
**Hydraulic fluid power —
Determination of the particulate
contamination level of a liquid sample
by automatic particle counting using
the light-extinction principle**

*Transmissions hydrauliques — Détermination du niveau de pollution
particulaire d'un échantillon liquide par comptage automatique des
particules par absorption de lumière*

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 131, *Fluid power systems*, Subcommittee SC 6, *Contamination control*.

This third edition cancels and replaces the second edition (ISO 11500:2008), which has been technically revised.

The main changes are as follows:

- the cleanliness requirements for sample containers have been updated to match ISO 11171;
- the instructions for flushing and diluting solutions using propan-2-ol (2-propanol) and demineralised water have been removed;
- Annex E has been deleted.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

In hydraulic fluid power systems, power is transmitted and controlled through a liquid under pressure within an enclosed circuit. The liquid is both a lubricant and a power-transmitting medium.

The presence of solid contaminant particles in the liquid interferes with the ability of the hydraulic fluid to lubricate and causes wear to the components. The extent of contamination in the fluid has a direct bearing on the performance and reliability of the system, and it is essential to control solid contaminant particles to levels that are considered appropriate for the system concerned.

A quantitative determination of particulate contamination involves precision in obtaining the sample and in determining the extent of contamination. The liquid automatic particle counter (APC), which works on the light-extinction principle, has become an accepted means of determining the extent of contamination. The accuracy of particle count data can be affected by the techniques used to obtain such data.

This document details procedures for the analysis of contaminated liquid samples using an automatic particle counter. Correct use of an automatic particle counter helps to reduce errors and enhances the accuracy of reproducibility in data.

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Hydraulic fluid power — Determination of the particulate contamination level of a liquid sample by automatic particle counting using the light-extinction principle

1 Scope

This document specifies an automatic particle counting procedure for determining the number and sizes of particles present in hydraulic-fluid bottle samples of clear, homogeneous, single-phase liquids using an automatic particle counter (APC) that works on the light-extinction principle.

This document is applicable to the monitoring of:

- a) the cleanliness level of fluids circulating in hydraulic systems;
- b) the progress of a flushing operation;
- c) the cleanliness level of support equipment and test rigs;
- d) the cleanliness level of packaged stock fluid.

NOTE Measurements can be made with particles suspended in the original liquid or in a sample of the liquid diluted with a compatible liquid when APC coincidence error limits are exceeded.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3722, *Hydraulic fluid power — Fluid sample containers — Qualifying and controlling cleaning methods*

ISO 4406, *Hydraulic fluid power — Fluids — Method for coding the level of contamination by solid particles*

ISO 5598, *Fluid power systems and components — Vocabulary*

ISO 11171:2022, *Hydraulic fluid power — Calibration of automatic particle counters for liquids*

ASTM E694-18, *Standard specification for laboratory glass volumetric apparatus*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 5598, ISO 11171 and the following apply.

ISO and IEC maintain terminology databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <https://www.electropedia.org/>

3.1

dilution factor

state when the liquid sample is diluted, at which the multiplier coefficient is required to calculate the number concentration of particles contained in the original liquid sample

3.2

dilution ratio

ratio of the amount of diluted liquid sample to the amount of the diluents added at the time of dilution

3.3

coincidence error limit

highest concentration of NIST RM 8632x that can be counted with an *automatic particle counter* (3.7) with an error of less than 5 % resulting from the presence of more than one particle in the *sensing volume* (3.5) at one time

[SOURCE: ISO 11171:2022, 3.5]

3.4

light extinction

reduction in intensity of a light beam passing through the sensing volume caused by the interaction of the light with single particles

Note 1 to entry: This is also known as light blockage or light obscuration.

3.5

sensing volume

portion of the illuminated region of the sensor through which the fluid stream passes and from which the light is collected by the optical system

[SOURCE: ISO 11171:2022, 3.3]

3.6

threshold noise level

minimum voltage setting of an *automatic particle counter* (3.7) at which the observed pulse-counting frequency does not exceed 60 counts/min due to electrical noise in the absence of flow in the *sensing volume* (3.5)

[SOURCE: ISO 11171:2022, 3.2]

3.7

automatic particle counter

APC

instrument that automatically:

- a) senses individual particles suspended in a controlled volume of fluid using optical *light extinction* (3.4) or light scattering principles;
- b) measures the size of particles;
- c) sorts or compiles particles into size ranges;
- d) counts particles in each size range;
- e) reports the number of particles in each size range per unit volume; and
- f) facilitates instrument calibration according to this document

[SOURCE: ISO 11171:2022, 3.1, modified — Note 1 to entry has been deleted.]

4 Materials and equipment

4.1 Automatic particle counter (APC) for liquids, with bottle sampler utilizing the light extinction principle with at least 8 channels that can be sent at various threshold settings calibrated in accordance with ISO 11171.

4.2 Bottle sampler, used to transfer the liquid being analysed through a sensor, which may be an auxiliary component or a part of the APC itself.

If gas is used to force the liquid through the sensor, the gas shall be filtered through a 0,45 µm filter and shall be free from oil and water.

4.3 Density meter, with an accuracy of 0,001 g/cm³, if the mass-dilution method is used.

4.4 Electronic balance, calibrated, with a resolution of 0,1 mg or better.

4.5 Hot plate, capable of heating to 150 °C ± 2 °C.

4.6 Mechanical shaker, such as a paint or laboratory shaker, suitable for dispersing suspensions.

4.7 Sample bottles, normally flat-bottomed cylindrical bottles made of glass or high-density polyethylene fitted with closures (appropriate bottle caps, for example), and with cleanliness levels lower than 0,5 % of the number of particles (larger than the smallest particle size of interest) expected to be observed in the samples, confirmed in accordance with ISO 3722.

The dimensions of the bottle depend upon the type of bottle sampler in use with the APC, but bottles should normally have a minimum capacity of 250 ml.

4.8 Liquid dispensers, fitted with a 0,45 µm membrane filter directly at the outlet.

4.9 Temperature measuring device, calibrated, with an accuracy of ±1 °C or better.

4.10 Timer, capable of measuring minutes and seconds, calibrated, with an accuracy of 0,1 s or better.

4.11 Ultrasonic bath, rated at a power intensity of 3 000 W/m² to 11 000 W/m² of the bottom area.

4.12 Volumetric glassware, consisting of a range of calibrated graduated cylinders and graduated syringes or dosing pipettes (standard total displacement volumetric ware with multiple markings or air displacement) conforming to at least Class B, as defined in ASTM E694-18. The glassware shall be cleaned and verified in accordance with [6.2](#).

NOTE Examples of appropriate standards for volumetric glassware include ISO 4788 and ISO 8655 (all parts).

5 Diluent liquid

IMPORTANT — Observe standard laboratory safety practices when handling diluents.

5.1 The diluent liquid shall be cleaned to cleanliness levels lower than 0,5 % of the number of concentration of particles (larger than the smallest particle size of interest), which are expected to be observed in the samples, confirmed in accordance with ISO 3722.

NOTE See [Annex C](#) for information about a method for pre-cleaning the diluent.

5.2 The diluent liquid shall be physically and chemically compatible with both the sample liquid and the apparatus used. The diluent is considered acceptable if its refractive index is similar to the refractive index of the hydraulic liquid sample. This is to ensure that the diluent does not affect the particle counts.

The use of a volatile solvent can cause erroneous particle counts due to the generation of air bubbles, i.e. “boiling”, if its vapour pressure is reached in the sensor. This can be alleviated by ensuring that the pressure in the sensor is always above the vapour pressure of any liquids used.

It is necessary to take care when diluting to ensure that the sample and the diluent are mutually miscible and to ensure that the additive packages of the sample oil and diluent are compatible.

NOTE See [Annex B](#) for examples.

6 Pre-test requirements and procedures

6.1 Precautions

6.1.1 Chemicals

Good laboratory practices should be observed in the preparation and use of chemicals used in these procedures, as they can be harmful, toxic or flammable. Take care to ensure compatibility of the chemicals with the materials used. Refer to the material safety data sheet (MSDS) for each chemical and follow the precautions for safe handling and usage described therein.

6.1.2 Electrical interference

Determining the threshold noise level of the APC should be completed in accordance with ISO 11171:2022, A.2. Precautions should be taken to ensure that the threshold noise level is determined with all potential sources of radio frequency interference (RFI) and electro-mechanical interference (EMI) active to simulate the end use case.

The voltage supply to the instrument shall be stable and free of electrical noise.

NOTE 1 An APC is typically a high-sensitivity device and can be affected by RFI or EMI.

NOTE 2 The use of a constant-voltage transformer is considered appropriate.

6.1.3 Use of magnetic stirrer

Do not use a magnetic stirrer for samples containing ferrous or other magnetic particles. If such a stirrer is fitted as standard equipment, it can be necessary to remove or eliminate the drive magnet.

6.1.4 Relative humidity

The relative humidity of the test area should be controlled within the range of 40 % RH to 70 % RH.

NOTE Relative humidity outside of the prescribed range can affect the particle counts.

6.1.5 Sample storage

Store samples susceptible to bacterial growth in sealed containers under refrigerated conditions (at $5\text{ °C} \pm 2\text{ °C}$). Bring refrigerated samples to room temperature prior to unsealing to avoid condensation being introduced. Evaluation and analysis shall be completed within 1 h of reaching room temperature.

6.2 Glassware cleaning procedure

6.2.1 Clean all glassware using a validated cleaning procedure. Validate cleanliness in accordance with ISO 3722. The final solvent liquid used for the flush should be filtered petroleum spirit or equivalent, if the samples being analysed are petroleum-based or synthetic liquids.

6.2.2 The required cleanliness level (RCL) of all glassware shall be such that contaminant thereon cannot significantly contribute to the overall result.

The glassware shall be cleaned to cleanliness levels lower than 0,5 % of the number of concentration of particles (larger than the smallest particle size of interest), which are expected to be observed in the samples, confirmed in accordance with ISO 3722.

6.2.3 Filter all liquids used for cleaning and rinsing through a 1 µm or finer membrane filter.

6.3 APC calibration procedure

Calibration of the APC shall be maintained in accordance with ISO 11171.

6.4 APC operation

6.4.1 Use the APC within the operating limits previously determined by ISO 11171 (refer to [6.3](#)).

6.4.2 Ensure that the APC has been switched on for long enough to become stabilized.

6.4.3 Clean the sensor and associated plumbing lines prior to use by flushing them with filtered solvent (see [6.2.1](#)).

NOTE Cleaning can be achieved by filling a clean sample bottle with filtered solvent, and then flushing the solvent through the sensor and associated plumbing lines, at a flow rate that is approximately 50 % higher than the flow rate used during analysis.

Ensure that the sampling probe is dried before analysing a sample, otherwise, errors can result from the creation of an optical interface between the liquids.

6.4.4 If the sensor has been used previously to analyse a liquid that is not miscible with the liquid being analysed, clean the sensor using the cleaning procedure in [7.3.10](#).

6.5 Sample inspection and preparation before counting

6.5.1 Outline

See [Figure 1](#) for a flowchart that illustrates the procedure for the preparation of a liquid sample for automatic particle counting.

6.5.2 Initial preparation and inspection

Remove any visible contamination from the exterior of the closed sample bottle using a lint-free cloth, and visually inspect the sample for:

- a) cloudiness (which can be an indication of excessive particles or free water);
- b) macroscopic particles;
- c) free water;
- d) inappropriate containers (i.e. leaking or damaged containers or containers not conforming to [4.7](#)).

A sample exhibiting the phenomena described in items a) through d) shall not be counted using the method specified in this document, as these conditions are likely to affect the performance of the sensor. Record the results of visual inspection in the test report [see [Clause 8](#), item p)].

If sample volume is excessive, proceed to [6.5.3](#).

If the sample does not exhibit items a) through d), proceed to [6.5.4](#).

While this document does not require a microscopic examination of the sample, one may be conducted, if desired.

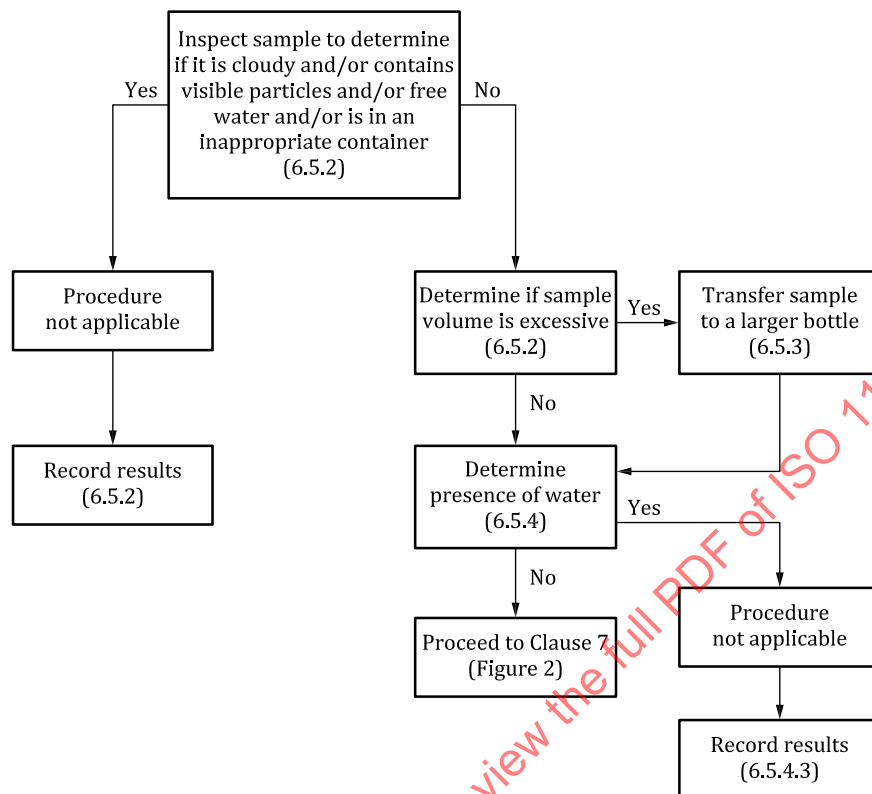


Figure 1 — Flowchart for inspection and preparation of a liquid sample before automatic particle counting

6.5.3 Preparation of sample of excessive volume

6.5.3.1 Estimate the fluid volume in the sample bottle. If the sample takes up less than 80 % of the bottle volume, it may be used. If it takes up more than 80 % of the bottle volume, reduce the volume following the procedure given in [6.5.3.2](#) to [6.5.3.4](#).

It is difficult to achieve re-dispersion of particulate contaminant in sample bottles that are filled to more than 80 % of the bottle volume, which results in a non-homogenous suspension. Use of the procedure specified in [6.5.3.2](#) and [6.5.3.4](#) corrects this problem.

Use caution to ensure that contamination is not added by using the procedure in [6.5.3.2](#) and [6.5.3.4](#).

6.5.3.2 Estimate the volume of the sample and select a clean sample bottle (secondary bottle) such that it is about 50 % to 80 % full when the complete sample is transferred into it. This bottle should fit into the sample-agitating device and the bottle-sampler.

6.5.3.3 Transfer the sample into the secondary sample bottle as follows.

- Pour approximately half of the sample into the secondary bottle.
- Vigorously shake the remaining sample by hand.
- Immediately pour the remaining sample into the secondary sample bottle.

Extreme care should be taken not to spill any of the sample. If any of the sample is spilled or lost during the transfer, the sample should not be counted.

6.5.3.4 Cap the secondary sample bottle.

6.5.4 Determination of presence of water

6.5.4.1 Determine that the amount of water in the sample is not too great to allow the use of the method in this document by either of the following methods.

- a) The hot plate method is as follows.
 - 1) Preheat the hot plate to $140\text{ }^{\circ}\text{C} \pm 2\text{ }^{\circ}\text{C}$.
 - 2) Agitate the sample in the mechanical shaker device for 5 min.
 - 3) Place the sample in an ultrasonic bath and energize the bath for 30 s or until no surfacing air bubbles are observed.
 - 4) Place 1 ml to 2 ml of the sample on the hot plate and observe the reaction of the liquid. If the sample spits or bubbles, it contains water. If the sample spreads out in a thin film without spitting, it does not contain water.
- b) Use another device for measuring relative water content, with the result that the water content shall not exceed 70 % of the saturation level of the hydraulic fluid.

NOTE ISO 760 and ISO 12937 give alternate methods for determining the presence of water.

6.5.4.2 If it is determined that the sample does not contain water in quantities that can affect the particle count provided by the APC, the sample may be used for particle counting in accordance with this document.

6.5.4.3 If it is determined that the sample contains water in quantities that can affect the particle count, the sample shall not be evaluated by the procedure specified in this document. Record the results.

6.6 Determination of need for sample dilution

It is preferable to analyse the sample in an undiluted form. However, dilution is often necessary to reduce the optical density of the sample, its viscosity or the particle concentration. Guidance on determining when dilution is necessary is given in [7.2.1](#).

7 Procedure for determining the particulate contamination level by automatic counting

7.1 Outline

[Figure 2](#) shows a flowchart that illustrates the procedure for determining particulate contamination in liquid samples by automatic counting.

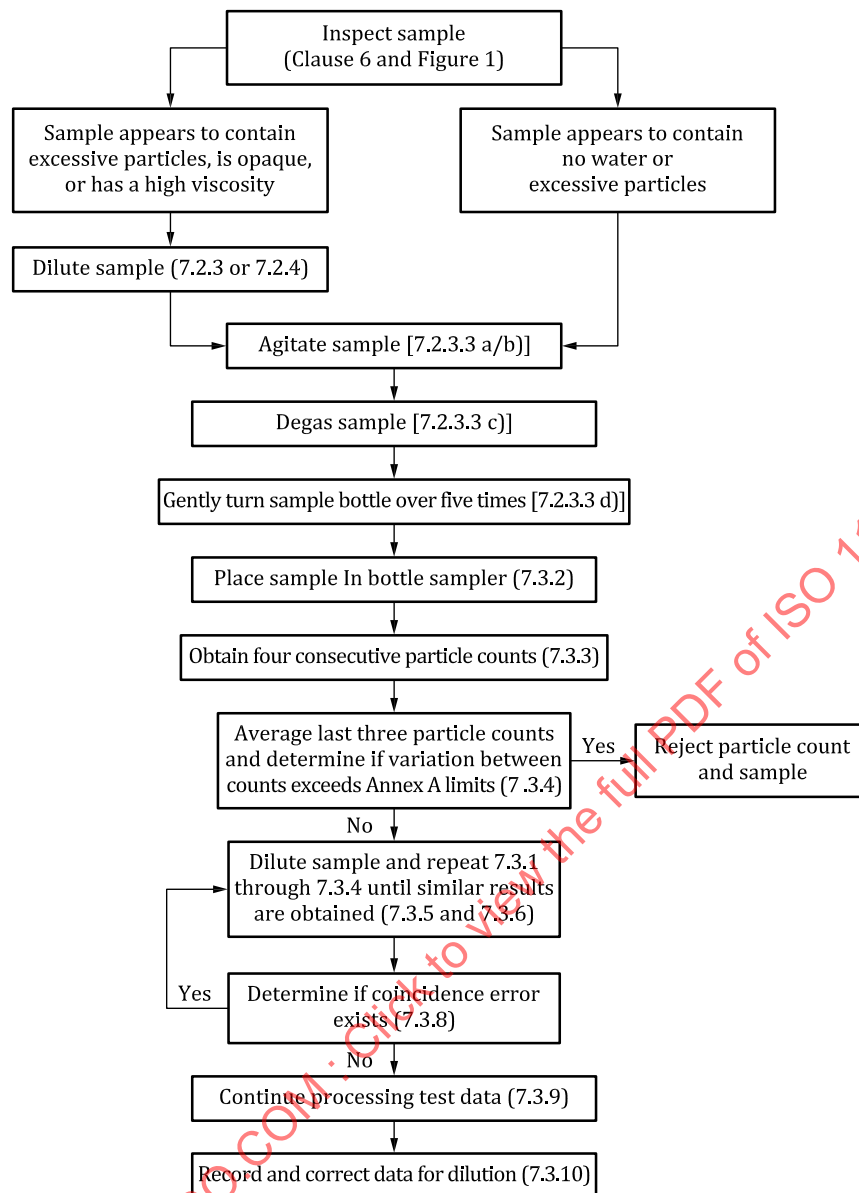


Figure 2 — Flowchart illustrating the procedure for determining particulate contamination in liquid samples by automatic counting

7.2 Sample dilution

7.2.1 Use of sample dilution

Sample dilution can be necessary to:

- reduce the viscosity of the sample commensurate with the design of the bottle sampler;
- reduce the particle population below the coincidence error limit of the APC;
- reduce the optical density of the sample; for example, with very dark liquids, the APC cannot operate correctly;
- perform an exploratory count to optimize the dilution ratio or to verify the validity of the particle count data.

Initial treatment of the sample is based on its opacity. If the sample looks clear (e.g. similar to the clarity of new MIL-PRF-5606), the first particle count may be made without dilution. If the sample is opaque, it should be diluted with clean diluent in the ratio of 25 % sample to 75 % diluent before particle counting.

7.2.2 Precautions

The process of dilution can introduce errors in particle count data because of the addition of extraneous contamination, which is magnified by the dilution ratio. To reduce such errors, dilution should be performed under clean air conditions and all apparatus used in the procedure should be cleaned to the cleanliness level specified in [6.2](#).

Dilution with solvent can change the water saturation characteristics of the sample. When diluting with solvents with a water saturation (solubility of water in the solvent) of less than approximately 100 mg/l, care should be taken to ensure that the water saturation point of the diluted samples is not exceeded.

7.2.3 Volumetric dilution method

7.2.3.1 Use volumetric glassware that conforms to the requirements of [4.12](#).

7.2.3.2 Select the dilution ratio (for example, 10 % sample to 90 % diluent).

7.2.3.3 Prepare the sample as follows.

- a) To prevent the agglomeration of particles, sonicate the sample by placing the sample bottle in an ultrasonic bath and energize the bath for 30 s.
- b) Vigorously shake the sample bottle for a minimum of 60 s.
- c) Degas the sample either by:
 - 1) placing the sample bottle in a vacuum chamber and applying vacuum until no surfacing air bubbles are observed, or
 - 2) placing the sample bottle in the ultrasonic bath and energizing the bath for 30 s or until no surfacing air bubbles are observed. When taking the sample bottle out of the ultrasonic bath, remove the water from the outside of the bottle using a lint-free wiper.
- d) Remove the bottle from the equipment used to degas the sample, and gently turn the sample bottle over at least five times, taking care not to introduce air bubbles into the liquid. Proceed without delay to the next step.

NOTE A commercially available roller bed can be used to turn sample bottles over. Rolling the bottle continuously until it is analysed prevents sedimentation.

7.2.3.4 Measure the quantity of clean diluent necessary to achieve the dilution ratio selected in [7.2.3.2](#), record the volume as V_d , then transfer approximately 50 % of the diluent to a clean sample bottle (secondary sample bottle).

7.2.3.5 Measure the sample volume required to achieve the dilution ratio selected in [7.2.3.2](#).

7.2.3.6 Add the sample collected in [7.2.3.5](#) to the clean diluent in the secondary sample bottle.

7.2.3.7 Rinse the container used to measure the sample in [7.2.3.5](#) with remaining diluent, and add all to the secondary sample bottle. Measure and record the total volume as V_t .

7.2.3.8 Calculate the actual dilution factor, D_F , using [Formula \(1\)](#):

$$D_F = \frac{V_t}{V_t - V_d} \quad (1)$$

where

V_t is the total volume, expressed in millilitres;

V_d is the volume of diluent, expressed in millilitres.

7.2.4 Mass dilution method

7.2.4.1 Determine and record the density of the sample and the diluent. Care should be taken so that the density meter does not add contamination to the sample.

7.2.4.2 Place an empty clean sample bottle (secondary sample bottle) on the balance and either tare the balance or record the mass of the clean sample bottle.

7.2.4.3 Follow steps [7.2.3.1](#) to [7.2.3.3](#) to prepare the sample for dilution.

7.2.4.4 Estimate the sample volume required. Using a pre-cleaned pipette (see [6.2](#)), extract that volume from the original sample bottle immediately after agitation transfer the sample to the secondary sample bottle, and measure and record the mass of the sample in the secondary sample bottle as M_s .

7.2.4.5 Add clean diluent to the secondary sample bottle to obtain the desired dilution ratio, and record the total mass as M_t (that is, the mass of the sample plus the diluent).

7.2.4.6 Calculate the actual dilution ratio, D_R , using [Formula \(2\)](#):

$$D_R = \frac{\frac{M_t - M_s}{\rho_d} + \frac{M_s}{\rho_s}}{\frac{M_s}{\rho_s}} \quad (2)$$

where

M_t is the total mass, expressed in grams;

M_s is the mass of the sample, expressed in grams;

ρ_d is the density of the diluent, expressed in grams per cubic centimetre;

ρ_s is the density of the sample, expressed in grams per cubic centimetre.

7.3 Analysis procedure

7.3.1 Prepare the sample as specified in [7.2.3.3](#).

CAUTION — Elapsed time after final sonication until particle counting should be kept to a minimum; a maximum of 1 min is recommended.

7.3.2 Place the sample in the bottle sampler.

7.3.3 Obtain four consecutive particle counts at the required particle size ranges.

NOTE The following particle sizes are commonly used in reporting such data and also allow approximate comparison with data obtained using APCs calibrated according to ISO 11171: $\geq 4 \mu\text{m(c)}$, $6 \mu\text{m(c)}$, $10 \mu\text{m(c)}$, $14 \mu\text{m(c)}$, $21 \mu\text{m(c)}$, $38 \mu\text{m(c)}$ and $70 \mu\text{m(c)}$.

Record the volume analysed and approximate flow rate through the sensor. See [Annex D](#) for details on how to record the volume analysed and approximate flow rate through the sensor.

7.3.4 Discard the first count and average the next three counts. Reject the data for any particle size if the variation between counts for that size exceeds the limits given in [Annex A](#). Reject the data for the sample if there are less than 6 channels of acceptable data.

If the sample is rejected, consideration should be given to repeating the test using a sample volume that will ensure that a minimum of 20 particles of the largest particle size of interest can be counted.

7.3.5 Normalize the values for counts recorded for the sample using [Formula \(3\)](#):

$$\bar{X}_N = \bar{X} * D_R \quad (3)$$

where

$\bar{X}_N$ is the mean normalized particle concentration, in particles per millilitre, of the undiluted sample;

$\bar{X}$ is the mean particle concentration, in particles per millilitre, of the sample;

D_R is the actual dilution ratio for the sample.

If the sample was not diluted, the value of D_R is 1.

7.3.6 If the sample was not diluted before the first set of particle counts performed in [7.3.3](#), dilute it with clean diluent to a ratio of 10 % sample to 90 % diluent. If the sample was diluted before the first set of particle counts performed in [7.3.3](#), dilute it at a higher dilution ratio than that selected in [7.2.3.8](#) or [7.2.4.6](#).

7.3.7 Repeat [7.3.1](#) to [7.3.4](#) until two sets of data showing similar results are obtained. Results shall be considered as similar if the variation between the normalized particle count reported and the normalized particle count obtained at the next higher dilution ratio is within the limits given in [Annex A](#).

If the initial particle count was carried out without dilution, a dilution of 10 % sample and 90 % diluent is recommended. If the initial sample contained 90 % diluent, a dilution of 5 % sample and 95 % diluent is suggested.

If dilution ratios must be used routinely, it is recommended to repeat [7.3.7](#) for all dilution ratios.

7.3.8 Determine whether the particle count at the smallest particle size of interest exceeds the coincidence error limit of the APC. The magnitude of the coincidence error at a given particle number concentration is governed by the physical dimensions of the sensing volume, as well as the particle size distribution of the sample, including those particles too small to be counted. If coincidence error exists (e.g. normative particle counts obtained at the last two dilutions do not give the same results, the observed particle concentration exceeds the coincidence error limits of the APC, or the APC indicates an over-concentration of particles), select a higher dilution ratio and repeat [7.3.1](#) to [7.3.4](#).

Coincidence causes an overcount of larger particles and an undercount of smaller particles. The coincidence error limit of the APC is the maximum acceptable concentration of all particles larger than the size of the smallest particle detectable by the instrument. All measurements should be taken at particle concentrations that are below 80 % of the APC manufacturer's stated coincidence limit. This

concentration is normally given by the APC manufacturer with a note indicating the probability of coincidence. Coincidence is reduced by dilution (see [7.2](#)).

7.3.9 If coincidence error does not exist, continue by processing the test data.

7.3.10 Record the normalized particle concentration obtained using the lowest acceptable dilution ratio. [Table D.1](#) provides a sample reporting form that may be used to record particle concentration analysis of different liquids.

Take care when the sensor is used to sequentially analyse non-compatible liquids. It is possible that films or droplets of the previous liquid remain on the transparent windows of the sensor, which leads to inaccurate counting. The procedure for changing liquids involves flushing with a succession of solvents, each one compatible with the preceding one. A typical sequence can be as follows:

- a) Flush with petroleum spirit (recommended boiling point between 100 °C and 120 °C) or a solvent with similar properties.
- b) Dry carefully with dry, oil-free compressed air that has passed through a compressed-air filter that is 99,99 % efficient at 2 µm with a pressure rating that is suitable for the application.
- c) Flush with liquid of the actual sample, if sufficient sample is available.

8 Test report

The following minimum information shall be recorded (the form given in [Annex D](#) may be used to record and report data):

- a) laboratory identification;
- b) date of analysis;
- c) sample identification;
- d) sample liquid;
- e) APC manufacturer and model;
- f) sensor model;
- g) sensor flow rate;
- h) sensor coincidence error limit;
- i) date of the most recent ISO 11171 calibration;
- j) diluent volume or mass and density, as required in [7.2](#);
- k) dilution ratio;
- l) diluent used;
- m) volume counted per run;
- n) particle count data with a minimum of three digits per millilitre at the particle sizes analysed in accordance with 7.3;
- o) if desired, contamination level code of the average of each particle count, expressed in accordance with ISO 4406;
- p) a reference to this document (i.e. ISO 11500:2022);
- q) any comments pertaining to the analysis.

9 Identification statement (reference to this document)

It is strongly recommended to manufacturers who have chosen to conform to this document that the following statement be used in test reports, catalogues and sales literature:

“Determination of particulate contamination level of a hydraulic liquid sample by automatic particle counting performed in accordance with ISO 11500:2022.”

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Annex A (normative)

Procedure for performing a statistical check of an automatic particle counter

A.1 After obtaining four particle counts on a particular sample, discard the first particle count, average the next three particle counts and record as $\bar{X}$.

A.2 Calculate the percentage difference, ΔX , between the highest and lowest measured particle count, $X_{\max}$ and $X_{\min}$, respectively, for each particle size using [Formula \(A.1\)](#):

$$\Delta X = \frac{100(X_{\max} - X_{\min})}{\bar{X}} \quad (\text{A.1})$$

A.3 Compare the calculated percentage differences to those shown in [Table A.1](#) for the corresponding average number of particle counts. If the calculated percentage difference is less than or equal to the maximum allowable percentage difference value in [Table A.1](#), correct the data for dilution ratio and volume to determine the number of particles per millilitre of the sample. If the calculated percentage difference exceeds the value given in [Table A.1](#), the data should be rejected, and appropriate steps taken to correct for analytical errors. If particle counts exceed the maximum allowable percentage difference, repeat the analysis.

Table A.1 — Maximum allowable percentage differences in particle counts between runs

Average number of particles counted per run $\bar{X}$	Maximum allowable difference %
$10\,000 \leq \bar{X} < \infty$	11,0
$5\,000 \leq \bar{X} < 10\,000$	11,3
$2\,000 \leq \bar{X} < 5\,000$	11,9
$1\,000 \leq \bar{X} < 2\,000$	13,4
$500 \leq \bar{X} < 1\,000$	15,6
$200 \leq \bar{X} < 500$	19,3
$100 \leq \bar{X} < 200$	27,5
$50 \leq \bar{X} < 100$	37,4
$20 \leq \bar{X} < 50$	51,8

A.4 If fewer than 20 particles of the particle size of interest are counted, repeat the analysis with a sample volume that ensures that a minimum of 20 particles of the largest particle size of interest can be counted or mark the data as advisory only.

Annex B (informative)

Acceptable diluents

CAUTION — Observe standard laboratory safety practices when handling diluents.

For the purposes of this document, the following liquids are considered acceptable for use as diluents:

- a) MIL-PRF-5606 (petroleum-based oil);
- b) mineral oil in the HL-XX category (as classified according to ISO 6743-4);
- c) petroleum spirit, 100 °C to 120 °C grade;
- d) others to suit.

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Annex C (informative)

Method for pre-cleaning diluent and method for incorporating additives into the diluent to eliminate the influence of static electricity on particle counts

CAUTION — Observe standard laboratory safety practices during the processing of samples.

C.1 Diluent pre-cleaning system

C.1.1 The diluent pre-cleaning system should be designed so as to provide diluent that meets or exceeds the cleanliness requirements of [Clause 5](#). A typical diluent pre-cleaning system is shown in [Figure C.1](#).

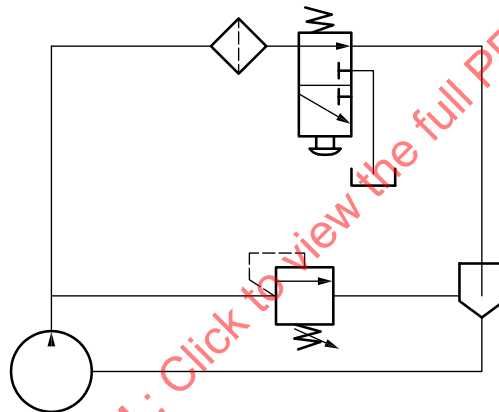


Figure C.1 — Circuit diagram for a typical diluent pre-cleaning system

C.1.2 The reservoir in the diluent pre-cleaning system should have a conical-shaped bottom with an included angle no greater than 90°, and the liquid that goes to the pump should be drawn from the lowest point of the cone. The conical-shaped bottom prevents the heavier particles from accumulating on the bottom of the reservoir and randomly entering the system flow. Piping may be made from polymeric material, stainless steel or copper. Any polymeric material should be compatible with the liquid used. Iron or rubber should not be used as they can contain contaminant generators. The length of the pipe delivering fluid to the valve should be as short as possible and positioned downwards to assist flushing.

C.1.3 A motor-driven impeller pump and a filter with Beta Ratio greater than 1 000 at 4 µm(c) or better should be used.

C.1.4 If the diluent pre-cleaning system uses a valve to control the dispensing of the liquid, a ball valve should be used. A needle valve should not be used. The ball valve should not be used to meter the flow rate and should be used in either the fully open or fully closed position.

Avoid the use of valves that have graphite-filled stem packing materials or silicone lubricants. Position the valve to prevent particles from settling in the valve.