstrate a non-monotonic shape.) This requirement enables the simulator to sum the tables, without the danger of double counting, and arrive at an accurate model in both the 3-stated and enabled conditions.

Since in the case of a non 3-statable buffer, this difference table cannot be generated through lab measurements (because the clamping tables cannot be measured alone), the [Pullup] and [Pulldown] tables of an IBIS model can contain the sum of the clamping characteristics and the output structure. In this case, the clamping tables must contain all zeroes, or the keywords must be omitted.

[Pulldown]

Voltage	I(typ)	I(min)	I(max)
-5.0V	-40.0m	-34.0m	-45.0m
-4.0V	-39.0m	-33.0m	-43.0m
.	.	.	.
0.0V	0.0m	0.0m	0.0m
.	.	.	.
5.0V	40.0m	34.0m	45.0m
10.0V	45.0m	40.0m	49.0m

[Pullup]

| Note: Vtable = Vcc - Voutput

Voltage	I(typ)	I(min)	I(max)
-5.0V	32.0m	30.0m	35.0m
-4.0V	31.0m	29.0m	33.0m
.	.	.	.
0.0V	0.0m	0.0m	0.0m
.	.	.	.
5.0V	-32.0m	-30.0m	-35.0m
10.0V	-38.0m	-35.0m	-40.0m

[GND Clamp]

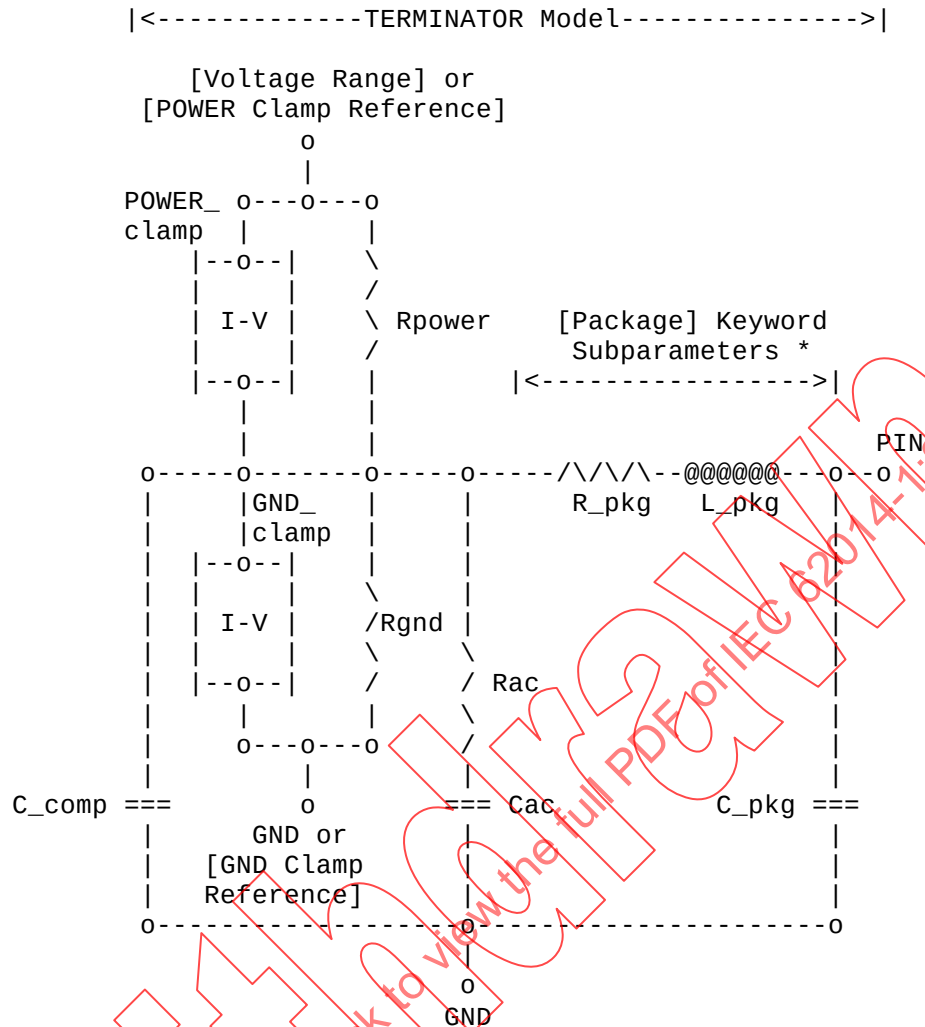
Voltage	I(typ)	I(min)	I(max)
-5.0V	-3900.0m	-3800.0m	-4000.0m
-0.7V	-80.0m	-75.0m	-85.0m
-0.6V	-22.0m	-20.0m	-25.0m
-0.5V	-2.4m	-2.0m	-2.9m
-0.4V	0.0m	0.0m	0.0m
5.0V	0.0m	0.0m	0.0m

[POWER Clamp]

| Note: $V_{table} = V_{cc} - V_{output}$

Voltage	I(typ)	I(min)	I(max)
-5.0V	4450.0m	NA	NA
-0.7V	95.0m	NA	NA
-0.6V	23.0m	NA	NA
-0.5V	2.4m	NA	NA
-0.4V	0.0m	NA	NA
0.0V	0.0m	NA	NA

Keywords:	[Rgnd], [Rpower], [Rac], [Cac]
Required:	Yes, if they exist in the model
Description:	The data for these keywords define the resistance values of Rgnd and Rpower connected to GND and the POWER pins, respectively, and the resistance and capacitance values for an AC terminator.
Usage Rules:	For each of these keywords, the three columns hold the typical, minimum, and maximum resistance values. The three entries for R(typ), R(min), and R(max), or the three entries for C(typ), C(min), and C(max) must be placed on a single line and must be separated by at least one white space. All three columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum values are not available, the reserved word "NA" must be used indicating the R(typ) or C(typ) value by default.
Other Notes:	It should be noted that [Rpower] is connected to 'Vcc' and [Rgnd] is connected to 'GND'. However, [GND Clamp Reference] voltages, if defined, apply to [Rgnd]. [POWER Clamp Reference] voltages, if defined, apply to [Rpower]. Either or both [Rgnd] and [Rpower] may be defined and may coexist with [GND Clamp] and [POWER Clamp] tables. If the terminator consists of a series R and C (often referred to as either an AC or RC terminator), then both [Rac] and [Cac] are required. When [Rgnd], [Rpower], or [Rac] and [Cac] are specified, the Model_type must be Terminator.



* Note: More advanced package parameters are available within this standard, including more detailed power and ground net descriptions.

variable	R(typ)	R(min)	R(max)	
[Rgnd]	330ohm	300ohm	360ohm	Parallel Terminator
[Rpower]	220ohm	200ohm	NA	
[Rac]	30ohm	NA	NA	
variable	C(typ)	C(min)	C(max)	
[Cac]	50pF	NA	NA	AC terminator

Keywords: [On], [Off]

Required:	Yes, both [On] and [Off] for Series_switch Model_types only
Description:	The 'On' state electrical models are positioned under [On]. The 'Off' state electrical models are positioned under [Off].
Usage Rules:	These keywords are only valid for Series_switch Model_types. Only keywords associated with Series_switch electrical models are permitted under [On] or [Off]. The Series electrical models describe the path for one state only and do not use

the [On] and [Off] keywords.

In Series_switch models, [On] or [Off] must be positioned before any of the [R Series], [L Series], [Rl Series], [C Series], [Lc Series], [Rc Series], [Series Current], and [Series MOSFET] keywords. There is no provision for any of these keywords to be defined once, but to apply to both states.

[On]

... On state keywords such as [R Series], [Series Current], [Series MOSFET]

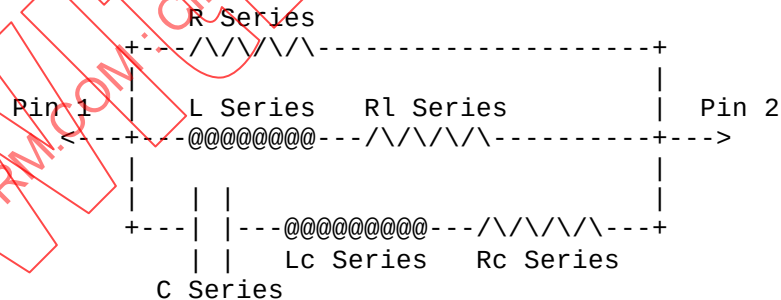
[Off]

... Off state keywords such as [R Series], [Series Current]

Keywords: [R Series], [L Series], [Rl Series], [C Series], [Lc Series], [Rc Series]
Required: Yes, if they exist in the model
Description: The data for these keywords allow the definition of Series or Series_switch R, L or C paths.
Usage Rules: For each of these keywords, the three columns hold the typical, minimum, and maximum resistance values. The three entries must be placed on a single line and must be separated by at least one white space. All three columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum values are not available, the reserved word "NA" must be used.
Other Notes: This series RLC model is defined to allow IBIS to model simple passive models and/or parasitics.

These keywords are valid only for Series or Series_switch Model_types.

The model is:



[Rl Series] shall be defined only if [L Series] exists.
[Rl Series] is 0 ohms if it is not defined in the path.

[Rc Series] and [Lc Series] shall be defined only if [C Series] exists. [Rc Series] is 0 ohms if it is not defined in the path. [Lc Series] is 0 henries if it is not defined in the path.

C_comp values are ignored for these keywords.

variable [R Series]	R(typ) 80hm	R(min) 60hm	R(max) 120hm	
variable [L Series]	L(typ) 5nH	L(min) NA	L(max) NA	
variable [Rl Series]	R(typ) 40hm	R(min) NA	R(max) NA	
variable [C Series]	C(typ) 50pF	C(min) NA	C(max) NA	The other elements are 0 impedance

Keyword: [Series Current]

Required: Yes, if they exist in the model

Description: The data points under this keyword define the I-V tables for voltages measured at Pin 1 with respect to Pin 2. Currents are considered positive if they flow into Pin 1. Pins 1 and 2 are listed under the [Series Pin Mapping] keyword under columns [Series Pin Mapping] and pin 2, respectively.

Usage Rules: The first column contains the voltage value, and the remaining columns hold the typical, minimum, and maximum current values. The four entries, Voltage, I(typ), I(min), and I(max) must be placed on a single line and must be separated by at least one white space.

All four columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum current values are not available, the reserved word "NA" must be used. "NA" can be used for currents in the typical column, but numeric values MUST be specified for the first and last voltage points on any I-V table. Each I-V table must have at least 2, but not more than 100, voltage points.

Other Notes: There is no monotonicity requirement. However the model supplier should realize that it may not be possible to derive a behavioral model from non-monotonic data.

These keywords are valid only for Series or Series_switch Model_types.

The model is:

```

      Table Current
      ----->
      + Table Voltage -
      Pin 1 |-----| Pin 2
      <---+          +--->
           |-----|

```

C_comp values are ignored for [Series Current] models.

[Series Current]

Voltage	I(typ)	I(min)	I(max)
-5.0V	-3900.0m	-3800.0m	-4000.0m
-0.7V	-80.0m	-75.0m	-85.0m
-0.6V	-22.0m	-20.0m	-25.0m
-0.5V	-2.4m	-2.0m	-2.9m
-0.4V	0.0m	0.0m	0.0m
5.0V	0.0m	0.0m	0.0m

Keyword: [Series MOSFET]

Required: Yes, for series MOSFET switches

Description: The data points under this keyword define the I-V tables for voltages measured at Pin 2 for a given Vds setting. Currents are considered positive if they flow into Pin 1. Pins 1 and 2 are listed under the [Series Pin Mapping] keyword under [Series Pin Mapping] and pin_2 columns, respectively.

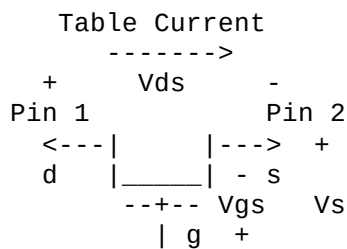
Sub-Params: Vds

Usage Rules: The first column contains the voltage value, and the three remaining columns hold the typical, minimum, and maximum current values. The four entries, Voltage, I(typ), I(min), and I(max) must be placed on a single line and must be separated by at least one white space.

All four columns are required under these keywords. However, data is only required in the typical column. If minimum and/or maximum current values are not available, the reserved word "NA" must be used. "NA" can be used for currents in the typical column, but numeric values MUST be specified for the first and last voltage points on any I-V table. Each I-V table must have at least 2, but not more than 100, voltage points.

Other Notes: There is no monotonicity requirement. However the model supplier should realize that it may not be possible to derive a behavioral model from non-monotonic data.

The model is:



Vg = [Voltage Range] = Vcc

Vgs = Table Voltage = Vtable = Vcc - Vs

Ids = Table Current for a given Vcc and Vds

Internal logic that is generally referenced to the power rail is used to set the MOSFET switch to its 'On' state. Thus the [Voltage Range] settings provide the assumed gate voltages. If the [POWER Clamp Reference] exists, it overrides the [Voltage Range] value. The table entries are actually the Vgs

values referenced to the power rail. The polarity conventions are identical with those used for other tables that are referenced to power rails. Thus the voltage column can be viewed as a table defining the source voltages V_s according to the convention: $V_{table} = V_{cc} - V_s$.

If the switch is used in an application such as interfacing between 3.3 V and 5.0 V logic, the V_{cc} may be biased at a voltage (such as 4.3 V) that is different from a power rail voltage (such as 5.0 V) used to create the model. Just readjust the [Voltage Range] entries (or [POWER Clamp Reference] entries).

One fundamental assumption in the MOSFET switch model is that it operates in a symmetrical manner. The tables and expressions are given assuming that $V_d \geq V_s$. If $V_d < V_s$, then apply the same relationships under the assumption that the source and drain nodes are interchanged. A consequence of this assumption is that the V_{ds} subparameter is constrained to values $V_{ds} > 0$. It is assumed that with $V_{ds} = 0$ the currents will be 0 mA. A further consequence of this assumption that would be embedded in the analysis process is that the voltage table is based on the side of the model with the lowest voltage (and that side is defined as the source). Thus the analysis must allow current to flow in both directions, as would occur due to reflections when the switch is connected in series with an unterminated transmission line.

The model data is used to create an On state relationship between the actual drain to source current, i_{ds} , and the actual drain to source voltage, v_{ds} :

$$i_{ds} = f(v_{ds}).$$

This functional relationship depends on the actual source voltage V_s and can be expressed in terms of the corresponding table currents associated with V_s (and expressed as a function of V_{gs}).

If only one [Series MOSFET] table is supplied (as a first order approximation), the functional relationship is assumed to be linearly related to the table drain to source current, I_{ds} , for the given V_{ds} subparameter value and located at the existing gate to source voltage value V_{gs} . This table current is denoted as $I_{ds}(V_{gs}, V_{ds})$. The functional relationship becomes:

$$i_{ds} = I_{ds}(V_{gs}, V_{ds}) * v_{ds} / V_{ds}.$$

More than one [Series MOSFET] table is permitted, but it is simulator dependent how the data will be used. Each successive [Series MOSFET] table must have a different subparameter value for V_{ds} . The number of tables must not exceed 100.

C_{comp} values are ignored for [Series MOSFET] models.

[On]

[Series MOSFET]

Vds = 1.0

Voltage	I(typ)	I(min)	I(max)	
5.0V	257.9m	153.3m	399.5m	Defines the Ids current as a function of Vgs, for Vds = 1.0
4.0V	203.0m	119.4m	317.3m	
3.0V	129.8m	74.7m	205.6m	
2.0V	31.2m	16.6m	51.0m	
1.0V	52.7p	46.7p	56.7p	
0.0V	0.0p	0.0p	0.0p	

Keyword: [Ramp]

Required: Yes, except for inputs, terminators, Series and Series_switch model types.

Description: Defines the rise and fall times of a buffer. The ramp rate does not include packaging but does include the effects of the C_comp parameter.

Sub-Params: dV/dt_r, dV/dt_f, R_load

Usage Rules: The rise and fall time is defined as the time it takes the output to go from 20% to 80% of its final value. The ramp rate is defined as:

$$\frac{dV}{dt} = \frac{20\% \text{ to } 80\% \text{ voltage swing}}{\text{Time it takes to swing the above voltage}}$$

The ramp rate must be specified as an explicit fraction and must not be reduced. The [Ramp] values can use "NA" for the min and max values only. The R_load subparameter is optional if the default 50 ohm load is used. The R_load subparameter is required if a non-standard load is used.

[Ramp]

variable	typ	min	max
dV/dt_r	2.20/1.06n	1.92/1.28n	2.49/650p
dV/dt_f	2.46/1.21n	2.21/1.54n	2.70/770p
R_load = 300ohms			

Keywords: [Rising Waveform], [Falling Waveform]

Required: No

Description: Describes the shape of the rising and falling edge waveforms of a driver.

Sub-Params: R_fixture, V_fixture, V_fixture_min, V_fixture_max, C_fixture, L_fixture, R_dut, L_dut, C_dut

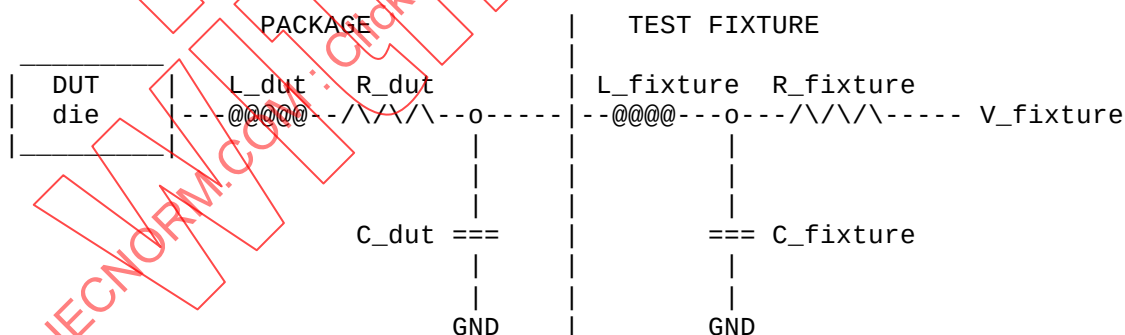
Usage Rules: Each [Rising Waveform] and [Falling Waveform] keyword introduces a table of time vs. voltage points that describe the shape of an output waveform. These time/voltage points are taken under the conditions specified in the R/L/C/V_fixture and R/L/C_dut subparameters. The table itself consists of one column of time points, then three columns of voltage points in the standard typ, min, and max format. The four entries must be placed on a single line and must be separated by at least one white space. All four columns are required. However, data is only required in the typical column. If minimum or maximum data is not available, use the

reserved word "NA". The first value in the time column need not be '0'. Time values must increase as one parses down the table. The waveform table can contain a maximum of 100 data points. A maximum of 100 waveform tables are allowed per model. Note that for backward compatibility, the existing [Ramp] keyword is still required. The data in the waveform table is taken with the effects of the C_comp parameter included.

A waveform table must include the entire waveform; i.e., the first entry (or entries) in a voltage column must be the DC voltage of the output before switching and the last entry (or entries) of the column must be the final DC value of the output after switching. Each table must contain at least two entries. Thus, numerical values are required for the first and last entries of any column containing numerical data.

A [Model] specification can contain more than one rising edge or falling edge waveform table. However, each new table must begin with the appropriate keyword and subparameter list as shown below. If more than one rising or falling edge waveform table is present, then the data in each of the respective tables must be time correlated. In other words, the rising (falling) edge data in each of the rising (falling) edge waveform tables must be entered with respect to a common reference point on the input stimulus waveform.

The 'fixture' subparameters specify the loading conditions under which the waveform is taken. The R_dut, C_dut, and L_dut subparameters are analogous to the package parameters R_pkg, C_pkg, and L_pkg and are used if the waveform includes the effects of pin inductance/capacitance. The diagram below shows the interconnection of these elements.



NOTE: The use of L_dut, R_dut, and C_dut is strongly discouraged in developing Waveform data from simulation models. Some simulators may ignore these parameters because they may introduce numerical time constant artifacts.

Only the `R_fixture` and `V_fixture` subparameters are required, the rest of the subparameters are optional. If a subparameter is not used, its value defaults to zero. The subparameters must appear in the text after the keyword and before the first row of the waveform table.

V_fixture defines the voltage for typ, min, and max supply conditions. However, when the fixture voltage is related to the power supply voltages, then the subparameters V_fixture_min and V_fixture_max can be used to further specify the fixture voltage for min and max supply voltages.

NOTE: Test fixtures with R_fixture and V_fixture, V_fixture_min, and V_fixture_max only are strongly encouraged because they provide the BEST set of data needed to produce the best model for simulation. C_fixture and L_fixture can be used to produce waveforms which describe the typical test case setups for reference.

NOTE: In most cases two [Rising Waveform] tables and two [Falling Waveform] tables will be necessary for accurate modeling.

All tables assume that the die capacitance is included. Potential numerical problems associated with processing the data using the effective C_comp for effective die capacitance may be handled differently among simulators.

[Rising Waveform]

R_fixture = 50

V_fixture = 0.0

C_fixture = 50p

L_fixture = 2n

C_dut = 7p

R_dut = 1m

L_dut = 1n

Time	V(typ)	V(min)	V(max)
0.0000s	25.2100mV	15.2200mV	43.5700mV
0.2000ns	2.3325mV	-8.5090mV	23.4150mV
0.4000ns	0.1484V	15.9375mV	0.3944V
0.6000ns	0.7799V	0.2673V	1.3400V
0.8000ns	1.2960V	0.6042V	1.9490V
1.0000ns	1.6603V	0.9256V	2.4233V
1.2000ns	1.9460V	1.2050V	2.8130V
1.4000ns	2.1285V	1.3725V	3.0095V
1.6000ns	2.3415V	1.5560V	3.1265V
1.8000ns	2.5135V	1.7015V	3.1600V
2.0000ns	2.6460V	1.8085V	3.1695V
...			
10.0000ns	2.7780V	2.3600V	3.1670V

[Falling Waveform]

R_fixture = 50

V_fixture = 5.5

V_fixture_min = 4.5

V_fixture_max = 5.5

Time	V(typ)	V(min)	V(max)
0.0000s	5.0000V	4.5000V	5.5000V
0.2000ns	4.7470V	4.4695V	4.8815V
0.4000ns	3.9030V	4.0955V	3.5355V
0.6000ns	2.7313V	3.4533V	1.7770V
0.8000ns	1.8150V	2.8570V	0.8629V
1.0000ns	1.1697V	2.3270V	0.5364V

1.2000ns	0.7539V	1.8470V	0.4524V
1.4000ns	0.5905V	1.5430V	0.4368V
1.6000ns	0.4923V	1.2290V	0.4266V
1.8000ns	0.4639V	0.9906V	0.4207V
2.0000ns	0.4489V	0.8349V	0.4169V
...			
10.0000ns	0.3950V	0.4935V	0.3841V

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Section 6a

A D D S U B M O D E L D E S C R I P T I O N

The [Add Submodel] keyword can be used under a top-level [Model] keyword to add special-purpose functionality to the existing top-level model. This section describes the structure of the top-level model and the submodel.

TOP-LEVEL MODEL:

When special-purpose functional detail is needed, the top-level model can call one or more submodels. The [Add Submodel] keyword is positioned after the initial set of required and optional subparameters of the [Model] keyword and among the keywords under [Model].

The [Add Submodel] keyword lists of name of each submodel and the permitted mode (Driving, Non-Driving or All) under which each added submodel is used.

SUBMODEL:

A submodel is defined using the [Submodel] keyword. It contains a subset of keywords and subparameters used for the [Model] keyword along with other keywords and subparameters that are needed for the added functionality.

The [Submodel] and [Submodel Spec] keywords are defined first since they are used for all submodels

The only required subparameter in [Submodel] is Submodel_type to define the list of submodel types. No subparameters under [Model] are permitted under the [Submodel] keyword.

The following set of keywords that are defined under the [Model] keyword are supported by the [Submodel] keyword:

- [Pulldown]
- [Pullup]
- [GND Clamp]
- [POWER Clamp]
- [Ramp]
- [Rising Waveform]
- [Falling Waveform]

The [Voltage Range], [Pullup Reference], [Pulldown Reference], [GND Clamp Reference], and [POWER Clamp Reference] keywords are not permitted. The voltage settings are inherited from the top-level model.

These additional keywords are used only for the [Submodel] are documented in this section:

[Submodel Spec]
 [GND Pulse Table]
 [POWER Pulse Table]

The application of these keywords depends upon the Submodel_type entries listed below:

Dynamic_clamp
 Bus_hold

Permitted keywords that are not defined for any of these submodel types are ignored. The rules for what set of keywords are required are found under the Dynamic Clamp and Bus Hold headings of this section.

Keyword:	[Submodel]
Required:	No
Description:	Used to define a submodel, and its attributes.
Sub-Params:	Submodel_type
Usage Rules:	Each submodel must begin with the keyword [Submodel]. The submodel name must match the one that is listed under an [Add Submodel] keyword and must not contain more than 20 characters. A .ibs file must contain enough [Submodel] keywords to cover all of the model names specified under the [Add Submodel] keyword. Submodel_type subparameter is required and must be one of the following: Dynamic_clamp, Bus_hold The C_comp subparameter is not permitted under the [Submodel] keyword. The total effective die capacitance including the submodel contributions are provided in the top-level model.
Other Notes:	The following list of keywords that are defined under the [Model] keyword can be used under [Submodel]: [Pulldown], [Pullup], [GND Clamp], [POWER Clamp], [Ramp], [Rising waveform], and [Falling waveform]. The following list of additional keywords can be used: [Submodel Spec], [GND Pulse Table], and [POWER Pulse Table].
[Submodel]	Dynamic_clamp1
Submodel_type	Dynamic_clamp

Keyword:	[Submodel Spec]
Required:	No
Description:	The [Submodel Spec] keyword defines four columns under which specification and information subparameters are defined for submodels.
Sub-Params:	V_trigger_r, V_trigger_f, Off_delay
Usage Rules:	The [Submodel Spec] is to be used only with submodels. The following subparameters are used:

V_trigger_r	Rising edge trigger voltage
V_trigger_f	Falling edge trigger voltage
Off_delay	Turn-off delay from V_trigger_r or V_trigger_f

For each subparameter contained in the first column, the remaining three hold its typical, minimum and maximum values. The entries of typical, minimum and maximum be must be placed on a single line and must be separated by at least one white space. All four columns are required under the [Submodel Spec] keyword. However, data is required only in the typical column. If minimum and/or maximum values are not available, the reserved word "NA" must be used to indicate the typical value by default.

The values in the minimum and maximum columns usually correspond to the values in the same columns for the inherited top-level voltage range or reference voltages in the top-level model. The V_trigger_r and V_trigger_f subparameters should hold values in the minimum and maximum columns that correspond to the voltage range or reference voltages of the top-level model. The Off_delay subparameter, however, is an exception to this rule because in some cases it may be completely or or partially independent from supply voltages and/or manufacturing process variations. Therefore the minimum and maximum entries for the Off_delay subparameter should be ordered simply by their magnitude.

Unless noted, each [Submodel Spec] subparameter is independent of any other subparameter.

V_trigger_r, V_trigger_f rules:

The voltage trigger values for the rising and falling edges provide the starting time when an action is initiated.

Off_delay rules:

The functionality of the Off_delay subparameter is to provide an additional time related mechanism to turn off circuit elements.

Dynamic Clamp Example:

[Submodel Spec]				
Subparameter	typ	min	max	
V_trigger_r	3.6	2.9	4.3	Starts power pulse table
V_trigger_f	1.4	1.2	1.6	Starts gnd pulse table

Bus Hold Example:

[Submodel Spec]				
Subparameter	typ	min	max	
V_trigger_r	3.1	2.4	3.7	Starts low to high bus hold transition

V_trigger_f	1.8	1.6	2.0	Starts high to low bus hold transition
Bus_hold application with pullup structure triggered on and then clocked off:				
[Submodel Spec]				
Subparameter	typ	min	max	
V_trigger_r	3.1	2.4	3.7	Low to high transition triggers the turn on process of the pullup
V_trigger_f	-10.0	-10.0	-10.0	Not used, so trigger voltages are set out of range
Off_delay	5n	6n	4n	Time from rising edge trigger at which the pullup turned off

Dynamic Clamp:

When the Submodel_type subparameter under the [Submodel] keyword is set to Dynamic_clamp, the submodel describes the dynamic clamp functionality.

The [GND Pulse Table] and [POWER Pulse Table] keywords are defined. An example for a complete dynamic clamp model is provided.

Keywords:	[GND Pulse Table], [POWER Pulse Table]
Required:	No
Description:	Used to specify the offset voltage versus time of [GND Clamp] and [POWER Clamp] tables within submodels.
Usage Rules:	Each [GND Pulse Table] and [POWER Pulse Table] keyword introduces a table of time versus vs. points that describe the shape of an offset voltage from the [GND Clamp Reference] voltage (or default ground) or the [POWER Clamp Reference] voltage (or default [Voltage Range] voltage). Note, these voltage values are inherited from the top-level model.
	The table itself consists of one column of time points, then three columns of voltage points in the standard typ, min, and max format. The four entries must be placed on a single line and must be separated by at least one white space. All four columns are required. However, data is only required in the typical column. If minimum or maximum data is not available, use the reserved word "NA". Time values must increase as one parses down the table. The waveform table can contain of maximum of 100 data points.
	Each table must contain at least two entries. Thus, numerical values are required for the first and last entries of any column containing numerical data.
	The voltage entries in both the [Gnd Pulse Table] and [POWER Pulse Table] tables are directly measured offsets. At each instance, the [Gnd Pulse Table] voltage is ADDED to the [GND Clamp] table voltages to provide the shifted table voltages.

At each instance, the [POWER Pulse Table] voltage is SUBTRACTED (because of polarity conventions) from the [POWER Clamp] table voltages to provide the shifted table voltages.

Only one [GND Pulse Table] and one [POWER Pulse Table] are allowed per model.

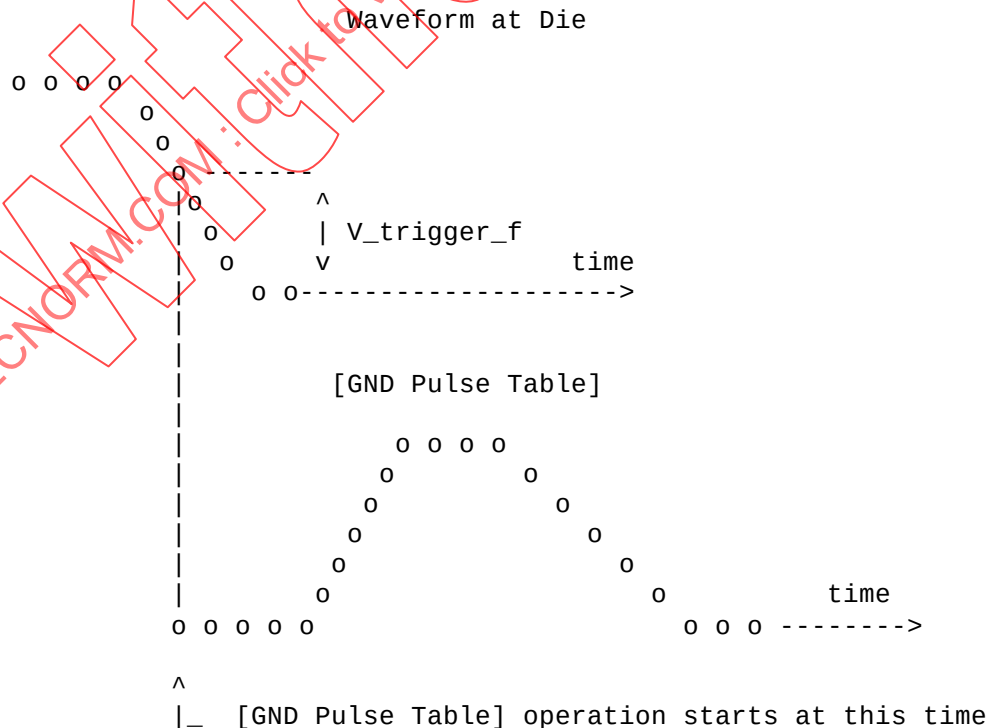
The [GND Pulse Table] and [POWER Pulse Table] interact with [Submodel Spec] subparameters V_trigger_f and V_trigger_r. Several modes of operation exist based on whether a pulse table and its corresponding trigger subparameter are given. These modes are classified as triggered and static.

Triggered Mode:

For triggered mode a pulse table must exist and include the entire waveform; i.e., the first entry (or entries) in a voltage column must be equal to the last entry.

Also, a corresponding [Submodel Spec] V_trigger_* subparameter must exist. The triggered interaction is described:

The V_trigger_f subparameter under [Submodel Spec] is used to detect when the falling edge waveform at the die passes the trigger voltage. At that time the [Gnd Pulse Table] operation starts. Similarly, the V_trigger_r subparameter is used to detect when the rising edge waveform at the die passes the trigger voltage. At that time [POWER Pulse Table] operation starts. The [GND Pulse Table] dependency is shown below:



The V_trigger_r and [POWER Pulse Table] operate in a similar manner. When the V_trigger_r voltage value is reached on the rising edge, the [POWER Pulse Table] is started. Normally the offset voltage entries in the [POWER Pulse Table] are negative.

Static Mode:

When the [GND Pulse Table] keyword does not exist, but the added model [GND Clamp] table does exist, the added model [GND Clamp] is used directly. Similarly, when the [POWER Pulse Table] keyword does not exist, but the added model [POWER Clamp] table does exist, the added model [POWER Clamp] is used directly.

This mode provides additional fixed clamping to an I/O_* buffer or a 3-state buffer when it is used as a driver.

Example of Dynamic_clamp Model with both dynamic GND and POWER clamps:

[Submodel] Dynamic_Clamp_1
Submodel_type Dynamic_clamp

[Submodel Spec]

Subparameter	typ	min	max	
V_trigger_f	1.4	1.2	1.6	Falling edge trigger
V_trigger_r	3.6	2.9	4.3	Rising edge trigger

	typ	min	max
[Voltage Range]	5.0	4.5	5.5

Note, the actual voltage range and reference voltages are inherited from the top-level model.

[GND Pulse Table] | GND Clamp offset table

Time	V(typ)	V(min)	V(max)
0	0	0	0
1e-9	0	0	0
2e-9	0.9	0.8	1.0
10e-9	0.9	0.8	1.0
11e-9	0	0	0

[GND Clamp] | Table to be offset

Voltage	I(typ)	I(min)	I(max)
-5.000	-3.300e+01	-3.000e+01	-3.500e+01
-4.000	-2.300e+01	-2.200e+01	-2.400e+01
-3.000	-1.300e+01	-1.200e+01	-1.400e+01
-2.000	-3.000e+00	-2.300e+00	-3.700e+00
-1.900	-2.100e+00	-1.500e+00	-2.800e+00
-1.800	-1.300e+00	-8.600e-01	-1.900e+00
-1.700	-6.800e-01	-4.000e-01	-1.100e+00
-1.600	-2.800e-01	-1.800e-01	-5.100e-01
-1.500	-1.200e-01	-9.800e-02	-1.800e-01
-1.400	-7.500e-02	-7.100e-02	-8.300e-02
-1.300	-5.750e-02	-5.700e-02	-5.900e-02

-1.200	-4.600e-02	-4.650e-02	-4.550e-02
-1.100	-3.550e-02	-3.700e-02	-3.450e-02
-1.000	-2.650e-02	-2.850e-02	-2.500e-02
-0.900	-1.850e-02	-2.100e-02	-1.650e-02
-0.800	-1.200e-02	-1.400e-02	-9.750e-03
-0.700	-6.700e-03	-8.800e-03	-4.700e-03
-0.600	-3.000e-03	-4.650e-03	-1.600e-03
-0.500	-9.450e-04	-1.950e-03	-3.650e-04
-0.400	-5.700e-05	-2.700e-04	-5.550e-06
-0.300	-1.200e-06	-1.200e-05	-5.500e-08
-0.200	-3.000e-08	-5.000e-07	0.000e+00
-0.100	0.000e+00	0.000e+00	0.000e+00
0.000	0.000e+00	0.000e+00	0.000e+00
5.000	0.000e+00	0.000e+00	0.000e+00

[POWER Pulse Table]

| POWER Clamp offset table

Time	V(typ)	V(min)	V(max)
0	0	0	0
1e-9	0	0	0
2e-9	-0.9	-1.0	-0.8
10e-9	-0.9	-1.0	-0.8
11e-9	0	0	0

[POWER Clamp]

| Table to be offset

Voltage	I(typ)	I(min)	I(max)
-5.000	1.150e+01	1.100e+01	1.150e+01
-4.000	7.800e+00	7.500e+00	8.150e+00
-3.000	4.350e+00	4.100e+00	4.700e+00
-2.000	1.100e+00	8.750e-01	1.300e+00
-1.900	8.000e-01	6.050e-01	1.000e+00
-1.800	5.300e-01	3.700e-01	7.250e-01
-1.700	2.900e-01	1.800e-01	4.500e-01
-1.600	1.200e-01	6.850e-02	2.200e-01
-1.500	3.650e-02	2.400e-02	6.900e-02
-1.400	1.200e-02	1.100e-02	1.600e-02
-1.300	6.300e-03	6.650e-03	6.100e-03
-1.200	4.200e-03	4.750e-03	3.650e-03
-1.100	2.900e-03	3.500e-03	2.350e-03
-1.000	1.900e-03	2.450e-03	1.400e-03
-0.900	1.150e-03	1.600e-03	7.100e-04
-0.800	5.500e-04	9.150e-04	2.600e-04
-0.700	1.200e-04	4.400e-04	5.600e-05
-0.600	5.400e-05	1.550e-04	1.200e-05
-0.500	1.350e-05	5.400e-05	1.300e-06
-0.400	8.650e-07	7.450e-06	4.950e-08
-0.300	6.250e-08	7.550e-07	0.000e+00
-0.200	0.000e+00	8.400e-08	0.000e+00
-0.100	0.000e+00	0.000e-08	0.000e+00
0.000	0.000e+00	0.000e+00	0.000e+00

Bus Hold:

When the Submodel_type subparameter under the [Submodel] keyword is set to Bus_hold, the added model describes the bus hold functionality. However, while described in terms of bus hold functionality, active terminators can also be modeled.

Existing keywords and subparameters are used to describe bus hold models. The [Pullup] and [Pulldown] tables both are used to define an internal buffer that is triggered switch to its opposite state. This switching transition is specified by a [Ramp] keyword or by the [Rising Waveform] and [Falling Waveform] keywords. The usage rules for these keywords are the same as under the [Model] keyword. In particular, at least either the [Pullup] or [Pulldown] keyword is required. Also, the [Ramp] keyword is required, even if the [Rising Waveform] and [Falling Waveform] tables exist. However, the voltage ranges and reference voltages are inherited from the top-level model.

For bus hold submodels, the [Submodel Spec] keyword, V_trigger_r, and V_trigger_f are required. The Off_delay subparameter is optional, but can only be used if the submodel consists of a pullup or a pulldown structure only, and not both. Devices which have both pullup and pulldown structures controlled in this fashion can be modeled using two submodels, one for each half of the circuit.

The transition is triggered by action at the die using the [Submodel Spec] V_trigger_r and V_trigger_f subparameters as follows:

If the starting voltage is below V_trigger_f, then the bus hold model is set to the low state causing additional pulldown current. If the starting voltage is above V_trigger_r, the bus hold model is set to the high state for additional pullup current. When the input passes through V_trigger_f during a high-to-low transition at the die, the bus hold output switches to the low state. Similarly, when the input passes through V_trigger_r during a low-to-high transition at the die, the bus hold output switches to the high state.

If the bus hold submodel has a pullup structure only, V_trigger_r provides the time when its pullup is turned on and V_trigger_f or Off_delay provides the time when it is turned off, whichever occurs first. Similarly, if the submodel has a pulldown structure only, V_trigger_f provides the time when its pulldown is turned on and V_trigger_r or Off_delay provides the time when it is turned off, whichever occurs first. The required V_trigger_r and V_trigger_f voltage entries can be set to values outside of the input signal range if the pullup or pulldown structures are to be held on until the Off_delay turns them off.

The starting mode for each of the submodels which include the Off_delay subparameter of the [Submodel Spec] keyword is the off state. Also, while two submodels provide the desired operation, either of the submodels may exist without the other to simulate turning on and off only a pullup or a pulldown current.

No additional keywords are needed for this functionality.

| Complete Bus Hold Model Example:

[Submodel] Bus_hold_1
Submodel_type Bus_hold

[Submodel Spec]

Subparameter	typ	min	max	
V_trigger_f	1.3	1.2	1.4	Falling edge trigger
V_trigger_r	3.1	2.6	4.6	Rising edge trigger

	typ	min	max
[Voltage Range]	5.0	4.5	5.5

Note, the actual voltage range and reference voltages are inherited from the top-level model.

[Pulldown]

-5V	-100uA	-80uA	-120uA
-1V	-30uA	-25uA	-40uA
0V	0	0	0
1V	30uA	25uA	40uA
3V	50uA	45uA	50uA
5V	100uA	80uA	120uA
10v	120uA	90uA	150uA

[Pullup]

-5V	100uA	80uA	120uA
-1V	30uA	25uA	40uA
0V	0	0	0
1V	-30uA	-25uA	-40uA
3V	-50uA	-45uA	-50uA
5V	-100uA	-80uA	-120uA
10v	-120uA	-90uA	-150uA

[Ramp]

	typ	min	max
dV/dt_r	2.0/0.50n	2.0/0.75n	2.0/0.35n
dV/dt_f	2.0/0.50n	2.0/0.75n	2.0/0.35n

R_load = 500

| Complete Pullup Timed Latch Example:

[Submodel] Timed_pullup_latch
Submodel_type Bus_hold

[Submodel Spec]

Subparameter	typ	min	max	
V_trigger_r	3.1	2.6	4.6	Rising edge trigger Values could be set out of range to disable the trigger
V_trigger_f	1.3	1.2	1.4	Falling edge trigger
Off_delay	3n	5n	2n	Delay to turn off the pullup table

Note that if the input signal goes above the V_trigger_r value, the pulldown structure will turn off even if the timer didn't expire yet.

	typ	min	max
[Voltage Range]	5.0	4.5	5.5

Note, the actual voltage range and reference voltages are inherited from the top-level model.

[Pulldown]

-5V	-100uA	-80uA	-120uA
-1V	-30uA	-25uA	-40uA
0V	0	0	0
1V	30uA	25uA	40uA
3V	50uA	45uA	50uA
5V	100uA	80uA	120uA
10v	120uA	90uA	150uA

[Pullup] table is omitted to signal open_source functionality

[Ramp]

	typ	min	max
dV/dt_r	2.0/0.50n	2.0/0.75n	2.0/0.35n
dV/dt_f	2.0/0.50n	2.0/0.75n	2.0/0.35n
R_load = 500			

Section 7

P A C K A G E M O D E L I N G

The [Package Model] keyword is optional. If more than the default RLC package model is desired, use the [Define Package Model] keyword.

Use the [Package Model] keyword within a [Component] to indicate the package model for that component. The specification permits .ibs files to contain the following additional list of package model keywords. Note that the actual package models can be in a separate <package_file_name>.pkg file or can exist in the IBIS files between the [Define Package Model]... [End Package Model] keywords for each package model that is defined. For reference, these keywords are listed below. Full descriptions follow. Simulators that do not support these keywords will ignore all entries between the [Define Package Model] and [End Package Model] keywords.

[Define Package Model]	Required if the [Package Model] keyword is used
[Manufacturer]	(note 1)
[OEM]	(note 1)
[Description]	(note 1)
[Number Of Sections]	(note 2)
[Number Of Pins]	(note 1)
[Pin Numbers]	(note 1)
[Model Data]	(note 2)
[Resistance Matrix]	Optional when [Model Data] is used
[Inductance Matrix]	(note 3)
[Capacitance Matrix]	(note 3)
[Bandwidth]	Required (for Banded_matrix matrices only)
[Row]	(note 3)
[End Model Data]	(note 2)
[End Package Model]	(note 1)

(note 1) Required when the [Define Package Model] keyword is used

(note 2) Either the [Number Of Sections] or the [Model Data]/[End Model Data] keywords are required. Note that [Number of Sections] and the [Model Data]/[End Model Data] keywords are mutually exclusive.

(note 3) Required when the [Define Package Model] keyword is used and the [Number Of Sections] keyword is not used.

When package model definitions occur within a .ibs file, their scope is "local" -- they are known only within that .ibs file and no other. In addition, within that .ibs file, they override any globally defined package models that have the same name.

USAGE RULES FOR THE .PKG FILE:

Package models are stored in a file whose name looks like:

<filename>.pkg.

The <filename> provided must adhere to the General Syntax Rules. Use the ".pkg" extension to identify files containing package models. The .pkg file must contain all of the required elements of a normal .ibs file, including [IBIS Ver], [File Name], [File Rev], and the [End] keywords. Optional elements include the [Date], [Source], [Notes], [Disclaimer], [Copyright], and [Comment Char] keywords.

All of the elements follow the same rules as those for a normal .ibs file.

Note that the [Component] and [Model] keywords are not allowed in the .pkg file. The .pkg file is for package models only.

```
=====
Keyword:  [Define Package Model]
Required:   Yes
Description: Marks the beginning of a package model description.
Usage Rules: If the .pkg file contains data for more than one package, each
              section must begin with a new [Define Package Model] keyword.
              The length of the package model name must not exceed 40
              characters in length. Blank characters are allowed. For
              every package model name defined under the [Package Model]
              keyword, there must be a matching [Define Package Model]
              keyword.
=====
```

```
[Define Package Model]    QS-SMT-cer-8-pin-pkgs
=====
```

```
=====
Keyword:  [Manufacturer]
Required:   Yes
Description: Declares the manufacturer of the component(s) that use this
              package model.
Usage Rules: The length of the manufacturer's name must not exceed 40
              characters (blank characters are allowed, e.g., Texas
              Instruments). In addition, each manufacturer must use a
              consistent name in all .ibs and .pkg files.
=====
```

```
[Manufacturer]    Quality Semiconductors Ltd.
=====
```

```
=====
Keyword:  [OEM]
Required:   Yes
Description: Declares the manufacturer of the package.
Usage Rules: The length of the manufacturer's name must not exceed 40
              characters (blank characters are allowed). In addition, each
              manufacturer must use a consistent name in all .ibs and .pkg
              files.
Other Notes: This keyword is useful if the semiconductor vendor sells a
              single IC in packages from different manufacturers.
=====
```

```
[OEM]    Acme Packaging Co.
=====
```

```
=====
Keyword:  [Description]
Required:   Yes
Description: Provides a concise yet easily human-readable description of
              what kind of package the [Package Model] is representing.
Usage Rules: The description must be less than 60 characters in length,
=====
```

must fit on a single line, and may contain spaces.

[Description] 220-Pin Quad Ceramic Flat Pack

Keyword: [Number Of Sections]

Required: No

Description: Defines the maximum number of sections that make up a 'package stub'. A package stub is defined as the connection between the die pad and the corresponding package pin; it can include (but is not limited to) the bondwire, the connection between the bondwire and pin, and the pin itself. This keyword must be used if a modeler wishes to describe any package stub as other than a single, lumped L/R/C. The sections of a package stub are assumed to connect to each other in a series fashion.

Usage Rules: The argument is a positive integer greater than zero. This keyword, if used, must appear in the specification before the [Pin Numbers] keyword. The maximum number of sections includes sections between the Fork and Endfork subparameters.

[Number Of Sections] 3

Keyword: [Number Of Pins]

Required: Yes

Description: Tells the parser how many pins to expect.

Usage Rules: The field must be a positive decimal integer. The [Number Of Pins] keyword must be positioned before the [Pin Numbers] keyword.

[Number Of Pins] 128

Keyword: [Pin Numbers]

Required: Yes

Description: Tells the parser the set of names that are used for the package pins and also defines pin ordering. If the [Number Of Sections] keyword is present it also lists the elements for each section of a pin's die to pin connection.

Sub-Params: Len, L, R, C, Fork, Endfork

Usage Rules: Following the [Pin Numbers] keyword, the names of the pins are listed. There must be as many names listed as there are pins (as given by the preceding [Number Of Pins] keyword). Pin names can not exceed 5 characters in length. The first pin name given is the "lowest" pin, and the last pin given is the "highest." If the [Number Of Sections] keyword is used then each pin name must be followed by one or more of the legal subparameter combinations listed below. If the [Number Of Sections] keyword is not present then subparameter usage is NOT allowed.

Subparameters:

The Len, L, R, and C subparameters specify the length, inductance, capacitance and resistance of each section of each stub on a package.

The Fork and Endfork subparameters are used to denote branches from the main package stub.

Len	The length of a package stub section. Lengths are given in terms of arbitrary 'units'.
L	The inductance of a package stub section, in terms of 'inductance/unit length'. For example, if the total inductance of a section is 3.0nH and the length of the section is 2 'units', the inductance would be listed as $L = 1.5\text{nH}$ (i.e. $3.0 / 2$).
C	The capacitance of a package stub section, in terms of capacitance per unit length.
R	The DC (ohmic) resistance of a package stub section, in terms of ohms per unit length.
Fork	This subparameter indicates that the sections following (up to the Endfork subparameter) are part of a branch off of the main package stub. This subparameter has no arguments.
Endfork	This subparameter indicates the end point of a branch. For every Fork subparameter there must be a corresponding Endfork subparameter. As with the Fork subparameter, the Endfork subparameter has no arguments.

Specifying a Len or L/R/C value of zero is allowed. If $\text{Len} = 0$ is specified, then the L/R/C values are the total for that section. If a non-zero length is specified, then the total L/R/C for a section is calculated by multiplying the value of the Len subparameter by the value of the L, R, or C subparameter. However, if a non-zero length section is specified, the L and C for that section should be treated as distributed elements.

Using The Subparameters to Describe Package Stub Sections:

A section description begins with the Len subparameter and ends with the slash (/) character. The value of the Len, L, R, and C subparameters and the subparameter itself are separated by an equals sign (=); white space around the equals sign is optional. The Fork and Endfork subparameters are placed between section descriptions (i.e. between the concluding slash of one section and the 'Len' parameter that starts another). A particular section description can contain no data (i.e. the description is given as 'Len = 0 /').

Legal Subparameter Combinations for Section Descriptions:

A) A single $\text{Len} = 0$ subparameter, followed by a slash. This is used to describe a section with no data.

B) Len, and one or more of the L, R and C subparameters. If the Len subparameter is given as zero, then the L/R/C subparameters represent lumped elements. If the Len subparameter is non-zero, then the L/R/C subparameters represent distributed elements.

C) Single Fork or Endfork subparameter. Normally, a package stub is described as several sections, with the Fork and EndFork subparameters surrounding a group of sections in the middle of the complete package stub description. However, it is legal for the Fork/Endfork subparameters to appear at the end of a section description. The package pin is connected to the last section of a package stub description not surrounded by a Fork/Endfork statements. See the examples below.

Package Stub Boundaries:

A package stub description starts at the connection to the die and ends at the point at which the package pin interfaces with the board or substrate the IC package is mounted on. Note that in the case of a component with through-hole pins, the package stub description should include only the portion of the pin not physically inserted into the board or socket. However, it is legal for a package stub description to include both the component and socket together if this is how the component is intended to be used.

A three-section package stub description that includes a bond wire (lumped inductance), a trace (treated as a transmission line with DC resistance), and a pin modeled as a lumped L/C element.

[Pin Numbers]

A1 Len=0 L=1.2n/ Len=1.2 L=2.0n C=0.5p R=0.05/ Len=0 L=2.0n C=1.0p/

Pin A2 below has a section with no data

A2 Len=0 L=1.2n/ Len=0/ Len=1.2 L=2.0n C=0.5p R=0.05/ Len=0 L=2.0n C=1.0p/

A section description using the Fork and Endfork subparameters. Note that the indentation of the Fork and Endfork subparameters are for readability are not required.

A1 Len=0 L=2.3n /	bondwire
Len=1.2 L=1.0n C=2.5p /	first section
Fork	indicates the starting of a branch
Len=1.0 L=2.0n C=1.5p /	section
Endfork	ending of the branch
Len=0.5 L=1.0 C=2.5p/	second section
Len=0.0 L=1.5n /	pin

Here is an example where the Fork/Endfork subparameters are at the end of a package stub description

B13 Len=0 L=2.3n /	bondwire
Len=1.2 L=1.0n C=2.5p /	first section
Len=0.5 L=1.0 C=2.5/	second section, pin connects here
Fork	indicates the starting of a branch
Len=1.0 L=2.0n C=1.5p /	section
Endfork	ending of the branch

=====

Keyword: [Model Data]
Required: Yes
Description: Indicates the beginning of the formatted package model data, that can include the [Resistance Matrix], [Inductance Matrix], [Capacitance Matrix], [Bandwidth], and [Row] keywords.

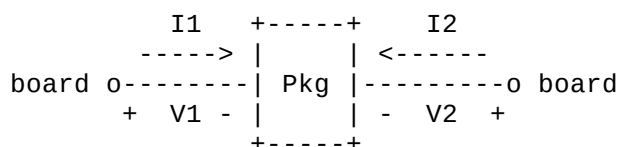
[Model Data]

Keyword: [End Model Data]
Required: Yes
Description: Indicates the end of the formatted model data.
Other Notes: In between the [Model Data] and [End Model Data] keywords is the package model data itself. The data is a set of 3 matrices: the resistance (R), inductance (L), and capacitance (C) matrices. Each matrix can be formatted differently (see below). Use one of the matrix keywords below to mark the beginning of each new matrix.

[End Model Data]

Keywords: [Resistance Matrix], [Inductance Matrix], [Capacitance Matrix]
Required: [Resistance Matrix] is optional. If it is not present, its entries are assumed to be zero. [Inductance Matrix] and [Capacitance Matrix] are required.
Sub-Params: Banded_matrix, Sparse_matrix, or Full_matrix
Description: The subparameters mark the beginning of a matrix, and specify how the matrix data is formatted.
Usage Rules: For each matrix keyword, use only one of the subparameters. After each of these subparameters, insert the matrix data in the appropriate format. (These formats are described in detail below.)
Other Notes: The resistance, inductance, and capacitance matrices are also referred to as "RLC matrices" within this specification.

When measuring the entries of the RLC matrices, either with laboratory equipment or field-solver software, currents are defined as ENTERING the pins of the package from the board (General Syntax Rule #11). The corresponding voltage drops are to be measured with the current pointing "in" to the "+" sign and "out" of the "-" sign.



It is important to observe this convention in order to get the correct signs for the mutual inductances and resistances.

[Resistance Matrix] Banded_matrix
 [Inductance Matrix] Sparse_matrix
 [Capacitance Matrix] Full_matrix

RLC MATRIX NOTES:

For each [Resistance Matrix], [Inductance Matrix], or [Capacitance Matrix] a different format can be used for the data. The choice of formats is provided to satisfy different simulation accuracy and speed requirements. Also, there are many packages in which the resistance matrix can have no coupling terms at all. In this case, the most concise format (Banded_matrix) can be used.

There are two different ways to extract the coefficients that are reported in the capacitance and inductance matrices. For the purposes of this specification, the coefficients reported in the capacitance matrices shall be the 'electrostatic induction coefficients' or 'Maxwell's capacitances'. The Maxwell capacitance K_{ij} is defined as the charge induced on conductor "j" when conductor "i" is held at 1 volt and all other conductors are held at zero volts. Note that K_{ij} (when $i \neq j$) will be a negative number and should be entered as such. Likewise, for the inductance matrix the coefficients for L_{ij} are defined as the voltage induced on conductor "j" when conductor "i"'s current is changed by 1amp/sec and all other conductors have no current change.

One common aspect of all the different formats is that they exploit the symmetry of the matrices they describe. This means that the entries below the main diagonal of the matrix are identical to the corresponding entries above the main diagonal. Therefore, only roughly one-half of the matrix needs to be described. By convention, the main diagonal and the UPPER half of the matrix are provided.

In the following text, we use the notation [I, J] to refer to the entry in row I and column J of the matrix. Note that I and J are allowed to be alphanumeric strings as well as integers. An ordering of these strings is defined in the [Pin Numbers] section. In the following text, "Row 1" means the row corresponding to the first pin.

Also note that the numeric entries of the RLC matrices are standard IBIS floating point numbers. As such, it is permissible to use metric "suffix" notation. Thus, an entry of the C matrix could be given as 1.23e-12 or as 1.23p or 1.23pF.

Full_matrix:

When the Full matrix format is used, the couplings between every pair of elements is specified explicitly. Assume that the matrix has N rows and N columns. The Full_matrix is specified one row at a time, starting with Row 1 and continuing down to Row N.

Each new row is identified with the Row keyword.

```
=====
Keyword:  [Row]
Required: Yes
Description: Indicates the beginning of a new row of the matrix.
Usage Rules: The argument must be one of the pin names listed under the
                [Pin Numbers] keyword.
-----
```

[Row] 3

Following a [Row] keyword is a block of numbers that represent the entries for that row. Suppose that the current row is number M. Then the first number listed is the diagonal entry, [M,M]. Following this number are the entries of the upper half of the matrix that belong to row M: [M, M+1], [M, M+2], ... up to [M,N].

For even a modest-sized package, this data will not all fit on one line. You can break the data up with new-line characters so that the 80 character line length limit is observed.

An example: suppose the package has 40 pins and that we are currently working on Row 19. There is 1 diagonal entry, plus $40 - 19 = 21$ entries in the upper half of the matrix to be specified, for 22 entries total. The data might be formatted as follows:

```
[Row] 19
5.67e-9 1.1e-9 0.8e-9 0.6e-9 0.4e-9 0.2e-9 0.1e-9 0.09e-9
8e-10 7e-10 6e-10 5e-10 4e-10 3e-10 2e-10 1e-10
9e-11 8e-11 7e-11 6e-11 5e-11 4e-11
```

In the above example, the entry 5.67e-9 is on the diagonal of row 19.

Observe that Row 1 always has the most entries, and that each successive row has one fewer entry than the last; the last row always has just a single entry.

Banded_matrix:

A Banded_matrix is one whose entries are guaranteed to be zero if they are farther away from the main diagonal than a certain distance, known as the "bandwidth." Let the matrix size be N x M, and let the bandwidth be B. An entry [I,J] of the matrix is zero if:

$$|I - J| > B$$

where |.| denotes the absolute value.

The Banded matrix is used to specify the coupling effects up to B pins on either side. Two variations are supported. One allows for the coupling to circle back on itself. This is technically a simple form of a bordered block diagonal matrix. However, its data can be completely specified in terms of a Banded_matrix for an N x M matrix consisting of N rows and $M = N + B$ columns. The second variation is just in terms of an N x N matrix where no circle back coupling needs to be specified.

The bandwidth for a Banded_matrix must be specified using the [Bandwidth] keyword:

Keyword: [Bandwidth]

Required: Yes (for Banded_matrix matrices only)

Description: Indicates the bandwidth of the matrix.

Usage Rules: The bandwidth field must be a non-negative integer. This keyword must occur after the [Resistance Matrix], etc.,

keywords, and before the matrix data is given.

[Bandwidth] 10

Specify the banded matrix one row at a time, starting with row 1 and working up to higher rows. Mark each row with the [Row] keyword, as above. As before, symmetry is exploited: do not provide entries below the main diagonal.

For the case where coupling can circle back on itself, consider a matrix of N pins organized into N rows $1 \dots N$ and M columns $1 \dots N, 1 \dots B$. The first row only needs to specify the entries $[1,1]$ through $[1,1+B]$ since all other entries are guaranteed to be zero. The second row will need to specify the entries $[2,2]$ through $[2,2+B]$, and so on. For row K , the entries $[K,K]$ through $[K,K+B]$ are given when $K + B$ is less than or equal to the size of the matrix N . When $K + B$ exceeds N , the entries in the last columns $1 \dots B$ specify the coupling to the first rows. For row K , the entries $[K,K] \dots [K,N] [K,1] \dots [K,R]$ are given where $R = \text{mod}(K + B - 1, N) + 1$. All rows will contain $B + 1$ entries. To avoid redundant entries, the bandwidth is limited to $B \leq \text{int}((N - 1) / 2)$.

For the case where coupling does not circle back on itself, the process is modified. Only N columns need to be considered. When $K + B$ finally exceeds the size of the matrix N , the number of entries in each row starts to decrease; the last row (row N) has only 1 entry. This construction constrains the bandwidth to $B < N$.

As in the Full_matrix, if all the entries for a particular row do not fit into a single 80-character line, the entries can be broken across several lines.

It is possible to use a bandwidth of 0 to specify a diagonal matrix (a matrix with no coupling terms.) This is sometimes useful for resistance matrices.

Sparse_matrix:

A Sparse_matrix is expected to consist mostly of zero-valued entries, except for a few nonzeros. Unlike the Banded_matrix, there is no restriction on where the nonzero entries can occur. This feature is useful in certain situations, such as for Pin Grid Arrays (PGAs).

As usual, symmetry can be exploited to reduce the amount of data by eliminating from the matrix any entries below the main diagonal.

An $N \times N$ Sparse_matrix is specified one row at a time, starting with row 1 and continuing down to row N . Each new row is marked with the [Row] keyword, as in the other matrix formats.

Data for the entries of a row is given in a slightly different format, however. For the entry $[I, J]$ of a row, it is necessary to explicitly list the name of pin J before the value of the entry is given. This specification serves to indicate to the parser where the entry is put into the matrix.

The proper location is not otherwise obvious because of the lack of