INTERNATIONAL STANDARD

ISO 26900

First edition
2012-07-15

Corrected version
2012-11-01

Space data and information transfer systems — Orbit data messages

Systèmes de transfert des informations et données spatiales — Messages pour données d'orbites

Reference number
ISO 26900:2012(E)

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 26900 was prepared by the Consultative Committee for Space Data Systems (CCSDS) (as CCSDS 502.0-B-2, November 2009) and was adopted (without modifications except those stated in Clause 2 of this International Standard) by Technical Committee ISO/TC 20, *Aircraft and space vehicles*, Subcommittee SC 14, *Space systems and operations*, in collaboration with SC 13, *Space data and information transfer systems*.

ISO 26900 cancels and replaces ISO 22644:2006, which has been technically revised.

This corrected version of ISO 26900:2012 also incorporates the corrections of Technical Corrigendum CCSDS 502.0-B-2 Cor. 1, May 2012. Corrections are identified in the enclosed CCSDS publication by a bar in the margin and the designation "Cor. 1". In addition, the list of equivalent references in Clause 2 of this International Standard has been updated.

Space data and information transfer systems — Orbit data messages

1 Scope

This International Standard specifies three standard message formats for use in transferring spacecraft orbit information between space agencies and commercial or governmental spacecraft operators: the Orbit Parameter Message (OPM), the Orbit Mean-Elements Message (OMM), and the Orbit Ephemeris Message (OEM). Such exchanges are used for

a) pre-flight planning for tracking or navigation support,

b) scheduling tracking support,

c) carrying out tracking operations (sometimes called metric predicts),

d) performing orbit comparisons,

e) carrying out navigation operations such as orbit propagation and orbit reconstruction,

f) assessing mutual physical and electromagnetic interference among satellites orbiting the same celestial body (currently primarily Earth, Moon, and Mars),

g) performing orbit conjunction (collision avoidance) studies, and

h) developing and executing collaborative manoeuvres to mitigate interference or enhance mutual operations.

This International Standard includes sets of requirements and criteria that the message formats have been designed to meet.

NOTE For exchanges where these requirements do not capture the needs of the participating agencies and satellite operators, another mechanism can be selected.

The scope and field of application are furthermore detailed in subclauses 1.1 and 1.2 of the enclosed CCSDS publication.

2 Requirements

Requirements are the technical recommendations made in the following publication (reproduced on the following pages), which is adopted as an International Standard:

CCSDS 502.0-B-2, November 2009, *Orbit data messages.*

For the purposes of international standardization, the modifications outlined below shall apply to the specific clauses and paragraphs of publication CCSDS 502.0-B-2.

Pages i to v

This part is information which is relevant to the CCSDS publication only.

Page 1-3

Add the following information to the reference indicated:

[1] Document CCSDS 301.0-B-4, November 2010, is equivalent to ISO 11104:2011.

[4] Document CCSDS 505.0-B-1, December 2010, is equivalent to ISO 17107:2011

Page G-1

Add the following information to the reference indicated:

[G5] Document CCSDS 504.0-B-1, May 2008, is equivalent to ISO 13541:2010.

3 Revision of publication CCSDS 502.0-B-2

It has been agreed with the Consultative Committee for Space Data Systems that Subcommittee ISO/TC 20/SC 13 will be consulted in the event of any revision or amendment of publication CCSDS 502.0-B-2. To this end, NASA will act as a liaison body between CCSDS and ISO.

The Consultative Committee for Space Data Systems

Recommendation for Space Data System Standards

ORBIT DATA MESSAGES

RECOMMENDED STANDARD

CCSDS 502.0-B-2

Note:
This current issue includes all updates through Technical Corrigendum 1, dated May 2012.

BLUE BOOK
November 2009

(Blank page)

AUTHORITY

Issue:	Recommended Standard, Issue 2
Date:	November 2009
Location:	Washington, DC, USA

This document has been approved for publication by the Management Council of the Consultative Committee for Space Data Systems (CCSDS) and represents the consensus technical agreement of the participating CCSDS Member Agencies. The procedure for review and authorization of CCSDS documents is detailed in the *Procedures Manual for the Consultative Committee for Space Data Systems*, and the record of Agency participation in the authorization of this document can be obtained from the CCSDS Secretariat at the address below.

This document is published and maintained by:

CCSDS Secretariat
Space Communications and Navigation Office, 7L70
Space Operations Mission Directorate
NASA Headquarters
Washington, DC 20546-0001, USA

STATEMENT OF INTENT

The Consultative Committee for Space Data Systems (CCSDS) is an organization officially established by the management of its members. The Committee meets periodically to address data systems problems that are common to all participants, and to formulate sound technical solutions to these problems. Inasmuch as participation in the CCSDS is completely voluntary, the results of Committee actions are termed **Recommended Standards** and are not considered binding on any Agency.

This **Recommended Standard** is issued by, and represents the consensus of, the CCSDS members. Endorsement of this **Recommendation** is entirely voluntary. Endorsement, however, indicates the following understandings:

- o Whenever a member establishes a CCSDS-related **standard**, this **standard** will be in accord with the relevant **Recommended Standard**. Establishing such a **standard** does not preclude other provisions which a member may develop.

- o Whenever a member establishes a CCSDS-related **standard**, that member will provide other CCSDS members with the following information:

  -- The **standard** itself.

  -- The anticipated date of initial operational capability.

  -- The anticipated duration of operational service.

- o Specific service arrangements shall be made via memoranda of agreement. Neither this **Recommended Standard** nor any ensuing **standard** is a substitute for a memorandum of agreement.

No later than five years from its date of issuance, this **Recommended Standard** will be reviewed by the CCSDS to determine whether it should: (1) remain in effect without change; (2) be changed to reflect the impact of new technologies, new requirements, or new directions; or (3) be retired or canceled.

In those instances when a new version of a **Recommended Standard** is issued, existing CCSDS-related member standards and implementations are not negated or deemed to be non-CCSDS compatible. It is the responsibility of each member to determine when such standards or implementations are to be modified. Each member is, however, strongly encouraged to direct planning for its new standards and implementations towards the later version of the Recommended Standard.

FOREWORD

This document is a Recommended Standard for Orbit Data Messages (ODMs) and has been prepared by the Consultative Committee for Space Data Systems (CCSDS). The set of orbit data messages described in this Recommended Standard is the baseline concept for trajectory representation in data interchange applications that are cross-supported between Agencies of the CCSDS.

This Recommended Standard establishes a common framework and provides a common basis for the interchange of orbit data. It allows implementing organizations within each Agency to proceed coherently with the development of compatible derived standards for the flight and ground systems that are within their cognizance. Derived Agency standards may implement only a subset of the optional features allowed by the Recommended Standard and may incorporate features not addressed by this Recommended Standard.

Through the process of normal evolution, it is expected that expansion, deletion, or modification of this document may occur. This Recommended Standard is therefore subject to CCSDS document management and change control procedures, which are defined in the *Procedures Manual for the Consultative Committee for Space Data Systems*. Current versions of CCSDS documents are maintained at the CCSDS Web site:

http://www.ccsds.org/

Questions relating to the contents or status of this document should be addressed to the CCSDS Secretariat at the address indicated on page i.

At time of publication, the active Member and Observer Agencies of the CCSDS were:

Member Agencies

- Agenzia Spaziale Italiana (ASI)/Italy.
- British National Space Centre (BNSC)/United Kingdom.
- Canadian Space Agency (CSA)/Canada.
- Centre National d'Etudes Spatiales (CNES)/France.
- China National Space Administration (CNSA)/People's Republic of China.
- Deutsches Zentrum für Luft- und Raumfahrt e.V. (DLR)/Germany.
- European Space Agency (ESA)/Europe.
- Russian Federal Space Agency (RFSA)/Russian Federation.
- Instituto Nacional de Pesquisas Espaciais (INPE)/Brazil.
- Japan Aerospace Exploration Agency (JAXA)/Japan.
- National Aeronautics and Space Administration (NASA)/USA.

Observer Agencies

- Austrian Space Agency (ASA)/Austria.
- Belgian Federal Science Policy Office (BFSPO)/Belgium.
- Central Research Institute of Machine Building (TsNIIMash)/Russian Federation.
- Centro Tecnico Aeroespacial (CTA)/Brazil.
- Chinese Academy of Sciences (CAS)/China.
- Chinese Academy of Space Technology (CAST)/China.
- Commonwealth Scientific and Industrial Research Organization (CSIRO)/Australia.
- CSIR Satellite Applications Centre (CSIR)/Republic of South Africa.
- Danish National Space Center (DNSC)/Denmark.
- European Organization for the Exploitation of Meteorological Satellites (EUMETSAT)/Europe.
- European Telecommunications Satellite Organization (EUTELSAT)/Europe.
- Geo-Informatics and Space Technology Development Agency (GISTDA)/Thailand.
- Hellenic National Space Committee (HNSC)/Greece.
- Indian Space Research Organization (ISRO)/India.
- Institute of Space Research (IKI)/Russian Federation.
- KFKI Research Institute for Particle & Nuclear Physics (KFKI)/Hungary.
- Korea Aerospace Research Institute (KARI)/Korea.
- Ministry of Communications (MOC)/Israel.
- National Institute of Information and Communications Technology (NICT)/Japan.
- National Oceanic and Atmospheric Administration (NOAA)/USA.
- National Space Organization (NSPO)/Chinese Taipei.
- Naval Center for Space Technology (NCST)/USA.
- Scientific and Technological Research Council of Turkey (TUBITAK)/Turkey.
- Space and Upper Atmosphere Research Commission (SUPARCO)/Pakistan.
- Swedish Space Corporation (SSC)/Sweden.
- United States Geological Survey (USGS)/USA.

DOCUMENT CONTROL

Document	Title	Date	Status
CCSDS 502.0-B-1	Orbit Data Messages, Issue 1	September 2004	Original issue, superseded
CCSDS 502.0-B-2	Orbit Data Messages, Recommended Standard, Issue 2	November 2009	Current issue: – changes from the original issue are documented in annex E
EC 1	Editorial Change 1	April 2012	Corrects erroneous cross references and table of contents entries; corrects typographical anomaly in annex B; updates informative references [G1] and [G2] to current issues in annex G.
CCSDS 502.0-B-2 Cor. 1	Technical Corrigendum 1	May 2012	Corrects/clarifies text; updates references [1] and [4] to current issues in 1.7.

CONTENTS

CONTENTS (continued)

CONTENTS (continued)

1 INTRODUCTION

1.1 PURPOSE AND SCOPE

This Orbit Data Message (ODM) Recommended Standard specifies three standard message formats for use in transferring spacecraft orbit information between space agencies and commercial or governmental spacecraft operators: the Orbit Parameter Message (OPM), the Orbit Mean-Elements Message (OMM), and the Orbit Ephemeris Message (OEM). Such exchanges are used for:

a) pre-flight planning for tracking or navigation support;

b) scheduling tracking support;

c) carrying out tracking operations (sometimes called metric predicts);

d) performing orbit comparisons;

e) carrying out navigation operations such as orbit propagation and orbit reconstruction;

f) assessing mutual physical and electromagnetic interference among satellites orbiting the same celestial body (currently primarily Earth, Moon, and Mars);

g) performing orbit conjunction (collision avoidance) studies; and

h) developing and executing collaborative maneuvers to mitigate interference or enhance mutual operations.

This Recommended Standard includes sets of requirements and criteria that the message formats have been designed to meet. For exchanges where these requirements do not capture the needs of the participating agencies and satellite operators, another mechanism may be selected.

1.2 APPLICABILITY

The rationale behind the design of each orbit data message is described in annex C and may help the application engineer to select a suitable message. Definition of the orbit accuracy underlying a particular orbit message is outside of the scope of this Recommended Standard and should be specified via Interface Control Document (ICD) between data exchange participants (or specified via COMMENT sections in the message itself). Applicability information specific to each orbit data message format appears in sections 3, 4, and 5, as well as in C3.

This Recommended Standard is applicable only to the message format and content, but not to its transmission. The transmission of the message between agencies and operators is outside the scope of this document and should be specified in the ICD.

Description of the message formats based on the use of Extensible Markup Language (XML) is detailed in an integrated XML schema document for all Navigation Data Message Recommended Standards. (See reference [4].)

1.3 RATIONALE

This update to version 1 of the Orbit Data Messages adds a third message type based on collaboration of the CCSDS Navigation Working Group and the ISO Technical Committee 20, Subcommittee 14, Working Group 3 (ISO TC20/SC14/WG3). Additionally, added to the messages in the previous version are data structures that provide information regarding the uncertainty of the orbital states represented in the messages. Such information will increase the number of applications for which the messages are useful. A full list of the changes in this document is located in annex E.

1.4 DOCUMENT STRUCTURE

Section 2 provides a brief overview of the CCSDS-recommended Orbit Data Message types, the Orbit Parameter Message (OPM), Orbit Mean-Elements Message (OMM), and Orbit Ephemeris Message (OEM).

Section 3 provides details about the structure and content of the OPM.

Section 4 provides details about the structure and content of the OMM.

Section 5 provides details about the structure and content of the OEM.

Section 6 discusses the syntax considerations of the set of Orbit Data Messages (OPM, OMM, OEM).

Section 7 discusses security requirements for the Orbit Data Messages.

Annex A lists acceptable values for selected ODM keywords.

Annex B is a list of abbreviations and acronyms applicable to the ODM.

Annex C lists a set of requirements that were taken into consideration in the design of the OPM, OMM, and OEM, along with tables and discussion regarding the applicability of the three message types to various navigation tasks/functions.

Annex D lists a number of items that should be covered in ICDs prior to exchanging ODMs on a regular basis. There are several statements throughout the document that refer to the desirability or necessity of such a document; this annex lists all the suggested ICD items in a single place in the document. Also provided is a set of generic comment statements that may be added to one of the Orbit Data Messages to convey supplementary information for scenarios in which there is no ICD in place.

Annex E provides a summary of the changes introduced in this version 2 of the ODM and documents the differences between ODM version 1 and ODM version 2.

Annex F provides instructions for how to produce a version 2 OPM/OEM that is backwards compatible to version 1 implementations.

Annex G provides a listing of informative references.

1.5 DEFINITIONS

For the purposes of this document, the following definitions apply:

a) the word 'agencies' may also be construed as meaning 'satellite operators' or 'satellite service providers';

b) the word 'participant' denotes an entity that has the ability to acquire or broadcast navigation messages and/or radio frequencies, for example, a spacecraft, a tracking station, a tracking instrument, or an agency/operator;

c) the notation 'n/a' signifies 'not applicable';

d) depending on context, the term 'ODM' may be used to refer to this document, or may be used to refer collectively to the OPM, OMM and OEM messages.

1.6 NOMENCLATURE

The following conventions apply throughout this Recommended Standard:

a) the words 'shall' and 'must' imply a binding and verifiable specification;

b) the word 'should' implies an optional, but desirable, specification;

c) the word 'may' implies an optional specification;

d) the words 'is', 'are', and 'will' imply statements of fact.

1.7 REFERENCES

The following documents contain provisions which, through reference in this text, constitute provisions of this Recommended Standard. At the time of publication, the editions indicated were valid. All documents are subject to revision, and users of this Recommended Standard are encouraged to investigate the possibility of applying the most recent editions of the documents indicated below. The CCSDS Secretariat maintains a register of currently valid CCSDS Recommended Standards.

Cor. 1

[1] *Time Code Formats*. Recommendation for Space Data System Standards, CCSDS 301.0-B-4. Blue Book. Issue 4. Washington, D.C.: CCSDS, November 2010.

[2] *Spacewarn Bulletin*. Greenbelt, MD, USA: World Data Center for Satellite Information: WDC-SI. <http://nssdc.gsfc.nasa.gov/spacewarn>

[3] *Information Technology—8-Bit Single-Byte Coded Graphic Character Sets—Part 1: Latin Alphabet No. 1*. International Standard, ISO/IEC 8859-1:1998. Geneva: ISO, 1998.

[4] *XML Specification for Navigation Data Messages*. Recommendation for Space Data System Standards, CCSDS 505.0-B-1. Blue Book. Issue 1. Washington, D.C.: CCSDS, December 2010.

[5] "JPL Solar System Dynamics." Solar System Dynamics Group. <http://ssd.jpl.nasa.gov/>

[6] Paul V. Biron and Ashok Malhotra, eds. *XML Schema Part 2: Datatypes*. 2nd Edition. W3C Recommendation. N.p.: W3C, October 2004. <http://www.w3.org/TR/2001/REC-xmlschema-2-20010502/>

[7] *IEEE Standard for Binary Floating-Point Arithmetic*. IEEE Std 754-1985. New York: IEEE, 1985.

Cor. 1

2 OVERVIEW

2.1 ORBIT DATA MESSAGE TYPES

Three CCSDS-recommended Orbit Data Messages (ODMs) are described in this Recommended Standard: the Orbit Parameter Message (OPM), the Orbit Mean-Elements Message (OMM), and the Orbit Ephemeris Message (OEM).

The recommended orbit data messages are ASCII text format (reference [3]). This ODM document describes 'keyword = value notation' formatted messages, while reference [4] describes XML formatted messages (the ICD should specify which of these formats will be exchanged).

NOTE – As currently specified, an OPM, OMM, or OEM file is to represent orbit data for a single spacecraft. It is possible that the architecture may support multiple spacecraft per file; this could be considered in the future.

2.2 ORBIT PARAMETER MESSAGE (OPM)

An OPM specifies the position and velocity of a single object at a specified epoch. Optionally, osculating Keplerian elements may be provided. This message is suited to exchanges that (1) involve automated interaction and/or human interaction, and (2) do not require high-fidelity dynamic modeling.

The OPM requires the use of a propagation technique to determine the position and velocity at times different from the specified epoch, leading to a higher level of effort for software implementation than for the OEM. A 6x6 position/velocity covariance matrix that may be used in the propagation process is optional.

The OPM allows for modeling of any number of maneuvers (as both finite and instantaneous events) and simple modeling of solar radiation pressure and atmospheric drag.

The OPM also contains an optional covariance matrix which reflects the uncertainty of the orbit state.

Though primarily intended for use by computers, the attributes of the OPM also make it suitable for applications such as exchanges by email, FAX or voice, or applications where the message is to be frequently interpreted by humans.

2.3 ORBIT MEAN-ELEMENTS MESSAGE (OMM)

An OMM specifies the orbital characteristics of a single object at a specified epoch, expressed in mean Keplerian elements. This message is suited to exchanges that (1) involve automated interaction and/or human interaction, and (2) do not require high-fidelity dynamic modeling. Such exchanges may be inter-agency exchanges, or ad hoc exchanges among satellite operators when interface control documents have not been negotiated. Ad hoc interactions usually involve more than one satellite, each satellite controlled and operated by a different operating authority.

The OMM includes keywords and values that can be used to generate canonical NORAD Two Line Element Sets (TLEs) to accommodate the needs of heritage users (see reference [G4]).

The OMM also contains an optional covariance matrix which reflects the uncertainty of the mean Keplerian elements. This information may be used to determine contact parameters that encompass uncertainties in predicted future states of orbiting objects of interest.

This message is suited for directing antennas and planning contacts with satellites. It is not recommended for assessing mutual physical or electromagnetic interference among Earth-orbiting spacecraft, developing collaborative maneuvers, or propagating precisely the orbits of active satellites, inactive man made objects, and near-Earth debris fragments. It is not suitable for numerical integration of the governing equations.

Though primarily intended for use by computers, the attributes of the OMM also make it suitable for applications such as exchanges by email, FAX or voice, or applications where the message is to be frequently interpreted by humans.

2.4 ORBIT EPHEMERIS MESSAGE (OEM)

An OEM specifies the position and velocity of a single object at multiple epochs contained within a specified time range. The OEM is suited to exchanges that (1) involve automated interaction (e.g., computer-to-computer communication where frequent, fast automated time interpretation and processing is required), and (2) require higher fidelity or higher precision dynamic modeling than is possible with the OPM.

The OEM allows for dynamic modeling of any number of gravitational and non-gravitational accelerations. The OEM requires the use of an interpolation technique to interpret the position and velocity at times different from the tabular epochs.

The OEM also contains an optional covariance matrix which reflects the uncertainty of the orbit solution used to generate states in the ephemeris.

2.5 EXCHANGE OF MULTIPLE MESSAGES

For a given object, multiple OPM, OMM, or OEM messages may be provided in a message exchange session to achieve ephemeris fidelity requirements. If ephemeris information for multiple objects is to be exchanged, then multiple OPM, OMM, or OEM files must be used.

2.6 DEFINITIONS

Definitions of time systems, reference frames, planetary models, maneuvers and other fundamental topics related to the interpretation and processing of state vectors and spacecraft ephemerides are provided in reference [G1].

3 ORBIT PARAMETER MESSAGE (OPM)

3.1 GENERAL

3.1.1 Orbit information may be exchanged between two participants by sending a state vector (see reference [G1]) for a specified epoch using an Orbit Parameter Message (OPM). The message recipient must have an orbit propagator available that is able to propagate the OPM state vector to compute the orbit at other desired epochs. For this propagation, additional ancillary information (spacecraft properties such as mass, area, and maneuver planning data, if applicable) may be included with the message.

3.1.2 Osculating Keplerian elements and Gravitational Coefficient may be included in the OPM in addition to the Cartesian state to aid the message recipient in performing consistency checks. If any Keplerian element is included, the entire set of elements must be provided.

3.1.3 If participants wish to exchange mean element information, then the Orbit Mean-Elements Message (OMM) should be the selected message type. (See section 4.)

3.1.4 The use of the OPM is best applicable under the following conditions:

a) an orbit propagator consistent with the models used to develop the orbit data should be available at the receiver's site;

b) the receiver's modeling of gravitational forces, solar radiation pressure, atmospheric drag, and thrust phases (see reference [G1]) should fulfill accuracy requirements established between the exchange partners.

3.1.5 The OPM shall be a plain text file consisting of orbit data for a single object. It shall be easily readable by both humans and computers.

3.1.6 The OPM file-naming scheme should be agreed to on a case-by-case basis between the exchange partners, and should be documented in an ICD. The method of exchanging OPMs should be decided on a case-by-case basis by the exchange partners and documented in an ICD.

NOTE – Detailed syntax rules for the OPM are specified in section 6.

3.2 OPM CONTENT/STRUCTURE

3.2.1 GENERAL

The OPM shall be represented as a combination of the following:

a) a header;

b) metadata (data about data);

c) data; and

d) optional comments (explanatory information).

3.2.2 OPM HEADER

3.2.2.1 Table 3-1 specifies for each header item:

a) the keyword to be used;

b) a short description of the item;

c) examples of allowed values; and

d) whether the item is obligatory or optional.

3.2.2.2 Only those keywords shown in table 3-1 shall be used in an OPM header.

Table 3-1: OPM Header

Keyword	Description	Examples of Values	Obligatory
`CCSDS_OPM_VERS`	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes.	`2.0`	Yes
`COMMENT`	Comments (allowed in the OPM Header only immediately after the OPM version number). (See 6.7 for formatting rules.)	`COMMENT This is a comment`	No
`CREATION_DATE`	File creation date/time in UTC. (For format specification, see 6.5.9.)	`2001-11-06T11:17:33` `2002-204T15:56:23Z`	Yes
`ORIGINATOR`	Creating agency or operator (value should be specified in an ICD). The country of origin should also be provided where the originator is not a national space agency.	`CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT/USA, USAF, INMARSAT/UK`	Yes

3.2.3 OPM METADATA

3.2.3.1 Table 3-2 specifies for each metadata item:

a) the keyword to be used;

b) a short description of the item;

c) examples of allowed values; and

d) whether the item is obligatory or optional.

3.2.3.2 Only those keywords shown in table 3-2 shall be used in OPM metadata.

NOTE – For some keywords (OBJECT_NAME, OBJECT_ID, CENTER_NAME) there are no definitive lists of authorized values maintained by a control authority; the references listed in 1.7 are the best known sources for authorized values to date. For the TIME_SYSTEM and REF_FRAME keywords, the approved values are listed in annex A.

Cor. 1

Table 3-2: OPM Metadata

Keyword	Description	Examples of Values	Obligatory
COMMENT	Comments (allowed at the beginning of the OPM Metadata). (See 6.7 for formatting rules.)	COMMENT This is a comment	No
OBJECT_NAME	Spacecraft name for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended to use names from the SPACEWARN Bulletin (reference [2]), which include Object name and international designator of the participant.	EUTELSAT W1 MARS PATHFINDER STS 106 NEAR	Yes
OBJECT_ID	Object identifier of the object for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended that values be the international spacecraft designator as published in the SPACEWARN Bulletin (reference [2]). Recommended values have the format YYYY-NNNP{PP}, where: YYYY = Year of launch. NNN = Three digit serial number of launch in year YYYY (with leading zeros). P{PP} = At least one capital letter for the identification of the part brought into space by the launch. In cases where the asset is not listed in the bulletin, or the SPACEWARN format is not used, the value should be provided in an ICD.	2000-052A 1996-068A 2000-053A 1996-008A	Yes
CENTER_NAME	Origin of reference frame, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, or another spacecraft (in this case the value for 'CENTER_NAME' is subject to the same rules as for 'OBJECT_NAME'). There is no CCSDS-based restriction on the value for this keyword, but for natural bodies it is recommended to use names from the NASA/JPL Solar System Dynamics Group at http://ssd.jpl.nasa.gov (reference [5]).	EARTH EARTH BARYCENTER MOON SOLAR SYSTEM BARYCENTER SUN JUPITER BARYCENTER STS 106 EROS	Yes
REF_FRAME	Name of the reference frame in which the state vector and optional Keplerian element data are given. Use of values other than those in annex A must be documented in an ICD. The reference frame must be the same for all data elements, with the exception of the maneuvers and covariance matrix, for which applicable different reference frames may be specified.	ICRF ITRF-93 ITRF-97 ITRF2000 ITRFxxxx (Template for a future version) TOD (True Equator/Equinox of Date) EME2000 (Earth Mean Equator and Equinox of J2000) TDR (true of date rotating) GRC (Greenwich rotating coordinate frame)	Yes
REF_FRAME_EPOCH	Epoch of reference frame, if not intrinsic to the definition of the reference frame. (See 6.5.9 for formatting rules.)	2001-11-06T11:17:33 2002-204T15:56:23Z	No
TIME_SYSTEM	Time system used for state vector, maneuver, and covariance data (also see table 3-3). Use of values other than those in annex A must be documented in an ICD.	UTC, TAI, TT, GPS, TDB, TCB	Yes

3.2.4 OPM DATA

3.2.4.1 Table 3-3 provides an overview of the six logical blocks in the OPM Data section (State Vector, Osculating Keplerian Elements, Spacecraft Parameters, Position/Velocity Covariance Matrix, Maneuver Parameters, and User Defined Parameters), and specifies for each data item:

a) the keyword to be used;

b) a short description of the item;

c) the units to be used;

d) whether the item is obligatory or optional.

3.2.4.2 Only those keywords shown in table 3-3 shall be used in OPM data.

NOTE – Requirements relating to the keywords in table 3-3 appear after the table.

Table 3-3: OPM Data

Keyword	Description	Units	Obligatory
State Vector Components in the Specified Coordinate System			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
EPOCH	Epoch of state vector & optional Keplerian elements. (See 6.5.9 for formatting rules.)	n/a	Yes
X	Position vector X-component	km	Yes
Y	Position vector Y-component	km	Yes
Z	Position vector Z-component	km	Yes
X_DOT	Velocity vector X-component	km/s	Yes
Y_DOT	Velocity vector Y-component	km/s	Yes
Z_DOT	Velocity vector Z-component	km/s	Yes
Osculating Keplerian Elements in the Specified Reference Frame (none or all parameters of this block must be given.)			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
SEMI_MAJOR_AXIS	Semi-major axis	km	No
ECCENTRICITY	Eccentricity	n/a	No
INCLINATION	Inclination	deg	No
RA_OF_ASC_NODE	Right ascension of ascending node	deg	No
ARG_OF_PERICENTER	Argument of pericenter	deg	No
TRUE_ANOMALY or MEAN_ANOMALY	True anomaly or mean anomaly	deg	No
GM	Gravitational Coefficient (Gravitational Constant x Central Mass)	km**3/s**2	No
Spacecraft Parameters			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
MASS	S/C Mass	kg	No
SOLAR_RAD_AREA	Solar Radiation Pressure Area (A_R)	m**2	No
SOLAR_RAD_COEFF	Solar Radiation Pressure Coefficient (C_R)	n/a	No
DRAG_AREA	Drag Area (A_D)	m**2	No
DRAG_COEFF	Drag Coefficient (C_D)	n/a	No

Keyword	Description	Units	Obligatory
Position/Velocity Covariance Matrix (6x6 Lower Triangular Form. None or all parameters of the matrix must be given. COV_REF_FRAME may be omitted if it is the same as the metadata REF_FRAME.)			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
COV_REF_FRAME	Coordinate system for covariance matrix (value must be selected from annex A)	n/a	No
CX_X	Covariance matrix [1,1]	km**2	No
CY_X	Covariance matrix [2,1]	km**2	No
CY_Y	Covariance matrix [2,2]	km**2	No
CZ_X	Covariance matrix [3,1]	km**2	No
CZ_Y	Covariance matrix [3,2]	km**2	No
CZ_Z	Covariance matrix [3,3]	km**2	No
CX_DOT_X	Covariance matrix [4,1]	km**2/s	No
CX_DOT_Y	Covariance matrix [4,2]	km**2/s	No
CX_DOT_Z	Covariance matrix [4,3]	km**2/s	No
CX_DOT_X_DOT	Covariance matrix [4,4]	km**2/s**2	No
CY_DOT_X	Covariance matrix [5,1]	km**2/s	No
CY_DOT_Y	Covariance matrix [5,2]	km**2/s	No
CY_DOT_Z	Covariance matrix [5,3]	km**2/s	No
CY_DOT_X_DOT	Covariance matrix [5,4]	km**2/s**2	No
CY_DOT_Y_DOT	Covariance matrix [5,5]	km**2/s**2	No
CZ_DOT_X	Covariance matrix [6,1]	km**2/s	No
CZ_DOT_Y	Covariance matrix [6,2]	km**2/s	No
CZ_DOT_Z	Covariance matrix [6,3]	km**2/s	No
CZ_DOT_X_DOT	Covariance matrix [6,4]	km**2/s**2	No
CZ_DOT_Y_DOT	Covariance matrix [6,5]	km**2/s**2	No
CZ_DOT_Z_DOT	Covariance matrix [6,6]	km**2/s**2	No
Maneuver Parameters (Repeat for each maneuver. None or all parameters of this block must be given.)			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
MAN_EPOCH_IGNITION	Epoch of ignition. (See 6.5.9 for formatting rules.)	n/a	No
MAN_DURATION	Maneuver duration (If = 0, impulsive maneuver)	s	No
MAN_DELTA_MASS	Mass change during maneuver (value is < 0)	kg	No
MAN_REF_FRAME	Coordinate system for velocity increment vector (value must be selected from annex A)	n/a	No
MAN_DV_1	1st component of the velocity increment	km/s	No
MAN_DV_2	2nd component of the velocity increment	km/s	No
MAN_DV_3	3rd component of the velocity increment	km/s	No
User Defined Parameters (all parameters in this section must be described in an ICD).			
USER_DEFINED_x	User defined parameter, where 'x' is replaced by a variable length user specified character string. Any number of user defined parameters may be included, if necessary to provide essential information that cannot be conveyed in COMMENT statements. Example: USER_DEFINED_EARTH_MODEL = WGS-84	n/a	No

3.2.4.3 All values except Maneuver Parameters in the OPM data are ‘at epoch’, i.e., the value of the parameter at the time specified in the EPOCH keyword.

3.2.4.4 Table 3-3 is broken into six logical blocks, each of which has a descriptive heading. These descriptive headings shall not be included in an OPM, unless they appear in a properly formatted COMMENT statement.

3.2.4.5 If the solar radiation coefficient, C_R, is set to zero, no solar radiation pressure shall be taken into account.

3.2.4.6 If the atmospheric drag coefficient, C_D, is set to zero, no atmospheric drag shall be taken into account.

3.2.4.7 Parameters for thrust phases may be optionally given for the computation of the trajectory during or after maneuver execution (see reference [G1] for the simplified modeling of such maneuvers). For impulsive maneuvers, MAN_DURATION must be set to zero. MAN_DELTA_MASS may be used for both finite and impulsive maneuvers; the value must be a negative number. Permissible reference frames for the velocity increment vector shall be those specified in annex A.

3.2.4.8 Multiple sets of maneuver parameters may appear. For each maneuver, all the maneuver parameters shall be repeated in the order shown in table 3-3.

3.2.4.9 If the OPM contains a maneuver definition, the Spacecraft Parameters section must be included.

3.2.4.10 Values in the covariance matrix shall be expressed in the applicable reference frame (COV_REF_FRAME keyword if used, or REF_FRAME keyword if not), and shall be presented sequentially from upper left [1,1] to lower right [6,6], lower triangular form, row by row left to right. Variance and covariance values shall be expressed in standard double precision as related in 6.5. This logical block of the OPM may be useful for risk assessment and establishing maneuver and mission margins. The intent is to provide causal connections between output orbit data and both physical hypotheses and measurement uncertainties. These causal relationships guide operators’ corrective actions and mitigations.

3.2.4.11 A section of User Defined Parameters is allowed. In principle, this provides flexibility, but also introduces complexity, non-standardization, potential ambiguity, and potential processing errors. Accordingly, if used, the keywords and their meanings must be described in an ICD. User Defined Parameters, if included in an OPM, should be used as sparingly as possible; their use is not encouraged.

3.3 OPM EXAMPLES

Figure 3-1 through figure 3-4 are examples of Orbit Parameter Messages. The first has only a state; the second has state, Keplerian elements, and maneuvers; the third and fourth include the position/velocity covariance matrix.

Figure 3-1 and figure 3-2 are compatible with the ODM version 1.0 processing because they do not contain any of the unique features of the ODM version 2.0. Thus for these examples a value of 1.0 could be specified for the 'CCSDS_OPM_VERS' keyword. (See annex F.)

Figure 3-3 and figure 3-4 include unique features of ODM version 2.0, and thus 'CCSDS_OPM_VERS = 2.0' must be specified.

```
CCSDS_OPM_VERS = 2.0
CREATION_DATE  = 1998-11-06T09:23:57
ORIGINATOR     = JAXA

COMMENT          GEOCENTRIC, CARTESIAN, EARTH FIXED
OBJECT_NAME    = GODZILLA 5
OBJECT_ID      = 1998-057A
CENTER_NAME    = EARTH
REF_FRAME      = ITRF-97
TIME_SYSTEM    = UTC

EPOCH =          1998-12-18T14:28:15.1172
X =              6503.514000
Y =              1239.647000
Z =              -717.490000
X_DOT =            -0.873160
Y_DOT =             8.740420
Z_DOT =            -4.191076
MASS =           3000.000000
SOLAR_RAD_AREA =   18.770000
SOLAR_RAD_COEFF =   1.000000
DRAG_AREA =        18.770000
DRAG_COEFF =        2.500000
```

Figure 3-1: Simple OPM File Example

```
CCSDS_OPM_VERS    =  2.0

COMMENT  Generated by GSOC, R. Kiehling
COMMENT  Current intermediate orbit IO2 and maneuver planning data

CREATION_DATE     =  2000-06-03T05:33:00.000
ORIGINATOR        =  GSOC

OBJECT_NAME       =  EUTELSAT W4
OBJECT_ID         =  2000-028A
CENTER_NAME       =  EARTH
REF_FRAME         =  TOD
TIME_SYSTEM       =  UTC

COMMENT  State Vector
EPOCH             =  2006-06-03T00:00:00.000
X                 =    6655.9942        [km]
Y                 =  -40218.5751        [km]
Z                 =     -82.9177        [km]
X_DOT             =       3.11548208    [km/s]
Y_DOT             =       0.47042605    [km/s]
Z_DOT             =      -0.00101495    [km/s]

COMMENT  Keplerian elements
SEMI_MAJOR_AXIS   =   41399.5123        [km]
ECCENTRICITY      =       0.020842611
INCLINATION       =       0.117746      [deg]
RA_OF_ASC_NODE    =      17.604721      [deg]
ARG_OF_PERICENTER =     218.242943      [deg]
TRUE_ANOMALY      =      41.922339      [deg]
GM                =  398600.4415        [km**3/s**2]

COMMENT  Spacecraft parameters
MASS              =    1913.000         [kg]
SOLAR_RAD_AREA    =      10.000         [m**2]
SOLAR_RAD_COEFF   =       1.300
DRAG_AREA         =      10.000         [m**2]
DRAG_COEFF        =       2.300

COMMENT  2 planned maneuvers

COMMENT  First maneuver: AMF-3
COMMENT  Non-impulsive, thrust direction fixed in inertial frame
MAN_EPOCH_IGNITION =      2000-06-03T09:00:34.1
MAN_DURATION      =     132.60          [s]
MAN_DELTA_MASS    =     -18.418         [kg]
MAN_REF_FRAME     =       EME2000
MAN_DV_1          =      -0.02325700    [km/s]
MAN_DV_2          =       0.01683160    [km/s]
MAN_DV_3          =      -0.00893444    [km/s]

COMMENT  Second maneuver: first station acquisition maneuver
COMMENT  impulsive, thrust direction fixed in RTN frame
MAN_EPOCH_IGNITION =      2000-06-05T18:59:21.0
MAN_DURATION      =       0.00          [s]
MAN_DELTA_MASS    =      -1.469         [kg]
MAN_REF_FRAME     =       RTN
MAN_DV_1          =       0.00101500    [km/s]
MAN_DV_2          =      -0.00187300    [km/s]
MAN_DV_3          =       0.00000000    [km/s]
```

Figure 3-2: OPM File Example with Optional Keplerian Elements and Two Maneuvers

```
CCSDS_OPM_VERS = 2.0

CREATION_DATE  = 1998-11-06T09:23:57
ORIGINATOR     = JAXA

COMMENT          GEOCENTRIC, CARTESIAN, EARTH FIXED
OBJECT_NAME    = GODZILLA 5
OBJECT_ID      = 1998-057A
CENTER_NAME    = EARTH
REF_FRAME      = ITRF-97
TIME_SYSTEM    = UTC

EPOCH =          1998-12-18T14:28:15.1172
X =              6503.514000
Y =              1239.647000
Z =              -717.490000
X_DOT =            -0.873160
Y_DOT =             8.740420
Z_DOT =            -4.191076

MASS =           3000.000000
SOLAR_RAD_AREA =   18.770000
SOLAR_RAD_COEFF =   1.000000
DRAG_AREA =        18.770000
DRAG_COEFF =        2.500000

CX_X =  3.331349476038534e-04
CY_X =  4.618927349220216e-04
CY_Y =  6.782421679971363e-04
CZ_X =  -3.070007847730449e-04
CZ_Y =  -4.221234189514228e-04
CZ_Z =  3.231931992380369e-04
CX_DOT_X =  -3.349365033922630e-07
CX_DOT_Y =  -4.686084221046758e-07
CX_DOT_Z =  2.484949578400095e-07
CX_DOT_X_DOT =  4.296022805587290e-10
CY_DOT_X =  -2.211832501084875e-07
CY_DOT_Y =  -2.864186892102733e-07
CY_DOT_Z =  1.798098699846038e-07
CY_DOT_X_DOT =  2.608899201686016e-10
CY_DOT_Y_DOT =  1.767514756338532e-10
CZ_DOT_X =  -3.041346050686871e-07
CZ_DOT_Y =  -4.989496988610662e-07
CZ_DOT_Z =  3.540310904497689e-07
CZ_DOT_X_DOT =  1.869263192954590e-10
CZ_DOT_Y_DOT =  1.008862586240695e-10
CZ_DOT_Z_DOT =  6.224444338635500e-10
```

Figure 3-3: OPM File Example with Covariance Matrix

```
CCSDS_OPM_VERS    =  2.0
COMMENT  Generated by GSOC, R. Kiehling
COMMENT  Current intermediate orbit IO2 and maneuver planning data
CREATION_DATE     =  2000-06-03T05:33:00.000
ORIGINATOR        =  GSOC
OBJECT_NAME       =  EUTELSAT W4
OBJECT_ID         =  2000-028A
CENTER_NAME       =  EARTH
REF_FRAME         =  TOD
TIME_SYSTEM       =  UTC
COMMENT  State Vector
EPOCH             =  2006-06-03T00:00:00.000
X                 =    6655.9942        [km]
Y                 =  -40218.5751        [km]
Z                 =     -82.9177        [km]
X_DOT             =       3.11548208    [km/s]
Y_DOT             =       0.47042605    [km/s]
Z_DOT             =      -0.00101495    [km/s]
COMMENT  Keplerian elements
SEMI_MAJOR_AXIS   =   41399.5123        [km]
ECCENTRICITY      =       0.020842611
INCLINATION       =       0.117746      [deg]
RA_OF_ASC_NODE    =      17.604721      [deg]
ARG_OF_PERICENTER =     218.242943      [deg]
TRUE_ANOMALY      =      41.922339      [deg]
GM                =  398600.4415        [km**3/s**2]
COMMENT  Spacecraft parameters
MASS              =    1913.000         [kg]
SOLAR_RAD_AREA    =      10.000         [m**2]
SOLAR_RAD_COEFF   =       1.300
DRAG_AREA         =      10.000         [m**2]
DRAG_COEFF        =       2.300
COV_REF_FRAME = RTN
CX_X =  3.331349476038534e-04
CY_X =  4.618927349220216e-04
CY_Y =  6.782421679971363e-04
CZ_X =  -3.070007847730449e-04
CZ_Y =  -4.221234189514228e-04
CZ_Z =  3.231931992380369e-04
CX_DOT_X =  -3.349365033922630e-07
CX_DOT_Y =  -4.686084221046758e-07
CX_DOT_Z =  2.484949578400095e-07
CX_DOT_X_DOT =  4.296022805587290e-10
CY_DOT_X =  -2.211832501084875e-07
CY_DOT_Y =  -2.864186892102733e-07
CY_DOT_Z =  1.798098699846038e-07
CY_DOT_X_DOT =  2.608899201686016e-10
CY_DOT_Y_DOT =  1.767514756338532e-10
CZ_DOT_X =  -3.041346050686871e-07
CZ_DOT_Y =  -4.989496988610662e-07
CZ_DOT_Z =  3.540310904497689e-07
CZ_DOT_X_DOT =  1.869263192954590e-10
CZ_DOT_Y_DOT =  1.008862586240695e-10
CZ_DOT_Z_DOT =  6.224444338635500e-10
USER_DEFINED_EARTH_MODEL = WGS-84
```

Figure 3-4: OPM File Example with Optional Keplerian Elements, Covariance Matrix, and a User Defined Parameter

4 ORBIT MEAN-ELEMENTS MESSAGE (OMM)

4.1 GENERAL

4.1.1 Orbit information may be exchanged between two participants by sending an orbital state based on mean Keplerian elements (see reference [G1]) for a specified epoch using an Orbit Mean-Elements Message (OMM). The message recipient must use appropriate orbit propagator algorithms in order to correctly propagate the OMM state to compute the orbit at other desired epochs.

4.1.2 The OMM is intended to allow replication of the data content of an existing TLE in a CCSDS standard format, but the message can also accommodate other implementations of mean elements. All essential fields of the 'de facto standard' TLE are included in the OMM in a style that is consistent with that of the other ODMs (i.e., the OPM and OEM). From the fields in the OMM, it is possible to generate a TLE (see reference [G3]). Programs that convert OMMs to TLEs must be aware of the structural requirements of the TLE, including the checksum algorithm and the formatting requirements for the values in the TLE. The checksum and formatting requirements of the TLE do not apply to the values in an OMM.

4.1.3 If participants wish to exchange osculating element information, then the Orbit Parameter Message (OPM) should be the selected message type. (See section 3.)

4.1.4 The use of the OMM is best applicable under the following conditions:

a) an orbit propagator consistent with the models used to develop the orbit data should be run at the receiver's site;

b) the receiver's modeling of gravitational forces, solar radiation pressure, atmospheric drag, etc. (see reference [G1]), should fulfill accuracy requirements established between the exchange partners.

4.1.5 The OMM shall be a plain text file consisting of orbit data for a single object. It shall be easily readable by both humans and computers.

4.1.6 The OMM file-naming scheme should be agreed to on a case-by-case basis between the exchange partners, and should be documented in an ICD. The method of exchanging OMMs should be decided on a case-by-case basis by the exchange partners and documented in an ICD.

NOTE – Detailed syntax rules for the OMM are specified in section 6.

4.2 OMM CONTENT/STRUCTURE

4.2.1 GENERAL

The OMM shall be represented as a combination of the following:

a) a header;

b) metadata (data about data);

c) data; and

d) optional comments (explanatory information).

4.2.2 OMM HEADER

4.2.2.1 Table 4-1 specifies for each header item:

a) the keyword to be used;

b) a short description of the item;

c) examples of allowed values; and

d) whether the item is obligatory or optional.

4.2.2.2 Only those keywords shown in table 4-1 shall be used in an OMM header.

Table 4-1: OMM Header

Keyword	Description	Examples of Values	Obligatory
`CCSDS_OMM_VERS`	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes.	`2.0`	Yes
`COMMENT`	Comments (allowed in the OMM Header only immediately after the OMM version number). (See 6.7 for formatting rules.)	`COMMENT This is a comment`	No
`CREATION_DATE`	File creation date/time in UTC. (For format specification, see 6.5.9.)	`2001-11-06T11:17:33` `2002-204T15:56:23Z`	Yes
`ORIGINATOR`	Creating agency or operator (value should be specified in an ICD). The country of origin should also be provided where the originator is not a national space agency.	`CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT/USA, USAF, INMARSAT/UK`	Yes

4.2.3 OMM METADATA

4.2.3.1 Table 4-2 specifies for each metadata item:

a) the keyword to be used;

b) a short description of the item;

c) examples of allowed values; and

d) whether the item is obligatory or optional.

4.2.3.2 Only those keywords shown in table 4-2 shall be used in OMM metadata.

NOTE – For some keywords (OBJECT_NAME, OBJECT_ID, CENTER_NAME) there are no definitive lists of authorized values maintained by a control authority; the references listed in 1.7 are the best known sources for authorized values to date. For the TIME_SYSTEM and REF_FRAME keywords, the approved values are shown in annex A.

Table 4-2: OMM Metadata

Keyword	Description	Examples of Values	Obligatory
COMMENT	Comments (allowed at the beginning of the OMM Metadata). (See 6.7 for formatting rules.)	COMMENT This is a comment	No
OBJECT_NAME	Spacecraft name for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended to use names from the SPACEWARN Bulletin (reference [2]), which include Object name and international designator of the participant.	TELCOM 2 SPACEWAY 2 INMARSAT 4-F2	Yes
OBJECT_ID	Object identifier of the object for which the orbit state is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended that values be the international spacecraft designator as published in the SPACEWARN Bulletin (reference [2]). Recommended values have the format YYYY-NNNP{PP}, where: YYYY = Year of launch. NNN = Three digit serial number of launch in year YYYY (with leading zeros). P{PP} = At least one capital letter for the identification of the part brought into space by the launch. In cases where the asset is not listed in the bulletin, or the SPACEWARN format is not used, the value should be provided in an ICD.	2005-046B 2005-046A 2003-022A 2005-044A	Yes
CENTER_NAME	Origin of reference frame. There is no CCSDS-based restriction on the value for this keyword, but for natural bodies it is recommended to use names from the NASA/JPL Solar System Dynamics Group at http://ssd.jpl.nasa.gov (reference [5]).	EARTH MARS MOON	Yes
REF_FRAME	Name of the reference frame in which the Keplerian element data are given. Use of values other than those in annex A must be documented in an ICD. The reference frame must be the same for all data elements, with the exception of the covariance matrix, for which an applicable different reference frame may be specified.	TEME EME2000	Yes
REF_FRAME_EPOCH	Epoch of reference frame, if not intrinsic to the definition of the reference frame. (See 6.5.9 for formatting rules.)	2001-11-06T11:17:33 2002-204T15:56:23Z	No
TIME_SYSTEM	Time system used for the orbit state and covariance matrix. Use of values other than those in annex A must be documented in an ICD.	UTC	Yes
MEAN_ELEMENT_THEORY	Description of the Mean Element Theory. Indicates the proper method to employ to propagate the state.	SGP4 DSST USM	Yes

4.2.4 OMM DATA

4.2.4.1 Table 4-3 provides an overview of the five logical blocks in the OMM Data section (Mean Keplerian Elements, Spacecraft Parameters, TLE Related Parameters, Position/Velocity Covariance Matrix, and User Defined Parameters), and specifies for each data item:

a) the keyword to be used;

b) a short description of the item;

c) the units to be used;

d) whether the item is obligatory or optional.

4.2.4.2 Only those keywords shown in table 4-3 shall be used in OMM data.

NOTE – Requirements relating to the keywords in table 4-3 appear after the table.

Table 4-3: OMM Data

Keyword	Description	Units	Obligatory
Mean Keplerian Elements in the Specified Reference Frame			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
EPOCH	Epoch of Mean Keplerian elements. (See 6.5.9 for formatting rules.)	n/a	Yes
SEMI_MAJOR_AXIS or MEAN_MOTION	Semi-major axis in kilometers (preferred), or, if MEAN_ELEMENT_THEORY = SGP/SGP4, the Keplerian Mean motion in revolutions per day	km rev/day	Yes
ECCENTRICITY	Eccentricity	n/a	Yes
INCLINATION	Inclination	deg	Yes
RA_OF_ASC_NODE	Right ascension of ascending node	deg	Yes
ARG_OF_PERICENTER	Argument of pericenter	deg	Yes
MEAN_ANOMALY	Mean anomaly	deg	Yes
GM	Gravitational Coefficient (Gravitational Constant x Central Mass)	km**3/s**2	No
Spacecraft Parameters			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
MASS	S/C Mass	kg	No
SOLAR_RAD_AREA	Solar Radiation Pressure Area (A_R)	m**2	No
SOLAR_RAD_COEFF	Solar Radiation Pressure Coefficient (C_R)	n/a	No
DRAG_AREA	Drag Area (A_D)	m**2	No
DRAG_COEFF	Drag Coefficient (C_D)	n/a	No
TLE Related Parameters (This section is only required if MEAN_ELEMENT_THEORY=SGP/SGP4)			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
EPHEMERIS_TYPE	Default value = 0. (See 4.2.4.7.)	n/a	No
CLASSIFICATION_TYPE	Default value = U. (See 4.2.4.7.)	n/a	No

Keyword	Description	Units	Obligatory
NORAD_CAT_ID	NORAD Catalog Number ('Satellite Number') an integer of up to nine digits. This keyword is only required if MEAN_ELEMENT_THEORY=SGP/SGP4.	n/a	No
ELEMENT_SET_NO	Element set number for this satellite. Normally incremented sequentially, but may be out of sync if it is generated from a backup source. Used to distinguish different TLEs, and therefore only meaningful if TLE-based data is being exchanged (i.e., MEAN_ELEMENT_THEORY = SGP/SGP4).	n/a	No
REV_AT_EPOCH	Revolution Number	n/a	No
BSTAR	SGP/SGP4 drag-like coefficient (in units 1/[Earth radii]). Only required if MEAN_ELEMENT_THEORY=SGP/SGP4	1/ER	No
MEAN_MOTION_DOT	First Time Derivative of the Mean Motion (only required if MEAN_ELEMENT_THEORY = SGP)	rev/day**2	No
MEAN_MOTION_DDOT	Second Time Derivative of Mean Motion (only required if MEAN_ELEMENT_THEORY = SGP)	rev/day**3	No
Position/Velocity Covariance Matrix (6x6 Lower Triangular Form. None or all parameters of the matrix must be given. COV_REF_FRAME may be omitted if it is the same as the metadata REF_FRAME.)			
COMMENT	(See 6.7 for formatting rules.)	n/a	No
COV_REF_FRAME	Reference frame for the covariance matrix. The value must be selected from annex A.	n/a	No
CX_X	Covariance matrix [1,1]	km**2	No
CY_X	Covariance matrix [2,1]	km**2	No
CY_Y	Covariance matrix [2,2]	km**2	No
CZ_X	Covariance matrix [3,1]	km**2	No
CZ_Y	Covariance matrix [3,2]	km**2	No
CZ_Z	Covariance matrix [3,3]	km**2	No
CX_DOT_X	Covariance matrix [4,1]	km**2/s	No
CX_DOT_Y	Covariance matrix [4,2]	km**2/s	No
CX_DOT_Z	Covariance matrix [4,3]	km**2/s	No
CX_DOT_X_DOT	Covariance matrix [4,4]	km**2/s**2	No
CY_DOT_X	Covariance matrix [5,1]	km**2/s	No
CY_DOT_Y	Covariance matrix [5,2]	km**2/s	No
CY_DOT_Z	Covariance matrix [5,3]	km**2/s	No
CY_DOT_X_DOT	Covariance matrix [5,4]	km**2/s**2	No
CY_DOT_Y_DOT	Covariance matrix [5,5]	km**2/s**2	No
CZ_DOT_X	Covariance matrix [6,1]	km**2/s	No
CZ_DOT_Y	Covariance matrix [6,2]	km**2/s	No
CZ_DOT_Z	Covariance matrix [6,3]	km**2/s	No
CZ_DOT_X_DOT	Covariance matrix [6,4]	km**2/s**2	No
CZ_DOT_Y_DOT	Covariance matrix [6,5]	km**2/s**2	No
CZ_DOT_Z_DOT	Covariance matrix [6,6]	km**2/s**2	No
User Defined Parameters (all parameters in this section must be described in an ICD).			
USER_DEFINED_x	User defined parameter, where 'x' is replaced by a variable length user specified character string. Any number of user defined parameters may be included, if necessary to provide essential information that cannot be conveyed in COMMENT statements. Example: USER_DEFINED_EARTH_MODEL = WGS-84	n/a	No

Cor. 1

Cor. 1

Cor. 1

4.2.4.3 All values in the OMM are ‘at epoch’, i.e., the value of the parameter at the time specified in the EPOCH keyword.

4.2.4.4 Table 4-3 is broken into five logical blocks, each of which has a descriptive heading. These descriptive headings shall not be included in an OMM, unless they appear in a properly formatted COMMENT statement.

4.2.4.5 Values in the covariance matrix shall be expressed in the applicable reference frame (COV_REF_FRAME keyword if used, or REF_FRAME keyword if not), and shall be presented sequentially from upper left [1,1] to lower right [6,6], lower triangular form, row by row left to right. Variance and covariance values shall be expressed in standard double precision as related in 6.4. This logical block of the OMM may be useful for risk assessment and establishing maneuver and mission margins.

4.2.4.6 For operations in Earth orbit with a TLE-based OMM, some special conventions must be observed, as follows:

– The value associated with the CENTER_NAME keyword shall be ‘EARTH’.

Cor. 1

– The value associated with the REF_FRAME keyword shall be ‘TEME’ (see annex A).

– The value associated with the TIME_SYSTEM keyword shall be ‘UTC’.

– The format of the OBJECT_NAME and OBJECT_ID keywords shall be that of the SPACEWARN bulletin (reference [2]).

– The MEAN_MOTION keyword must be used instead of SEMI_MAJOR_AXIS.

4.2.4.7 For those who wish to use the OMM to represent a TLE, there are a number of considerations that apply with respect to precision of angle representation, use of certain fields by the propagator, reference frame, etc. Some sources suggest the coding for the EPHEMERIS_TYPE keyword: 1=SGP, 2=SGP4, 3=SDP4, 4=SGP8, 5=SDP8. Some sources suggest the following coding for the CLASSIFICATION_TYPE keyword: U=unclassified, S=secret. (For further information see references [G3] and [G4].)

4.2.4.8 Maneuvers are not accommodated in the OMM. Users of the OMM who wish to model maneuvers may use several OMM files to describe the orbit at applicable epochs.

4.2.4.9 A section of User Defined Parameters is allowed. In principle, this provides flexibility, but also introduces complexity, non-standardization, potential ambiguity, and potential processing errors. Accordingly, if used, the keywords and their meanings must be described in an ICD. User Defined Parameters, if included in an OMM, should be used as sparingly as possible; their use is not encouraged.

4.3 OMM EXAMPLES

Figure 4-2 and figure 4-3 are examples of OMMs based on the TLE shown in figure 4-1.

```
GOES 9 [P]
1 23581U 95025A   07064.44075725 -.00000113  00000-0  10000-3 0  9250
2 23581   3.0539  81.7939 0005013 249.2363 150.1602  1.00273272 43169
```

Figure 4-1: Example Two Line Element Set (TLE)

```
CCSDS_OMM_VERS = 2.0
CREATION_DATE  = 2007-065T16:00:00
ORIGINATOR     = NOAA/USA

OBJECT_NAME    = GOES 9
OBJECT_ID      = 1995-025A
CENTER_NAME    = EARTH
REF_FRAME      = TEME
TIME_SYSTEM    = UTC
MEAN_ELEMENT_THEORY = SGP/SGP4


EPOCH               = 2007-064T10:34:41.4264
MEAN_MOTION         = 1.00273272
ECCENTRICITY        = 0.0005013
INCLINATION         =   3.0539
RA_OF_ASC_NODE      =  81.7939
ARG_OF_PERICENTER   = 249.2363
MEAN_ANOMALY        = 150.1602
GM                  = 398600.8
EPHEMERIS_TYPE      = 0
CLASSIFICATION_TYPE = U
NORAD_CAT_ID        = 23581
ELEMENT_SET_NO      = 0925
REV_AT_EPOCH        = 4316
BSTAR               = 0.0001
MEAN_MOTION_DOT     = -0.00000113
MEAN_MOTION_DDOT    = 0.0
```

Figure 4-2: OMM File Example without Covariance Matrix

Cor. 1

Cor. 1

```
CCSDS_OMM_VERS = 2.0
CREATION_DATE  = 2007-065T16:00:00
ORIGINATOR     = NOAA/USA

OBJECT_NAME     = GOES 9
OBJECT_ID       = 1995-025A
CENTER_NAME     = EARTH
REF_FRAME       = TEME
TIME_SYSTEM     = UTC
MEAN_ELEMENT_THEORY = SGP/SGP4

EPOCH              = 2007-064T10:34:41.4264
MEAN_MOTION        = 1.00273272
ECCENTRICITY       = 0.0005013
INCLINATION        =   3.0539
RA_OF_ASC_NODE     =  81.7939
ARG_OF_PERICENTER  = 249.2363
MEAN_ANOMALY       = 150.1602
GM                 = 398600.8

EPHEMERIS_TYPE     = 0
CLASSIFICATION_TYPE = U
NORAD_CAT_ID    = 23581
ELEMENT_SET_NO = 0925
REV_AT_EPOCH       = 4316
BSTAR              = 0.0001
MEAN_MOTION_DOT    = -0.00000113
MEAN_MOTION_DDOT   = 0.0

COV_REF_FRAME = TEME
CX_X =  3.331349476038534e-04
CY_X =  4.618927349220216e-04
CY_Y =  6.782421679971363e-04
CZ_X =  -3.070007847730449e-04
CZ_Y =  -4.221234189514228e-04
CZ_Z =  3.231931992380369e-04
CX_DOT_X =  -3.349365033922630e-07
CX_DOT_Y =  -4.686084221046758e-07
CX_DOT_Z =  2.484949578400095e-07
CX_DOT_X_DOT =  4.296022805587290e-10
CY_DOT_X =  -2.211832501084875e-07
CY_DOT_Y =  -2.864186892102733e-07
CY_DOT_Z =  1.798098699846038e-07
CY_DOT_X_DOT =  2.608899201686016e-10
CY_DOT_Y_DOT =  1.767514756338532e-10
CZ_DOT_X =  -3.041346050686871e-07
CZ_DOT_Y =  -4.989496988610662e-07
CZ_DOT_Z =  3.540310904497689e-07
CZ_DOT_X_DOT =  1.869263192954590e-10
CZ_DOT_Y_DOT =  1.008862586240695e-10
CZ_DOT_Z_DOT =  6.224444338635500e-10
```

Figure 4-3: OMM File Example with Covariance Matrix

```
CCSDS_OMM_VERS = 2.0
CREATION_DATE  = 2007-065T16:00:00
ORIGINATOR     = NOAA/USA

OBJECT_NAME    = GOES 9
OBJECT_ID      = 1995-025A
CENTER_NAME    = EARTH
REF_FRAME      = TEME
TIME_SYSTEM    = UTC
MEAN_ELEMENT_THEORY = SGP/SGP4


EPOCH              = 2007-064T10:34:41.4264
MEAN_MOTION        = 1.00273272    [rev/day]
ECCENTRICITY       = 0.0005013
INCLINATION        =   3.0539      [deg]
RA_OF_ASC_NODE     =  81.7939      [deg]
ARG_OF_PERICENTER = 249.2363      [deg]
MEAN_ANOMALY       = 150.1602      [deg]
GM                 = 398600.8      [km**3/s**2]
EPHEMERIS_TYPE     = 0
CLASSIFICATION_TYPE = U
NORAD_CAT_ID   = 23581
ELEMENT_SET_NO = 0925
REV_AT_EPOCH       = 4316
BSTAR              = 0.0001        [1/ER]
MEAN_MOTION_DOT    = -0.00000113   [rev/day**2]
MEAN_MOTION_DDOT   = 0.0           [rev/day**3]

USER_DEFINED_EARTH_MODEL = WGS-84
```

Figure 4-4: OMM with Units and a User Defined Parameter

Cor. 1

5 ORBIT EPHEMERIS MESSAGE (OEM)

5.1 GENERAL

5.1.1 Orbit information may be exchanged between two participants by sending an ephemeris in the form of a series of state vectors (Cartesian vectors providing position and velocity, and optionally accelerations) using an Orbit Ephemeris Message (OEM). The message recipient must have a means of interpolating across these state vectors to obtain the state at an arbitrary time contained within the span of the ephemeris.

5.1.2 The OEM may be used for assessing mutual physical or electromagnetic interference among Earth-orbiting spacecraft, developing collaborative maneuvers, and representing the orbits of active satellites, inactive man made objects, near-Earth debris fragments, etc. The OEM reflects the dynamic modeling of any users' approach to conservative and non-conservative phenomena.

5.1.3 The OEM shall be a plain text file consisting of orbit data for a single object. It shall be easily readable by both humans and computers.

5.1.4 The OEM file-naming scheme should be agreed to on a case-by-case basis between the participants, typically using an ICD. The method of exchanging OEMs should be decided on a case-by-case basis by the participants and documented in an ICD.

NOTE – Detailed syntax rules for the OEM are specified in section 6.

5.2 OEM CONTENT/STRUCTURE

5.2.1 GENERAL

5.2.1.1 The OEM shall be represented as a combination of the following:

a) a header;

b) metadata (data about data);

c) ephemeris data;

d) optional covariance matrix data; and

e) optional comments (explanatory information).

5.2.1.2 OEM files must have a set of minimum required sections; some may be repeated. Table 5-1 outlines the contents of an OEM.

Table 5-1: OEM File Layout Specifications

Required Sections	Header Metadata Ephemeris Data (Appropriate comments should also be included, although they are not required.)
Allowable Repetitions of Sections	Covariance Matrix (optional) Metadata Ephemeris Data Covariance Matrix (optional) Metadata Ephemeris Data Covariance Matrix (optional) Metadata Ephemeris Data Covariance Matrix (optional) …etc. (Appropriate comments should also be included.)

5.2.2 OEM HEADER

5.2.2.1 The OEM header assignments are shown in table 5-2, which specifies for each item:

a) the keyword to be used;

b) a short description of the item;

c) examples of allowed values; and

d) whether the item is obligatory or optional.

5.2.2.2 Only those keywords shown in table 5-2 shall be used in an OEM header.

Table 5-2: OEM Header

Keyword	Description	Examples of Values	Obligatory
CCSDS_OEM_VERS	Format version in the form of 'x.y', where 'y' is incremented for corrections and minor changes, and 'x' is incremented for major changes.	2.0	Yes
COMMENT	Comments (allowed in the OEM Header only immediately after the OEM version number). (See 6.7 for formatting rules.)	COMMENT See 6.7	No
CREATION_DATE	File creation date and time in UTC. (For format specification, see 6.5.9.)	2001-11-06T11:17:33 2002-204T15:56:23	Yes
ORIGINATOR	Creating agency or operator (value should be specified in an ICD). The country of origin should also be provided where the originator is not a national space agency.	CNES, ESOC, GSFC, GSOC, JPL, JAXA, INTELSAT/USA, USAF, INMARSAT/UK	Yes

5.2.3 OEM METADATA

5.2.3.1 The OEM metadata assignments are shown in table 5-3, which specifies for each item:

a) the keyword to be used;

b) a short description of the item;

c) examples of allowed values; and

d) whether the item is obligatory or optional.

5.2.3.2 Only those keywords shown in table 5-3 shall be used in OEM metadata.

NOTE – For some keywords (OBJECT_NAME, OBJECT_ID, CENTER_NAME) there are no definitive lists of authorized values maintained by a control authority; the references listed in 1.7 are the best known sources for authorized values to date. For the TIME_SYSTEM and REF_FRAME keywords, the approved values are listed in annex A.

5.2.3.3 A single metadata group shall precede each ephemeris data block. Multiple occurrences of a metadata group followed by an ephemeris data block may be used. Before each metadata group the string 'META_START' shall appear on a separate line and after each metadata group (and before the associated ephemeris data block) the string 'META_STOP' shall appear on a separate line.

Table 5-3: OEM Metadata

Keyword	Description	Examples of Values	Obligatory
META_START	The OEM message contains metadata, ephemeris data, and covariance data; this keyword is used to delineate the start of a metadata block within the message (metadata are provided in a block, surrounded by 'META_START' and 'META_STOP' markers to facilitate file parsing). This keyword must appear on a line by itself.	n/a	Yes
COMMENT	Comments allowed only immediately after the META_START keyword. (See 6.7 for formatting rules.)	COMMENT This is a comment.	No
OBJECT_NAME	The name of the object for which the ephemeris is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended to use names from the SPACEWARN Bulletin (reference [2]), which include Object name and international designator of the participant.	EUTELSAT W1 MARS PATHFINDER STS 106 NEAR	Yes
OBJECT_ID	Object identifier of the object for which the ephemeris is provided. There is no CCSDS-based restriction on the value for this keyword, but it is recommended that values be the international spacecraft designator as published in the SPACEWARN Bulletin (reference [2]). Recommended values have the format YYYY-NNNP{PP}, where: YYYY = Year of launch. NNN = Three-digit serial number of launch in year YYYY (with leading zeros). P{PP} = At least one capital letter for the identification of the part brought into space by the launch. In cases where the asset is not listed in reference [2], or the SPACEWARN format is not used, the value should be provided in an ICD.	2000-052A 1996-068A 2000-053A 1996-008A	Yes
CENTER_NAME	Origin of reference frame, which may be a natural solar system body (planets, asteroids, comets, and natural satellites), including any planet barycenter or the solar system barycenter, or another spacecraft (in this case the value for 'CENTER_NAME' is subject to the same rules as for 'OBJECT_NAME'). There is no CCSDS-based restriction on the value for this keyword, but for natural bodies it is recommended to use names from the NASA/JPL Solar System Dynamics Group at http://ssd.jpl.nasa.gov (reference [5]).	EARTH EARTH BARYCENTER MOON SOLAR SYSTEM BARYCENTER SUN JUPITER BARYCENTER STS 106 EROS	Yes

Keyword	Description	Examples of Values	Obligatory

`REF_FRAME`	Name of the reference frame in which the ephemeris data are given. Use of values other than those in annex A must be documented in an ICD. The reference frame must be the same for all data elements, with the exception of the covariance matrix, for which an applicable different reference frame may be specified.	`ICRF`
		`ITRF-93`
		`ITRF-97`
		`ITRF2000`
		`ITRFxxxx` (template for future versions)
		`TOD` (True Equator and Equinox of Date)
		`EME2000` (Earth Mean Equator and Equinox of J2000)
		`TDR` (true of date rotating)
		`GRC` (Greenwich rotating coordinate frame, another name for TDR)
			`Yes`

`REF_FRAME_EPOCH`	Epoch of reference frame, if not intrinsic to the definition of the reference frame. (See 6.5.9 for formatting rules.)	`2001-11-06T11:17:33` `2002-204T15:56:23Z`	No
`TIME_SYSTEM`	Time system used for metadata, ephemeris data, and covariance data. Use of values other than those in annex A must be documented in an ICD.	`UTC, TAI, TT, GPS, TDB, TCB`	`Yes`
`START_TIME`	Start of TOTAL time span covered by ephemeris data and covariance data immediately following this metadata block. (For format specification, see 6.5.9.)	`1996-12-18T14:28:15.1172` `1996-277T07:22:54`	Yes

`USEABLE_START_TIME`
 	
`USEABLE_STOP_TIME`
	Optional start and end of USEABLE time span covered by ephemeris data immediately following this metadata block. To allow for proper interpolation near the ends of the ephemeris data block it may be necessary, depending upon the interpolation method to be used, to utilize these keywords with values within the time span covered by the ephemeris data records as denoted by the START/STOP_TIME time tags. (For format specification, see 6.5.9.) These keywords are optional items, and thus may not be necessary, depending on the recommended interpolation method. However, it is recommended to use the USEABLE_START_TIME and USEABLE_STOP_TIME capability in all cases. The USEABLE_START_TIME time tag at a new block of ephemeris data must be greater than or equal to the USEABLE_STOP_TIME time tag of the previous block.	`1996-12-18T14:28:15.1172`
		`1996-277T07:22:54`
			No

`STOP_TIME`	End of TOTAL time span covered by ephemeris data and covariance data immediately following this metadata block. (For format specification, see 6.5.9.)	`1996-12-18T14:28:15.1172` `1996-277T07:22:54`	Yes
`INTERPOLATION`	This keyword may be used to specify the recommended interpolation method for ephemeris data in the immediately following set of ephemeris lines.	Hermite Linear Lagrange	No

Keyword	Description	Examples of Values	Obligatory
INTERPOLATION_DEGREE	Recommended interpolation degree for ephemeris data in the immediately following set of ephemeris lines. Must be an integer value. This keyword must be used if the 'INTERPOLATION' keyword is used.	5 1	No
META_STOP	The OEM message contains metadata, ephemeris data, and covariance data; this keyword is used to delineate the end of a metadata block within the message (metadata are provided in a block, surrounded by 'META_START' and 'META_STOP' markers to facilitate file parsing). This keyword must appear on a line by itself.	n/a	Yes

5.2.4 OEM DATA: EPHEMERIS DATA LINES

5.2.4.1 Each set of ephemeris data, including the time tag, must be provided on a single line. The order in which data items are given shall be fixed: **Epoch**, **X, Y, Z**, **X_DOT, Y_DOT, Z_DOT, X_DDOT, Y_DDOT, Z_DDOT**.

5.2.4.2 The position and velocity terms shall be obligatory; acceleration terms may be provided.

5.2.4.3 At least one space character must be used to separate the items in each ephemeris data line.

5.2.4.4 Repeated time tags may occur in consecutive ephemeris data blocks if the STOP_TIME of the first ephemeris data block is greater than the START_TIME of the second ephemeris data block. Although the USEABLE_STOP_TIME and USEABLE_START_TIME of the consecutive ephemeris data blocks must not overlap (except for a possibly shared endpoint), the STOP_TIME of the first ephemeris data block may be greater than the START_TIME of the second ephemeris data block if the extra data is required for interpolation purposes. Cor. 1

5.2.4.5 The TIME_SYSTEM value must remain fixed within an OEM.

5.2.4.6 The occurrence of a second (or greater) metadata block after some ephemeris data indicates that interpolation using succeeding ephemeris data with ephemeris data occurring prior to that metadata block shall not be done. This method may be used for proper modeling of propulsive maneuvers or any other source of a discontinuity such as eclipse entry or exit.

5.2.4.7 Details about interpolation method should be specified using the INTERPOLATION and INTERPOLATION_DEGREE keywords within the OEM. All data blocks must contain a sufficient number of ephemeris data records to allow the recommended interpolation method to be carried out consistently throughout the OEM.

5.2.5 OEM DATA: COVARIANCE MATRIX LINES

5.2.5.1 A single covariance matrix data section may optionally follow each ephemeris data block.

5.2.5.2 If present, the covariance matrix data lines in the OEM are separated from the ephemeris data by means of two new keywords: COVARIANCE_START and COVARIANCE_STOP. The 'COVARIANCE_START' keyword must appear before the first line of the covariance matrix data. The 'COVARIANCE_STOP' keyword must appear after the last line of covariance data. Each of these keywords shall appear on a line by itself with no time tags or values.

5.2.5.3 The epoch of the navigation solution related to the covariance matrix must be provided via the 'EPOCH' keyword. The reference frame of the covariance matrix, if different from that of the states in the ephemeris, must be provided via the 'COV_REF_FRAME' keyword.

5.2.5.4 Each row of the 6x6 lower triangular covariance matrix must be provided on a single line. The order in which data items are given shall be fixed. The elements in each row of covariates shall be defined by the order in the ephemeris data line (i.e., **X, Y, Z, X_DOT, Y_DOT, Z_DOT**). The six rows of the covariance matrix contain from one to six numbers depending on what row of the matrix is being represented (first row has one element, second row has two, continuing in this fashion until the sixth row has six elements).

5.2.5.5 At least one space character must be used to separate the items in each covariance matrix data line.

5.2.5.6 Multiple covariance matrices may appear in the covariance matrix section; they may appear with any desired frequency (one for each navigation solution that makes up the overall ephemeris is recommended). The OEM may also contain propagated covariances, not just individual covariances associated with navigation solutions.

5.2.5.7 If there are multiple covariance matrices in the data section, they must be ordered by increasing time tag.

5.3 OEM EXAMPLES

Figure 5-1, figure 5-2, and figure 5-3 are example OEMs. Some ephemeris data lines have been omitted to save space.

Figure 5-1 is compatible with ODM version 1, and thus could use either 'CCSDS_OEM_VERS = 1.0' (since it does not contain any of the unique features of the ODM version 2), or 'CCSDS_OEM_VERS = 2.0' (as shown). Figure 5-2 and figure 5-3 contain features unique to the ODM version 2, and thus 'CCSDS_OEM_VERS = 2.0' must be specified.

```
CCSDS_OEM_VERS = 2.0
CREATION_DATE = 1996-11-04T17:22:31
ORIGINATOR = NASA/JPL

META_START
OBJECT_NAME          = MARS GLOBAL SURVEYOR
OBJECT_ID            = 1996-062A
CENTER_NAME          = MARS BARYCENTER
REF_FRAME            = EME2000
TIME_SYSTEM          = UTC
START_TIME           = 1996-12-18T12:00:00.331
USEABLE_START_TIME   = 1996-12-18T12:10:00.331
USEABLE_STOP_TIME    = 1996-12-28T21:23:00.331
STOP_TIME            = 1996-12-28T21:28:00.331
INTERPOLATION        = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP
COMMENT  This file was produced by M.R. Somebody, MSOO NAV/JPL, 1996NOV 04. It is
COMMENT  to be used for DSN scheduling purposes only.

1996-12-18T12:00:00.331  2789.619 -280.045 -1746.755  4.73372 -2.49586 -1.04195
1996-12-18T12:01:00.331  2783.419 -308.143 -1877.071  5.18604 -2.42124 -1.99608
1996-12-18T12:02:00.331  2776.033 -336.859 -2008.682  5.63678 -2.33951 -1.94687

   < intervening data records omitted here >

1996-12-28T21:28:00.331 -3881.024 563.959 -682.773  -3.28827 -3.66735 1.63861


META_START
OBJECT_NAME           = MARS GLOBAL SURVEYOR
OBJECT_ID             = 1996-062A
CENTER_NAME           = MARS BARYCENTER
REF_FRAME             = EME2000
TIME_SYSTEM           = UTC
START_TIME            = 1996-12-28T21:29:07.267
USEABLE_START_TIME    = 1996-12-28T22:08:02.5
USEABLE_STOP_TIME     = 1996-12-30T01:18:02.5
STOP_TIME             = 1996-12-30T01:28:02.267
INTERPOLATION         = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP

COMMENT  This block begins after trajectory correction maneuver TCM-3.

1996-12-28T21:29:07.267 -2432.166 -063.042 1742.754  7.33702 -3.495867 -1.041945
1996-12-28T21:59:02.267 -2445.234 -878.141 1873.073  1.86043 -3.421256 -0.996366
1996-12-28T22:00:02.267 -2458.079 -683.858 2007.684  6.36786 -3.339563 -0.946654

   < intervening data records omitted here >

1996-12-30T01:28:02.267 2164.375 1115.811 -688.131  -3.53328 -2.88452 0.88535
```

Figure 5-1: Version 1 OEM Compatible Example (No Acceleration, No Covariance)

```
CCSDS_OEM_VERS = 2.0

COMMENT  OEM WITH OPTIONAL ACCELERATIONS MUST BE OEM VERSION 2.0

CREATION_DATE = 1996-11-04T17:22:31
ORIGINATOR = NASA/JPL

META_START
OBJECT_NAME          = MARS GLOBAL SURVEYOR
OBJECT_ID            = 1996-062A
CENTER_NAME          = MARS BARYCENTER
REF_FRAME            = EME2000
TIME_SYSTEM          = UTC
START_TIME           = 1996-12-18T12:00:00.331
USEABLE_START_TIME   = 1996-12-18T12:10:00.331
USEABLE_STOP_TIME    = 1996-12-28T21:23:00.331
STOP_TIME            = 1996-12-28T21:28:00.331
INTERPOLATION        = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP

COMMENT  This file was produced by M.R. Somebody, MSOO NAV/JPL, 2000 NOV 04. It is
COMMENT  to be used for DSN scheduling purposes only.

1996-12-18T12:00:00.331  2789.6 -280.0 -1746.8  4.73 -2.50 -1.04  0.008 0.001 -0.159
1996-12-18T12:01:00.331  2783.4 -308.1 -1877.1  5.19 -2.42 -2.00  0.008 0.001  0.001
1996-12-18T12:02:00.331  2776.0 -336.9 -2008.7  5.64 -2.34 -1.95  0.008 0.001  0.159

   < intervening data records omitted here >

1996-12-28T21:28:00.331 -3881.0  564.0 -682.8 -3.29 -3.67  1.64  -0.003 0.000  0.000
```

Figure 5-2: Version 2 OEM Example with Optional Accelerations

```
CCSDS_OEM_VERS = 2.0
CREATION_DATE = 1996-11-04T17:22:31
ORIGINATOR = NASA/JPL

META_START
OBJECT_NAME          = MARS GLOBAL SURVEYOR
OBJECT_ID            = 1996-062A
CENTER_NAME          = MARS BARYCENTER
REF_FRAME            = EME2000
TIME_SYSTEM          = UTC
START_TIME           = 1996-12-28T21:29:07.267
USEABLE_START_TIME   = 1996-12-28T22:08:02.5
USEABLE_STOP_TIME    = 1996-12-30T01:18:02.5
STOP_TIME            = 1996-12-30T01:28:02.267
INTERPOLATION        = HERMITE
INTERPOLATION_DEGREE = 7
META_STOP


COMMENT  This block begins after trajectory correction maneuver TCM-3.

1996-12-28T21:29:07.267 -2432.166 -063.042 1742.754  7.33702 -3.495867 -1.041945
1996-12-28T21:59:02.267 -2445.234 -878.141 1873.073  1.86043 -3.421256 -0.996366
1996-12-28T22:00:02.267 -2458.079 -683.858 2007.684  6.36786 -3.339563 -0.946654

   < intervening data records omitted here >

1996-12-30T01:28:02.267 2164.375 1115.811 -688.131  -3.53328 -2.88452 0.88535


COVARIANCE_START
EPOCH = 1996-12-28T21:29:07.267
COV_REF_FRAME = EME2000
 3.3313494e-04
 4.6189273e-04  6.7824216e-04
-3.0700078e-04 -4.2212341e-04  3.2319319e-04
-3.3493650e-07 -4.6860842e-07  2.4849495e-07  4.2960228e-10
-2.2118325e-07 -2.8641868e-07  1.7980986e-07  2.6088992e-10  1.7675147e-10
-3.0413460e-07 -4.9894969e-07  3.5403109e-07  1.8692631e-10  1.0088625e-10  6.2244443e-10

EPOCH = 1996-12-29T21:00:00
COV_REF_FRAME = EME2000
 3.4424505e-04
 4.5078162e-04  6.8935327e-04
-3.0600067e-04 -4.1101230e-04  3.3420420e-04
-3.2382549e-07 -4.5750731e-07  2.3738384e-07  4.3071339e-10
-2.1007214e-07 -2.7530757e-07  1.6870875e-07  2.5077881e-10  1.8786258e-10
-3.0302350e-07 -4.8783858e-07  3.4302008e-07  1.7581520e-10  1.0077514e-10  6.2244443e-10
COVARIANCE_STOP
```

Figure 5-3: Version 2 OEM Example with Optional Covariance Matrices

6 ORBIT DATA MESSAGE SYNTAX

6.1 OVERVIEW

This section details the syntax requirements for each of the Orbit Data Messages.

6.2 GENERAL

The Orbit Data Messages (OPM, OMM, OEM) shall observe the syntax described in 6.2 through 6.7.

6.3 ODM LINES

6.3.1 Each ODM file shall consist of a set of OPM, OMM, or OEM lines. Each ODM line shall be one of the following:

– Header line;

– Metadata line;

– Data line; or

– Blank line.

6.3.2 Each OEM, OPM, or OMM line must not exceed 254 ASCII characters and spaces (excluding line termination character[s]).

6.3.3 Only printable ASCII characters and blanks shall be used. Control characters (such as TAB, etc.) shall not be used, with the exception of the line termination characters specified below.

6.3.4 Blank lines may be used at any position within the file. Blank lines shall have no assignable meaning, and may be ignored.

6.3.5 The first header line must be the first non-blank line in the file.

6.3.6 All lines shall be terminated by a single Carriage Return or a single Line Feed, or a Carriage Return/Line Feed pair or a Line Feed/Carriage Return pair.

6.4 KEYWORD = VALUE NOTATION AND ORDER OF ASSIGNMENT STATEMENTS

6.4.1 For the OPM and OMM, all header, metadata, and data lines shall use 'keyword = value' notation, abbreviated as KVN.

6.4.1.1 For the OEM, all header and metadata elements shall use KVN notation.

6.4.1.2 OEM ephemeris data lines shall not use KVN format; rather, the OEM ephemeris data line has a fixed structure containing seven required fields (epoch time, three position components, three velocity components), and three optional acceleration components. (See 5.2.4.)

6.4.1.3 OEM covariance matrix epoch and covariance reference frame (if used) shall use KVN format. The OEM covariance data lines shall not use KVN format; rather, the OEM covariance data line has a fixed structure containing from one to six required fields (a row from the 6x6 lower triangular form covariance matrix). (See 5.2.5.)

6.4.2 The keywords 'COMMENT', 'META_START', 'META_STOP', 'COVARIANCE_START', and 'COVARIANCE_STOP' are exceptions to the KVN syntax assignment.

6.4.3 Only a single 'keyword = value' assignment shall be made on a line.

6.4.4 Keywords must be uppercase and must not contain blanks.

6.4.5 Any white space immediately preceding or following the keyword shall not be significant.

6.4.6 Any white space immediately preceding or following the 'equals' sign shall not be significant.

6.4.7 Any white space immediately preceding the end of line shall not be significant.

6.4.8 The order of occurrence of obligatory and optional KVN assignments shall be fixed as shown in the tables in sections 3, 4, and 5 that describe the OPM, OMM, and OEM keywords.

6.5 VALUES

6.5.1 A non-empty value field must be specified for each obligatory keyword.

6.5.2 Integer values shall consist of a sequence of decimal digits with an optional leading sign ('+' or '-'). If the sign is omitted, '+' shall be assumed. Leading zeroes may be used. The range of values that may be expressed as an integer is:

$$-2,147,483,648 <= x <= +2,147,483,647 \quad (\text{i.e., } -2^{31} <= x <= 2^{31}-1).$$

6.5.3 Non-integer numeric values may be expressed in either fixed-point or floating-point notation. Both representations may be used within an OPM, OMM, or OEM.

6.5.4 Non-integer numeric values expressed in fixed-point notation shall consist of a sequence of decimal digits separated by a period as a decimal point indicator, with an optional leading sign ('+' or '-'). If the sign is omitted, '+' shall be assumed. Leading and trailing zeroes may be used. At least one digit shall appear before and after a decimal point. The number of digits shall be 16 or fewer.

6.5.5 Non-integer numeric values expressed in floating point notation shall consist of a sign, a mantissa, an alphabetic character indicating the division between the mantissa and exponent, and an exponent, constructed according to the following rules:

a) The sign may be '+' or '-'. If the sign is omitted, '+' shall be assumed.

b) The mantissa must be a string of no more than 16 decimal digits with a decimal point ('.') in the second position of the ASCII string, separating the integer portion of the mantissa from the fractional part of the mantissa.

c) The character used to denote exponentiation shall be 'E' or 'e'. If the character indicating the exponent and the following exponent are omitted, an exponent value of zero shall be assumed (essentially yielding a fixed point value).

d) The exponent must be an integer, and may have either a '+' or '-' sign (if the sign is omitted, then '+' shall be assumed).

e) The maximum positive floating point value is approximately 1.798E+308, with 16 significant decimal digits precision. The minimum positive floating point value is approximately 4.94E-324, with 16 significant decimal digits precision.

NOTE – These specifications for integer, fixed point and floating point values conform to the XML specifications for the data types four-byte integer 'xsd:int', 'decimal', and 'double', respectively (reference [6]). The specifications for floating point values conform to the IEEE double precision type (references [6] and [7]). Floating point numbers in IEEE extended-single or IEEE extended-double precision may be represented, but do require an ICD between exchange partners because of their implementation-specific attributes (reference [7]). The special values 'NaN', '-Inf', '+Inf', and '-0' are not supported in the ODM.

6.5.6 Text value fields must be constructed using only all uppercase or all lowercase.

6.5.7 Blanks shall not be permitted within numeric values and time strings.

6.5.8 In value fields that are text, an underscore shall be equivalent to a single blank. Individual blanks shall be retained (shall be significant), but multiple contiguous blanks shall be equivalent to a single blank.

6.5.9 In value fields that represent a time tag or epoch, times shall be given in one of the following two formats:

YYYY-MM-DDThh:mm:ss[.d→d][Z]

or

YYYY-DDDThh:mm:ss[.d→d][Z]

where 'YYYY' is the year, 'MM' is the two-digit month, 'DD' is the two-digit day, 'DDD' is the three-digit day of year, 'T' is constant, 'hh:mm:ss[.d→d]' is the time in hours, minutes seconds, and optional fractional seconds; 'Z' is an optional time code terminator (the only permitted value is 'Z' for Zulu, i.e., UTC). As many 'd' characters to the right of the period as required may be used to obtain the required precision, up to the maximum allowed for a fixed point number. All fields shall have leading zeros. (See reference [1], ASCII Time Code A or B.)

6.5.10 There are eight types of ODM values that represent a time tag or epoch, as shown in the applicable tables. The time system for the CREATION_DATE shall be UTC; the time system for the EPOCH, REF_FRAME_EPOCH, MAN_EPOCH_IGNITION, START_TIME, USEABLE_START_TIME, USEABLE_STOP_TIME, STOP_TIME, and the covariance matrix epoch time shall be as determined by the TIME_SYSTEM metadata keyword. Cor. 1

6.6 UNITS IN THE ORBIT DATA MESSAGES

6.6.1 OPM/OMM UNITS

6.6.1.1 For documentation purposes and clarity, units may be included as ASCII text after a value in the OPM and OMM. If units are displayed, they must exactly match the units specified in table 3-3 and table 4-3 (including case). If units are displayed, then:

a) there must be at least one blank character between the value and the units text;

b) the units must be enclosed within square brackets (e.g., '[km]');

c) exponents of units shall be denoted with a double asterisk (i.e., '**', for example, m/s^2=m/s**2).

6.6.1.2 Some of the items in the applicable tables are dimensionless. The table shows a unit value of 'n/a', which in this case means that there is no applicable units designator for these items (e.g., for ECCENTRICITY). The notation '[n/a]' should not appear in an OPM or OMM.

6.6.2 OEM UNITS

6.6.2.1 In an OEM ephemeris data line, units shall be km, km/s, and km/s**2 for position, velocity, and acceleration components, respectively, but the units shall not be displayed.

6.6.2.2 In an OEM covariance matrix line, units shall be km**2, km**2/s, or km**2/s**2 depending on whether the element is computed from two position components, one position component and one velocity component, or two velocity components. The units shall not be displayed.

6.7 COMMENTS IN THE ORBIT DATA MESSAGES

6.7.1 There are certain pieces of information that provide clarity and remove ambiguity about the interpretation of the information in a file, yet are not standardized so as to fit cleanly into the 'keyword = value' paradigm. Rather than force the information to fit into a space limited to one line, the ODM producer should put certain information into comments and use the ICD to provide further specifications.

6.7.2 Comments may be used to provide provenance information or to help describe dynamical events or other pertinent information associated with the data. This additional information is intended to aid in consistency checks and elaboration where needed, but shall not be required for successful processing of a file.

6.7.3 For the OPM, OMM, and OEM, comment lines shall be optional.

6.7.4 All comment lines shall begin with the '`COMMENT`' keyword followed by at least one space. This keyword must appear on every comment line, not just the first such line. The remainder of the line shall be the comment value. White space shall be retained (shall be significant) in comment values.

6.7.5 Placement of comments shall be as specified in the tables in sections 3, 4, and 5 that describe the OPM, OMM and OEM keywords.

6.7.6 Comments in the OPM may appear in the OPM Header immediately after the 'CCSDS_OPM_VERS' keyword, at the very beginning of the OPM Metadata section, and at the beginning of a logical block in the OPM Data section. Comments must not appear between the components of any logical block in the OPM Data section.

NOTE – The logical blocks in the OPM Data section are indicated in table 3-3.

6.7.7 Comments in the OMM may appear in the OMM Header immediately after the 'CCSDS_OMM_VERS' keyword, at the very beginning of the OMM Metadata section, and at the beginning of a logical block in the OMM Data section. Comments must not appear between the components of any logical block in the OMM Data section.

NOTE – The logical blocks in the OMM Data section are indicated in table 4-3.

6.7.8 Comments in the OEM may appear in the OEM Header immediately after the 'CCSDS_OEM_VERS' keyword, at the very beginning of the OEM Metadata section (after the 'META_START' keyword), at the beginning of the OEM Ephemeris Data Section, and at the beginning of the OEM Covariance Data section (after the 'COVARIANCE_START' keyword). Comment lines must not appear within any block of ephemeris lines or covariance matrix lines.

6.7.9 Extensive comments in an ODM are recommended in cases where there is insufficient time to negotiate an ICD. (For an example 'Checklist ICD', see annex D.)

6.7.10 The following comments should be provided:

a) Information regarding the genesis, history, interpretation, intended use, etc., of the state vector, spacecraft, maneuver, or ephemeris that may be of use to the receiver of the OPM, OMM, or OEM:

```
COMMENT Source: File created by JPL Multi-Mission Navigation Team as part
COMMENT of Launch Operations Readiness Test held on 20 April 2001.
```

b) Natural body ephemeris information: When the Earth is not the center of motion, the ephemerides of the planets, satellites, asteroids, and/or comets (including associated constants) consistent with the ODM should be identified so that the recipient can, in a consistent manner, make computations involving other centers:

```
COMMENT Based on latest orbit solution which includes observations
COMMENT through 2000-May-15 relative to planetary ephemeris DE-0405.
```

c) OEM accuracy vs. efficiency: If the covariance data section of the OEM is not utilized, the producer of an OEM should report in comment lines what the expected accuracy of the ephemeris is, so the user can smooth or otherwise compress the data without affecting the accuracy of the trajectory. The OEM producer also should strive to achieve not only the best accuracy possible, taking into account prediction errors, but also consider the efficiency of the trajectory representation (e.g., step sizes of fractional seconds between ephemeris lines may be necessary for precision scientific reconstruction of an orbit, but are excessive from the standpoint of antenna pointing predicts generation).

6.8 ORBIT DATA MESSAGE KEYWORDS

6.8.1 VERSION KEYWORDS

The Header of the OPM, OMM, and OEM shall provide a CCSDS Orbit Data Message version number that identifies the format version; this is included to anticipate future changes. The version keywords for the OPM, OMM, and OEM shall be CCSDS_OPM_VERS, CCSDS_OMM_VERS, and CCSDS_OEM_VERS, respectively. The value shall have the form of 'x.y', where 'y' shall be incremented for corrections and minor changes, and 'x' shall be incremented for major changes. Version x.0 shall be reserved for versions accepted by the CCSDS as an official Recommended Standard ('Blue Book'). Testing shall be conducted using OPM, OMM, and OEM version numbers less than 1.0 (e.g., 0.x). Exchange participants should specify in the ICD the specific OPM, OMM, and OEM version numbers they will support. The following version numbers are supported:

Version Keyword	Version Number	Applicable Recommendation
CCSDS_OPM_VERS	1.0	Silver Book 1.0, 09/2004
CCSDS_OPM_VERS	2.0	Blue Book 2.0 (this document)
CCSDS_OMM_VERS	2.0	Blue Book 2.0 (this document)
CCSDS_OEM_VERS	1.0	Silver Book 1.0, 09/2004
CCSDS_OEM_VERS	2.0	Blue Book 2.0 (this document)

6.8.2 GENERAL KEYWORDS

6.8.2.1 Only those keywords shown in table 3-1, table 3-2, and table 3-3 shall be used in an OPM. Some keywords represent obligatory items and some are optional. KVN assignments representing optional items may be omitted.

6.8.2.2 Only those keywords shown in table 4-1, table 4-2, and table 4-3 shall be used in an OMM. Some keywords represent obligatory items and some are optional. KVN assignments representing optional items may be omitted.

6.8.2.3 Only those keywords shown in table 5-2 and table 5-3 shall be used in an OEM. Some keywords represent obligatory items and some are optional. KVN assignments representing optional items may be omitted.

(Blank page)

7 SECURITY

7.1 OVERVIEW

This section presents the results of an analysis of security considerations applied to the technologies specified in this Recommended Standard.

7.2 SECURITY CONCERNS RELATED TO THIS RECOMMENDED STANDARD

7.2.1 DATA PRIVACY

Privacy of data formatted in compliance with the specifications of this Recommended Standard should be assured by the systems and networks on which this Recommended Standard is implemented.

7.2.2 DATA INTEGRITY

Integrity of data formatted in compliance with the specifications of this Recommended Standard should be assured by the systems and networks on which this Recommended Standard is implemented.

7.2.3 AUTHENTICATION OF COMMUNICATING ENTITIES

Authentication of communicating entities involved in the transport of data which complies with the specifications of this Recommended Standard should be provided by the systems and networks on which this Recommended Standard is implemented.

7.2.4 DATA TRANSFER BETWEEN COMMUNICATING ENTITIES

The transfer of data formatted in compliance with this Recommended Standard between communicating entities should be accomplished via secure mechanisms approved by the IT Security functionaries of exchange participants.

7.2.5 CONTROL OF ACCESS TO RESOURCES

This Recommended Standard assumes that control of access to resources will be managed by the systems upon which provider formatting and recipient processing are performed.

7.2.6 AUDITING OF RESOURCE USAGE

This Recommended Standard assumes that auditing of resource usage will be handled by the management of systems and networks on which this Recommended Standard is implemented.

7.3 POTENTIAL THREATS AND ATTACK SCENARIOS

Potential threats or attack scenarios include, but are not limited to, (a) unauthorized access to the programs/processes that generate and interpret the messages, and (b) unauthorized access to the messages during transmission between exchange partners. Unauthorized access to the programs/processes that generate and interpret the messages should be prohibited. Protection from unauthorized access during transmission is especially important if the mission utilizes open ground networks such as the Internet to provide ground station connectivity for the exchange of data formatted in compliance with this Recommended Standard. It is strongly recommended that potential threats or attack scenarios applicable to the systems and networks on which this Recommended Standard is implemented be addressed by the management of those systems and networks.

7.4 CONSEQUENCES OF NOT APPLYING SECURITY TO THE TECHNOLOGY

The consequences of not applying security to the systems and networks on which this Recommended Standard is implemented could include potential loss, corruption, and theft of data. Because these messages are used in preparing pointing and frequency predicts used during spacecraft commanding, and may also be used in collision avoidance studies, the consequences of not applying security to the systems and networks on which this Recommended Standard is implemented could include compromise or loss of the mission if malicious tampering of a particularly severe nature occurs.

7.5 DATA SECURITY IMPLEMENTATION SPECIFICS

Specific information-security interoperability provisions that may apply between agencies and other independent users involved in an exchange of data formatted in compliance with this Recommended Standard should be specified in an ICD.

ANNEX A

Cor. 1

VALUES FOR TIME_SYSTEM AND FRAME RELATED KEYWORDS

(NORMATIVE)

Cor. 1

The values in this annex represent the set of acceptable values for the TIME_SYSTEM, REF_FRAME, MAN_REF_FRAME, and COV_REF_FRAME keywords in the OPM, OMM, and OEM. (For details and description of these time systems, see reference [G1].) If exchange partners wish to use different settings, the settings should be documented in the ICD.

A1 TIME_SYSTEM METADATA KEYWORD

Time System Value	Meaning
GMST	Greenwich Mean Sidereal Time
GPS	Global Positioning System
MET	Mission Elapsed Time (note)
MRT	Mission Relative Time (note)
SCLK	Spacecraft Clock (receiver) (requires rules for interpretation in ICD)
TAI	International Atomic Time
TCB	Barycentric Coordinate Time
TDB	Barycentric Dynamical Time
TCG	Geocentric Coordinate Time
TT	Terrestrial Time
UT1	Universal Time
UTC	Coordinated Universal Time

If MET or MRT is chosen as the TIME_SYSTEM, then the epoch of either the start of the mission for MRT, or of the event for MET, should either be given in a comment in the message or provided in an ICD. The time system for the start of the mission or the event should also be provided in the comment or the ICD. If these values are used for the TIME_SYSTEM, then the times given in the file denote a duration from the mission start or event. However, for clarity, an ICD should be used to fully specify the interpretation of the times if these values are to be used. The time format should only utilize three digit days from the MET or MRT epoch, not months and days of the months.

A2 REF_FRAME KEYWORD

Reference Frame Value	Meaning
EME2000	Earth Mean Equator and Equinox of J2000
GCRF	Geocentric Celestial Reference Frame
GRC	Greenwich Rotating Coordinates
ICRF	International Celestial Reference Frame
ITRF2000	International Terrestrial Reference Frame 2000
ITRF-93	International Terrestrial Reference Frame 1993
ITRF-97	International Terrestrial Reference Frame 1997
MCI	Mars Centered Inertial
TDR	True of Date, Rotating
TEME	True Equator Mean Equinox (see below)
TOD	True of Date

Cor. 1

NORAD Two Line Element Sets are implicitly in a True Equator Mean Equinox (TEME) reference frame, which is ill defined in international standard or convention. TEME may be used only for OMMs based on NORAD Two Line Element sets, and in no other circumstances. There are subtle differences between TEME of Epoch and TEME of Date (see reference [G3] or [G4]). The effect is very small relative to TLE accuracy, and there is uncertainty regarding which of these is used by NORAD. The preferred option is TEME of Date. Users should specify in the ICD if their assumption is TEME of Epoch.

A3 MAN_REF_FRAME AND COV_REF_FRAME KEYWORDS

Reference Frame Value	Meaning
RSW	Another name for 'Radial, Transverse, Normal'
RTN	Radial, Transverse, Normal
TNW	A local orbital coordinate frame that has the x-axis along the velocity vector, W along the orbital angular momentum vector, and N completes the right handed system.

Cor. 1

ANNEX B

ABBREVIATIONS AND ACRONYMS

(INFORMATIVE)

ASCII	American Standard Code for Information Interchange
CCSDS	Consultative Committee for Space Data Systems
DSST	Draper Semi-Analytic Satellite Theory
ECI	Earth Centered Inertial
EGM	Earth Gravitational Model, Earth Geopotential Model
EME2000	Earth Mean Equator and Equinox of J2000 (Julian Date 2000)
EOP	Earth Orientation Parameters
GCRF	Geocentric Celestial Reference Frame
GPS	Global Positioning System
IAU	International Astronomical Union
ICD	Interface Control Document
ICRF	International Celestial Reference Frame
IEC	International Electrotechnical Commission
IERS	International Earth Rotation and Reference Systems Service
IIRV	Improved Inter-Range Vector
ISO	International Standards Organization
ITRF	International Terrestrial Reference Frame
ITRS	International Terrestrial Reference System
GRC	Greenwich Rotating Coordinate Frame
KVN	Keyword = Value Notation
NORAD	North American Aerospace Defense Command