
**Straight cylindrical involute splines —
Metric module, side fit —**

**Part 3:
Inspection**

*Cannelures cylindriques droites à flancs en développante — Module
métrique, à centrage sur flancs —*

Partie 3: Vérification

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Published in Switzerland

Contents

	Page
Foreword	v
Introduction	vi
1 Scope	1
2 Normative references	1
3 Terms and definitions	1
4 Symbols and abbreviated terms	1
5 Reference conditions	4
6 Quality features	4
6.1 General	4
6.2 Size	4
6.2.1 Actual size	4
6.2.2 Effective size	4
6.3 Location	5
6.4 Form	5
7 Methods of inspection	5
7.1 Size	5
7.1.1 General methods	5
7.1.2 Choice of measuring instrument	5
7.1.3 Actual size	5
7.1.4 Effective size	8
7.2 Location	8
7.2.1 General	8
7.2.2 Choice of the method of inspection of location	8
7.2.3 Effective axis using mating part	9
7.2.4 Actual pitch cylinder axis	9
7.2.5 Calculation with Fourier analysis	9
7.2.6 Spline clamping system	10
7.3 Form	10
8 Measurements with balls or pins	10
8.1 General	10
8.2 Selection of balls or pins	11
8.3 Use and marking of pins	11
8.4 Statistical actual tolerance limit L_{STA}	11
8.4.1 General	11
8.4.2 Acceptance of parts according to the statistical actual tolerance limit L_{STA}	12
8.4.3 Examples	13
8.5 Calculation of ball or pin diameter (D_{Re} or D_{Ri})	13
8.5.1 External spline	13
8.5.2 Internal spline	14
8.6 Calculation of dimensions for ball or pin inspection (part and gauge inspection)	15
8.6.1 Exact calculation	15
8.6.2 Approximation factor	18
9 Measurement over k teeth — External splines (W)	21
9.1 Calculation of W	21
9.2 Choice of k	21
10 Gauges	23
10.1 Generalities	23
10.1.1 Conditions of use of gauges	23
10.1.2 Limiting dimensions of use for gauges	23
10.1.3 Handles of spline gauges	23

10.1.4	Number of teeth for sector NO GO gauges.....	23
10.2	Length of measuring part of gauges.....	24
10.2.1	Influence of the active spline length and of the length of engagement.....	24
10.2.2	GO or NO GO gauges.....	24
10.2.3	Master plug gauges.....	25
10.2.4	Spline gauges of pitch diameters $D > 180$ mm.....	25
10.3	Manufacturing tolerances for spline gauges.....	25
10.4	Values of deviation allowances of spline gauges.....	28
10.5	Inspection of gauges.....	28
10.5.1	Damage.....	28
10.5.2	Marking.....	28
10.5.3	Major diameter of plug gauges and minor diameter of ring gauges.....	28
10.5.4	Form diameter.....	29
10.5.5	Tooth thickness of plug gauges.....	29
10.5.6	Space width of ring gauges.....	29
10.5.7	Form deviations.....	30
10.5.8	Gauge wear inspection.....	30
10.5.9	Inspection certificates.....	30
10.6	Dimensions, designation and marking of gauges.....	30
10.6.1	Inspection of external splines.....	30
10.6.2	Inspection of internal splines.....	37
10.6.3	Inspection with plain gauges for internal and external splines.....	39
10.6.4	Marking of gauges.....	40
11	Measurement of spline deviations.....	40
11.1	General.....	40
11.2	Total profile deviation F_α	40
11.3	Total pitch deviation F_p	41
11.4	Total helix deviation F_β	41
Annex A (informative) Influences of eccentricity and pitch deviation as explained in ISO 4156:1981.....		42
Bibliography.....		47

Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

The procedures used to develop this document and those intended for its further maintenance are described in the ISO/IEC Directives, Part 1. In particular, the different approval criteria needed for the different types of ISO documents should be noted. This document was drafted in accordance with the editorial rules of the ISO/IEC Directives, Part 2 (see www.iso.org/directives).

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights. Details of any patent rights identified during the development of the document will be in the Introduction and/or on the ISO list of patent declarations received (see www.iso.org/patents).

Any trade name used in this document is information given for the convenience of users and does not constitute an endorsement.

For an explanation of the voluntary nature of standards, the meaning of ISO specific terms and expressions related to conformity assessment, as well as information about ISO's adherence to the World Trade Organization (WTO) principles in the Technical Barriers to Trade (TBT), see www.iso.org/iso/foreword.html.

This document was prepared by Technical Committee ISO/TC 14, *Shafts for machinery and accessories*.

This second edition cancels and replaces the first edition (ISO 4156-3:2005), which has been technically revised.

The main changes compared to the previous edition includes:

- ISO/R 1938-1 has been removed from [Clause 2](#);
- ISO 268-1 and ISO 1328 (all parts) have been moved from [Clause 2](#) to Bibliography;
- symbols of length and arc length between two points, according to ISO 80000-3, have been adopted and used in the formulae;
- in [Figure 9](#), ball or pin contact diameter, internal spline has been added;
- in [Figure 12](#), measurement W , indication of base pitch, circular base thickness, and base diameter have been corrected;
- Table [10](#) has been revised;
- in [Figure 16](#), measurement of value A has been corrected;
- [Formula \(A.3\)](#) has been corrected;
- calculation results B_1 and E_r in [A.3](#) have been corrected;
- in [Figure A.2](#), the figure and subfigure titles have been corrected.

A list of all parts in the ISO 4156 series can be found on the ISO website.

Any feedback or questions on this document should be directed to the user's national standards body. A complete listing of these bodies can be found at www.iso.org/members.html.

Introduction

ISO 4156 (all parts) provides the data and indications necessary for the design, manufacture and inspection of straight (non-helical) side-fitting cylindrical involute splines.

Straight cylindrical involute splines manufactured in accordance with ISO 4156 (all parts) are used for clearance, sliding and interference connections of shafts and hubs. They contain all the necessary characteristics for the assembly, transmission of torque, and economic production.

The nominal pressure angles are 30° , $37,5^\circ$ and 45° . For electronic data processing purposes, the form of expression $37,5^\circ$ has been adopted instead of $37^\circ30'$. ISO 4156 (all parts) establishes a specification based on the following modules:

— for pressure angles of 30° and $37,5^\circ$ the module increments are:

0,5; 0,75; 1; 1,25; 1,5; 1,75; 2; 2,5; 3; 4; 5; 6; 8; 10;

— for pressure angle of 45° the module increments are:

0,25; 0,5; 0,75; 1; 1,25; 1,5; 1,75; 2; 2,5.

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Straight cylindrical involute splines — Metric module, side fit —

Part 3: Inspection

1 Scope

This document provides data, guidance and requirements for the inspection of straight (non-helical) side fitting cylindrical involute splines.

Limiting dimensions, tolerances, manufacturing deviations and their effects on the fit between connecting coaxial spline elements are defined and tabulated. Linear dimensions are expressed in millimetres and angular dimensions in degrees.

2 Normative references

The following documents are referred to in the text in such a way that some or all of their content constitutes requirements of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3, *Preferred numbers — Series of preferred numbers*

ISO 1101, *Geometrical product specifications (GPS) — Geometrical tolerancing — Tolerances of form, orientation, location and run-out*

ISO 1938-1, *Geometrical product specifications (GPS) — Dimensional measuring equipment — Part 1: Plain limit gauges of linear size*

ISO 4156-1, *Straight cylindrical involute splines — Metric module, side fit — Part 1: Generalities*

ISO 4156-2, *Straight cylindrical involute splines — Metric module, side fit — Part 2: Dimensions*

ISO 5459, *Geometrical product specifications (GPS) — Geometrical tolerancing — Datums and datum systems*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 4156-1 apply.

ISO and IEC maintain terminological databases for use in standardization at the following addresses:

- ISO Online browsing platform: available at <https://www.iso.org/obp>
- IEC Electropedia: available at <http://www.electropedia.org/>

4 Symbols and abbreviated terms

NOTE Some of the symbols used can have a meaning other than the one intended here. The symbols H, Z, Y and W are common for gauge tolerances in other ISO standards and can seem to conflict with symbols used in this document. However, it was not thought necessary to distinguish between them, since the context will always preclude any ambiguity.

a_{allowed}	Limited maximum value of distance out of the actual tolerance limit	μm
D	Pitch diameter	mm
D_{b}	Base diameter	mm
D_{ee}	Major diameter, external spline	mm
$D_{\text{ee max}}$	Maximum major diameter, external spline	mm
$D_{\text{ee min}}$	Minimum major diameter, external spline	mm
$D_{\text{Fe max}}$	Maximum form diameter, external spline	mm
$D_{\text{Fi min}}$	Minimum form diameter, internal spline	mm
D_{ii}	Minor diameter, internal spline	mm
$D_{\text{ii min}}$	Minimum minor diameter, internal spline	mm
D_{Re}	Diameter of measuring ball or pin for external spline	mm
D_{Ri}	Diameter of measuring ball or pin for internal spline	mm
d_{ce}	Ball or pin contact diameter, external spline	mm
d_{ci}	Ball or pin contact diameter, internal spline	mm
E	Basic space width, circular	mm
E_{max}	Maximum actual space width	mm
E_{min}	Minimum actual space width	mm
E_{r}	Eccentric radial offset	mm
E_{v}	Effective space width, circular	mm
$E_{\text{v max}}$	Maximum effective space width	mm
$E_{\text{v min}}$	Minimum effective space width	mm
F_{p}	Total pitch deviation	μm
F_{α}	Total profile deviation	μm
F_{β}	Total helix deviation	μm
i	Integer defining the tooth considered and has values 0, 1, 2, ..., z-1 (as used in Annex A)	—
$\text{inv } \alpha$	Involute $\alpha (= \tan \alpha - \pi \cdot \alpha / 180^\circ)$	—
K_{e}	Approximation factor for external spline	—
K_{i}	Approximation factor for internal spline	—
k	Number of measured teeth	—
L_{STA}	Statistical tolerance limit actual	$\mu\text{m}, \%$

$L_{STA \text{ absolute}}$	Statistical tolerance limit actual absolute	$\mu\text{m}, \%$
$L_{STA \text{ relative}}$	Statistical tolerance limit actual relative	$\%$
l_{BA}	Length between two points (e.g. point B and point A)	mm
M_{Re}	Measurement over two balls or pins, external splines	mm
M_{Ri}	Measurement between two balls or pins, internal	mm
m	Module	mm
n_{allowed}	Maximum allowed number of measured sizes outside tolerance limit	—
p_b	Base pitch	mm
S	Basic tooth thickness, circular	mm
S_{max}	Maximum actual tooth thickness	mm
S_{min}	Minimum actual tooth thickness	mm
S_b	Circular base thickness	mm
$S_{v \text{ max}}$	Maximum effective tooth thickness	mm
$S_{v \text{ min}}$	Minimum effective tooth thickness	mm
s_{DE}	Arc length between two points (e.g. point D and point E)	mm
T	Machining tolerance	μm
T_v	Effective clearance tolerance	μm
W	Measurement over k teeth, external spline	mm
z	Number of teeth	—
α	Pressure angle	$^\circ$
α_{ce}	Pressure angle at ball or pin diameter, external spline	$^\circ$
α_{ci}	Pressure angle at ball or pin diameter, internal spline	$^\circ$
α_D	Standard pressure angle at pitch diameter	$^\circ$
α_e	Pressure angle at ball or pin centre, external spline	$^\circ$
α_i	Pressure angle at ball or pin centre, internal spline	$^\circ$
Δ_{safety}	Safety recommendation value	mm
λ	Deviation allowance	μm
τ	Angular pitch	$^\circ$
ψ	Phase angle	$^\circ$

5 Reference conditions

The standard reference temperature for industrial length measurements is 20 °C. The dimensional requirements for parts and gauges are defined at that temperature and inspection shall also normally be carried out at that same temperature.

If measurements are taken at another temperature, the results shall be corrected using the expansion coefficients of parts and gauges respectively.

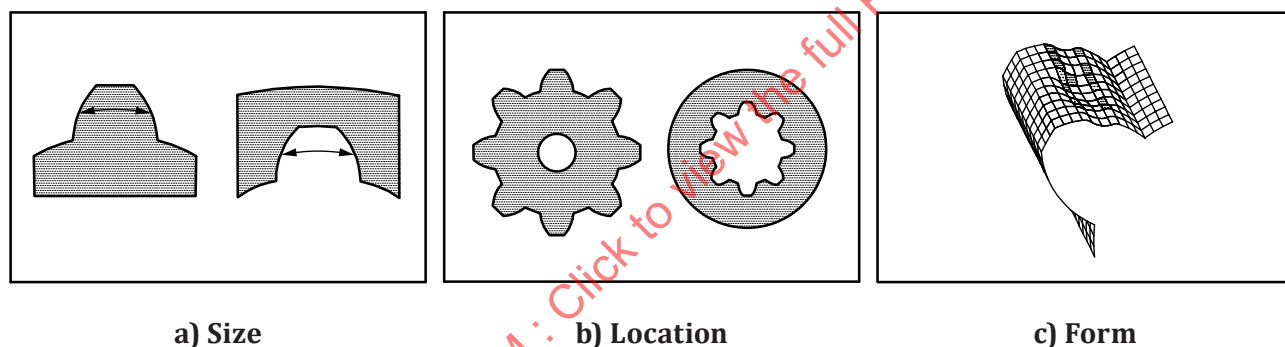
Unless otherwise specified, all measurements shall be made under zero measuring load.

If measurements are made under a non-zero load, the results shall be corrected accordingly. However, such correction is not required for comparison measurements made with the same comparison means and under the same measuring load, between similar components of the same material and with the same surface condition.

6 Quality features

6.1 General

The inspection of splines is divided into three quality features, as shown in [Figure 1](#). To specify the location ISO 1101 and ISO 5459 shall be used. For form and size ISO 4156-1 and ISO 4156-2 apply.



NOTE 1 Size can be a quality feature (actual, effective).

NOTE 2 Location can be a quality feature (runout, coaxiality, perpendicularity).

NOTE 3 Form can be a quality feature (profile, helix, pitch).

Figure 1 — Quality features

6.2 Size

6.2.1 Actual size

The actual size is

- a) for external splines, the circular tooth thickness at the pitch diameter, and
- b) for internal splines, the circular space width at the pitch diameter.

6.2.2 Effective size

The effective tooth thickness or space width is the maximum material condition resulting from the actual size and the accumulation of form deviations.

6.3 Location

The location of a spline is the location of the central axis in relation to any other geometrical element found by actual or effective inspection methods.

6.4 Form

The form deviations of a spline are the deviations to the true geometrical form of profile, helix and pitch.

7 Methods of inspection

7.1 Size

7.1.1 General methods

Three general methods of inspection are provided in [Table 1](#). If not otherwise specified, the standard method shall be used. If the alternative methods A or B are required, this shall be stated in the part data table. For the consequence of general methods, see [Table 2](#).

Table 1 — Relationship between parameters and control method

	Minimum material	Minimum effective clearance	Maximum effective clearance
Parameter	$S_{\min}/E_{\max}$	$S_{v\max}/E_{v\min}$	$S_{v\min}/E_{v\max}$
Standard method	X	X	—
Method A	X	X	X
Method B	—	X	X

Table 2 — Consequence of general methods

Inspection method	Theoretical maximum clearance between mating parts (zero form deviation)	Maximum deviation of form in each part (zero clearance)
Standard	$2(T + \lambda)$	$T + \lambda$
Alternative A	$2T_v$	$T + \lambda$
Alternative B	$2T_v$	Undetermined

NOTE The theoretical maximum clearance between mating parts in this table is for parts in their new condition. The clearance increases when wear occurs.

7.1.2 Choice of measuring instrument

The choice of measuring instrument shall be made according to the design requirements (see ISO 4156-1). See [Table 3](#) and [Figure 2](#).

7.1.3 Actual size

7.1.3.1 Dimensions over and between balls

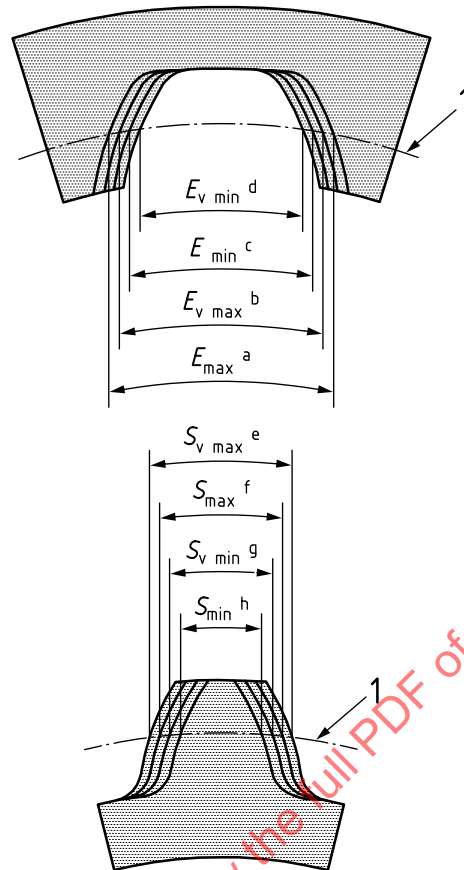
The dimension over or between balls facilitates the calculation of the theoretical actual circular tooth thickness or space width at the pitch circle diameter based on the actual tooth thickness or space width where the balls contact through one normal plane. The size measured over or between balls is a true size at 2 particular gaps and in one particular plane.

7.1.3.2 Dimensions over and between pins

The dimension over or between pins facilitates the calculation of the theoretical actual circular tooth thickness or space width at the pitch circle diameter based on the actual tooth thickness or space width where the pins have a line contact.

Table 3 — Size Inspection measuring instruments, methods and priorities

Priority	Parameter			
	$S_{\min}/E_{\max}$	$S_{v\max}/E_{v\min}$	$S_{v\min}/E_{v\max}$	$S_{\max}/E_{\min}$
	Method			
Highest	Measurement over and between balls	GO composite gauge	NO GO composite gauge	Measurement over and between balls
Lower ↓	Measurement over and between pins NO GO sector gauge Variable sector gauge Span size	Variable composite gauge Analysis calculations using size and form deviations	Variable composite gauge	Measurement over and between pins Variable sector gauge



Key

- 1 pitch circle
- a NO GO sector plug gauge or maximum measurement between balls or pins.
- b NO GO composite plug gauge.
- c Minimum measurement between balls or pins, auxiliary.
- d GO composite plug gauge.
- e GO composite ring gauge.
- f Maximum measurement over balls or pins, auxiliary.
- g NO GO composite ring gauge.
- h NO GO sector ring gauge or minimum measurement over balls or pins.

Figure 2 — Elementary inspection methods for space widths and tooth thicknesses

7.1.3.3 NO GO sector gauge

The NO GO sector gauge is used to inspect the specified actual tolerance limit of the circular tooth thickness or space width at the minimum material condition of the part, where the gauge contacts only at the ends.

7.1.3.4 Span size over k teeth

The span measurement facilitates the calculation of the theoretical actual circular tooth thickness of external splines at the pitch circle diameter based on the measurement over a block of teeth. Before using this method, suitability should be checked.

7.1.3.5 Variable sector gauge

The variable sector gauge measures the actual circular tooth thickness or space width. The actual measurement is achieved using radially locking left- and right-hand flanks and comparison to a master having a known tooth thickness or space width.

7.1.4 Effective size

7.1.4.1 GO composite gauge

GO composite gauges are used to check

- a) that the specified effective limits of tooth thickness or space width are not exceeded at the maximum material condition of the part,
- b) the specified form diameter of the part, thus ensuring that the required tolerances are controlled for the full involute depth, and
- c) the specified length of engagement, thus ensuring that the spline maximum material limit has not been exceeded.

7.1.4.2 Variable composite gauge

The variable composite gauge measures the effective size of tooth thickness or space width. The actual measurement is achieved using the radially locking left- and right-hand flanks and comparison to a master having a known tooth thickness or space width.

7.1.4.3 NO GO composite gauge

The NO GO composite gauge is used to check the specified effective limit of minimum tooth thickness or maximum space width, where the gauge contacts only at the ends.

7.1.4.4 Inspection of diameter at tooth tip (D_{ii} or D_{ee})

All these inspection methods require measuring the tooth tip (internal minor diameter, D_{ii} , or external major diameter, D_{ee}) using GO and NO GO plain (plug or ring) gauges or other acceptable measuring devices.

7.2 Location

7.2.1 General

Splines have an actual and effective true size of space width or tooth thickness, and hence also an actual and effective axis.

The tolerances concerning location (i.e. runout, total runout, concentricity, and coaxiality tolerances) shall be specified on the component drawing. Where the spline is used as a datum axis, other geometry features shall be toleranced to the spline axis. Because of the inherent form deviations, difficulties arise in the reproducibility and repeatability of the spline profile if the form deviations and cylindricity deviations are numerous.

7.2.2 Choice of the method of inspection of location

The methods of inspection of location are given in [Table 4](#).

Table 4 — Location inspection methods and priorities

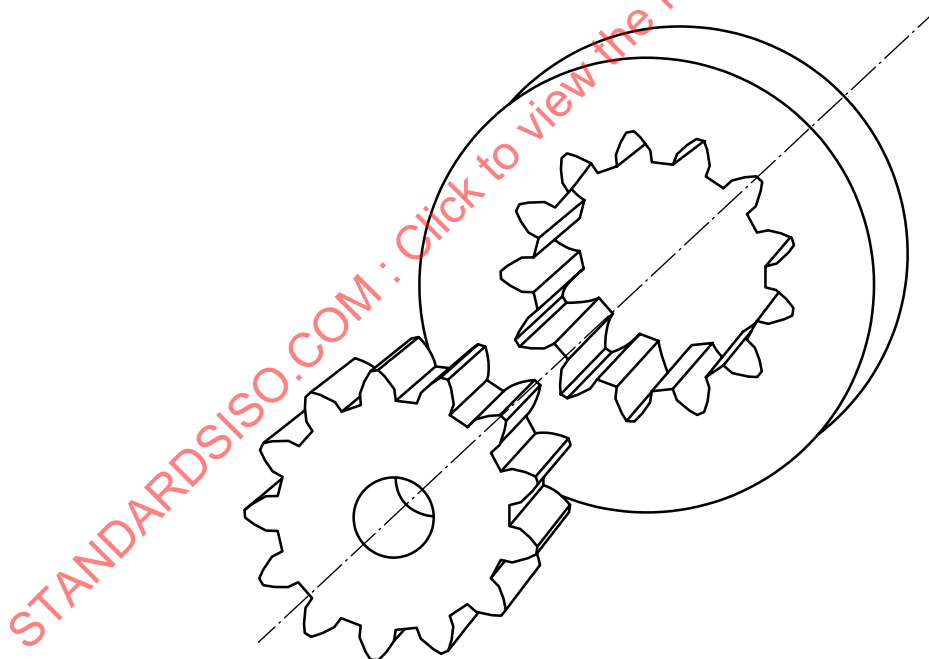
Priority	Method
Highest	Effective axis using perfectly fitting mating part without form deviations
Lower ↓	Actual pitch cylinder axis Calculation with Fourier analysis Spline clamping systems

7.2.3 Effective axis using mating part

The location of the effective spline axis is defined by the axis of a perfect (without form deviations) mating spline fitting without clearance or looseness. As this is difficult in practice, spline clamping systems or mathematic calculation methods using the individual form deviations derived from analytical inspection may be used.

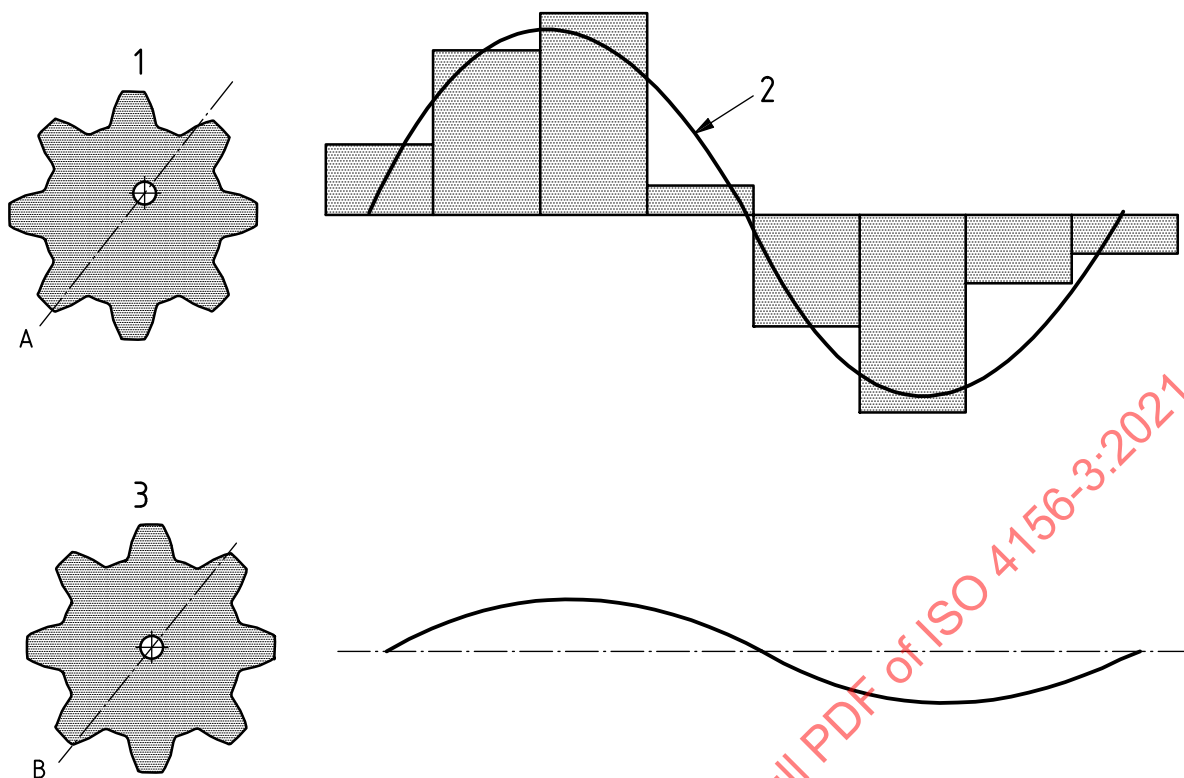
7.2.4 Actual pitch cylinder axis

The location of the actual spline axis (see [Figure 3](#)) is defined by the mean centre line of all measured points on the tooth flanks. This axis represents the position at which all deviations are minimum (least-square condition).

**Figure 3 — Actual spline axis**

7.2.5 Calculation with Fourier analysis

This can be carried out by the measurement and analysis of pitch deviation, profile deviation and helix deviation. This axis found by this method (see [Figure 4](#)) represents the axis where pitch, profile and helix deviations have their smallest values.

**Key**

- 1 pitch deviations to axis A
- 2 found by Fourier analysis
- 3 pitch deviations to axis B with minimum value

Figure 4 — Axis found by Fourier analysis of pitch deviation

7.2.6 Spline clamping system

In practice it is very difficult to manufacture a perfect (without form deviations) mating spline that fits without looseness or clearance. As an alternative, a splined clamping system can be used. These clamp the parts on the tooth flanks. A variety of different systems are available, but they are a compromise in comparison to the perfect mating spline.

7.3 Form

A more comprehensive explanation of form deviations exists in ISO 1328 (all parts) and ISO/TR 10064-1. The datum for form deviations is the effective pitch cylinder.

8 Measurements with balls or pins

8.1 General

The theoretical actual space width or tooth thickness can be calculated from the measurement over or between balls or pins.

The concepts in [8.2](#) to [8.6](#) and [Formulae \(1\) to \(28\)](#) apply when using ball or pins.

8.2 Selection of balls or pins

A ball or pin diameter shall be selected from the preferred number series R40 from ISO 3. Ideally, the ball or pin should contact the pitch diameter when the tooth or space is equal to S or E .

In practice it can be necessary to round the ball or pin diameter to the next greater value in the series.

In cases where it is not possible to select a size of pin or ball from ISO 4156-2, the size chosen shall satisfy the conditions of contact required for satisfactory measurements. The size to be used shall be subject to prior agreement between purchaser and manufacturer.

In some cases, it will be necessary to make a flat on the pin or ball to avoid contact on the major diameter of an internal spline or minor diameter of an external spline.

The difference in geometry of measuring balls and pins influences the measuring results. Surface finish and helix deviations also have an effect.

Ball and pin accuracies are given in [Table 5](#) with the length of the pin as a function of pin diameter.

Table 5 — Ball and pin accuracies and pin measuring length

Values in millimetres

Nominal diameter of balls or pins (D_{Ri} or D_{Re})	Tolerances on diameter (including all divisions)	Pin length
$0,3 \leq D_{Ri} \text{ or } D_{Re} \leq 1$	$\pm 0,001$	20 ± 5
$1 < D_{Ri} \text{ or } D_{Re} \leq 5$	$\pm 0,001$	30 ± 5
$5 < D_{Ri} \text{ or } D_{Re} \leq 15$	$\pm 0,001\ 5$	40 ± 5
$15 < D_{Ri} \text{ or } D_{Re} \leq 26$	$\pm 0,001\ 5$	50 ± 5
$D_{Ri} \text{ or } D_{Re} \geq 26$	$\pm 0,002$	60 ± 5

8.3 Use and marking of pins

Pins shall be usable over their whole length in any area of the spline length to be checked.

They shall be marked with their nominal diameter.

8.4 Statistical actual tolerance limit L_{STA}

8.4.1 General

A number of unavoidable uncertainties exist in the inspection of the actual size of splines. The inspection result will be influenced by

- the angular position,
- the measuring plane, and
- the inspection method.

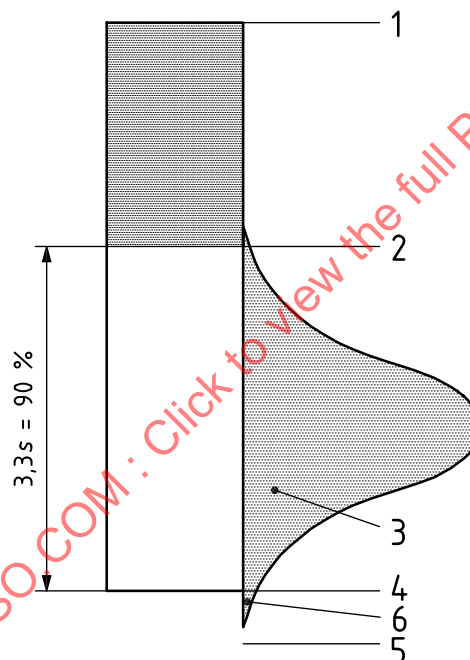
These three items influence the measurement results and reduce repeatability. If not otherwise agreed by the customer and the manufacturer, the priority shall be established as follows:

All methods of inspection may be used to measure the actual size, but in case of disagreement, the measurement between or over balls shall have the highest priority in the acceptance or rejection of a part. The actual size shall be inspected in at least three equally spaced angular positions and in at least three equally spaced measuring planes. In the case of disagreement between measuring results from the same measuring method, the result which has utilised the greatest number of angular and longitudinal measuring positions shall have priority.

If measurements with a high number of measuring points are used, a statistical distribution of all measured true actual sizes at any position will exist. In theory, all local true actual sizes measured at any position shall be within the actual tolerance limit. The statistical analysis of the actual tolerance limit uses two L_{STA} (statistical tolerance analysis) tolerance limits and enables a decision to be made as to whether a part is to be accepted or rejected with regard to the actual tolerance limit. This document allows the use of the statistical actual tolerance limit L_{STA} (see Figure 5).

The statistical actual tolerance limit L_{STA} defines 2 limits:

- a) L_{STA} relative
 - Number of local individual true actual sizes allowed to be outside the actual tolerance limit;
 - Given in % of all measured sizes.
- b) L_{STA} absolute
 - Maximum value of local individual true sizes to be allowed outside the tolerance limit.
 - Given in micrometers or as a percentage of the actual tolerance value.



Key

- 1 maximum effective tolerance limit
- 2 reference mark, maximum, actual, auxiliary
- 3 distribution of measured sizes within one part
- 4 minimum actual tolerance limit
- 5 L_{STA} absolute
- 6 L_{STA} relative

Figure 5 — Statistical actual tolerance limit L_{STA}

8.4.2 Acceptance of parts according to the statistical actual tolerance limit L_{STA}

The arithmetic average of all local sizes as well as compensated circles or cylinders shall always be inside the actual tolerance limit. The statistical tolerance limit actual shall only be used for local individual true sizes, and not for their average or their substituted elements. A limited number of individual true sizes may be allowed to be outside the actual tolerance limit by a limited amount.

The maximum number (n_{allowed}) of measured sizes allowed to be outside the tolerance limit is calculated from the number of measured sizes n and the percentage given by $L_{\text{STA relative}}$:

$$n_{\text{allowed}} = \text{int} \cdot (n \cdot L_{\text{STA relative}}) \quad (1)$$

The number of measured sizes shall be large enough for the L_{STA} to function with regard to n_{allowed} .

The maximum value allowed out of the actual tolerance limit allowed can be calculated by the percentage of the L_{STA} where $L_{\text{STA absolute}} = L_{\text{STA relative}}$ and the actual tolerance T :

$$a_{\text{allowed}} = T \cdot L_{\text{STA absolute}} \quad (2)$$

If it does not fit the requirements equal to $L_{\text{STA relative}} = L_{\text{STA absolute}}$, the $L_{\text{STA absolute}}$ value may be given separately in micrometers.

8.4.3 Examples

EXAMPLE 1

L_{STA} :	10 %	$= L_{\text{STA relative}}$ $= L_{\text{STA absolute}}$
Number of measured values:	85	
$n_{\text{allowed}} =$	$\text{int} (n \cdot L_{\text{STA relative}})$	$\text{int} (85 \cdot 10 / 100) = 8$
Tolerance $T = 0,035$		
$a_{\text{allowed}} =$	$T \cdot L_{\text{STA absolute}}$	$0,035 \cdot 10 / 100 = 0,003 \text{ 5}$

Maximum 8 measured values out of 85 may be out of the actual tolerance limit by maximum 0,003 5 mm and the component still shall be accepted.

EXAMPLE 2

$L_{\text{STA relative}}$	15 %	
$L_{\text{STA absolute}}$	0,005 mm	
number of measured values	28	
$n_{\text{allowed}} =$	$\text{int} (n \cdot L_{\text{STA relative}})$	$\text{int} (28 \cdot 15 / 100) = 4$

Maximum 4 measured values out of 28 may be out of the actual tolerance limit by maximum 0,005 mm and the component still shall be accepted.

8.5 Calculation of ball or pin diameter (D_{Re} or D_{Ri})

8.5.1 External spline

See [Figure 6](#).

S is the basic tooth thickness.

$$s_{\text{DE e}} = p_b - (S \cdot \cos \alpha_D + D_b \cdot \text{inv} \alpha_D) \quad (3)$$

$$l_{BA} = \frac{D_b \cdot \tan \alpha_D}{2} \quad (4)$$

$$l_{BO e} = \frac{D_b \cdot \tan \left(\alpha_D + \text{inv} \alpha_D + \frac{s_{DE e}}{D_b} \right)}{2} \quad (5)$$

$$\text{Calculated } D_{Re} = 2(l_{BO e} - l_{BA}) \quad (6)$$

Take D_{Re} as the next greater nominal diameter in the preferred number series R40 from ISO 3.

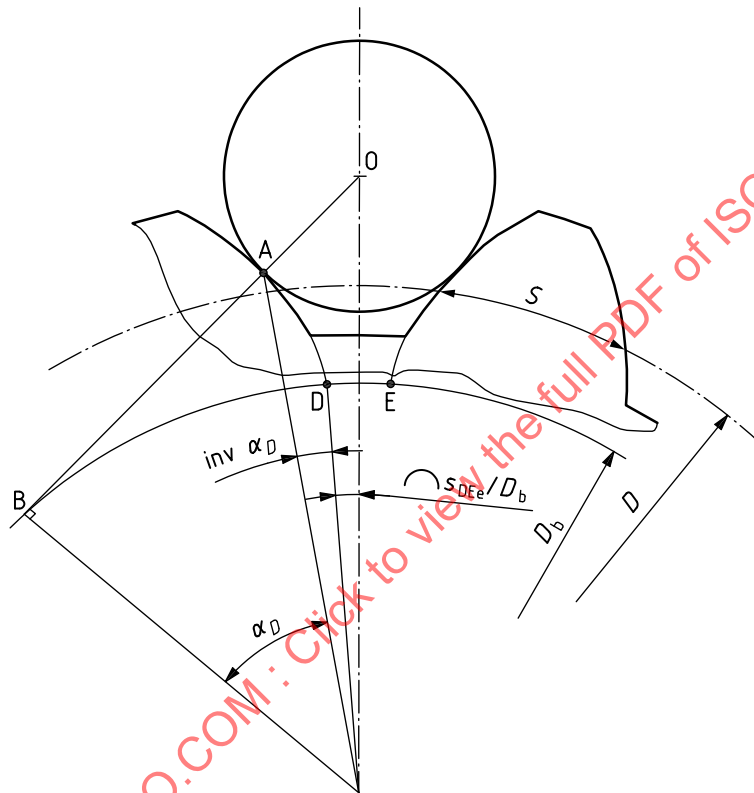


Figure 6 — External spline

8.5.2 Internal spline

See [Figure 7](#).

The following calculation should not be used for internal splines with 30° pressure angle and a number of teeth less than 8. For these splines, use a value of E equal to the minimum actual space width of the tolerance required.

E is the basic space width.

$$s_{DE i} = E \cdot \cos \alpha_D + D_b \cdot \text{inv} \alpha_D \quad (7)$$

$$l_{BA} = \frac{D_b \cdot \tan \alpha_D}{2} \quad (8)$$

$$l_{BOi} = \frac{D_b \cdot \tan \left(\alpha_D + \text{inv} \alpha_D + \frac{s_{DEi}}{D_b} \right)}{2} \quad (9)$$

$$\text{Calculated } D_{Ri} = 2(l_{BA} - l_{BOi}) \quad (10)$$

Take D_{Ri} as the next greater nominal diameter in the preferred number series R40 from ISO 3.

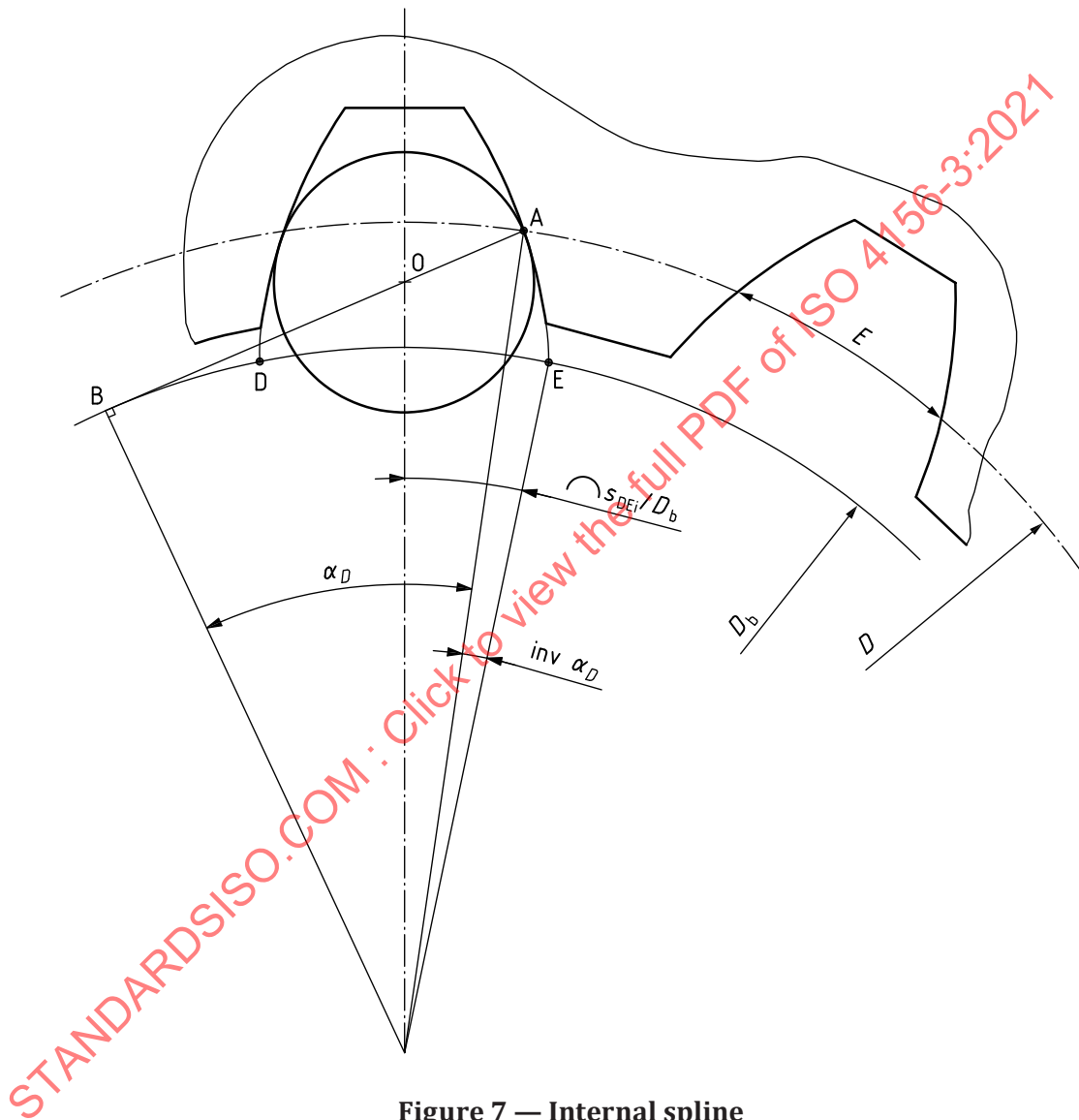


Figure 7 — Internal spline

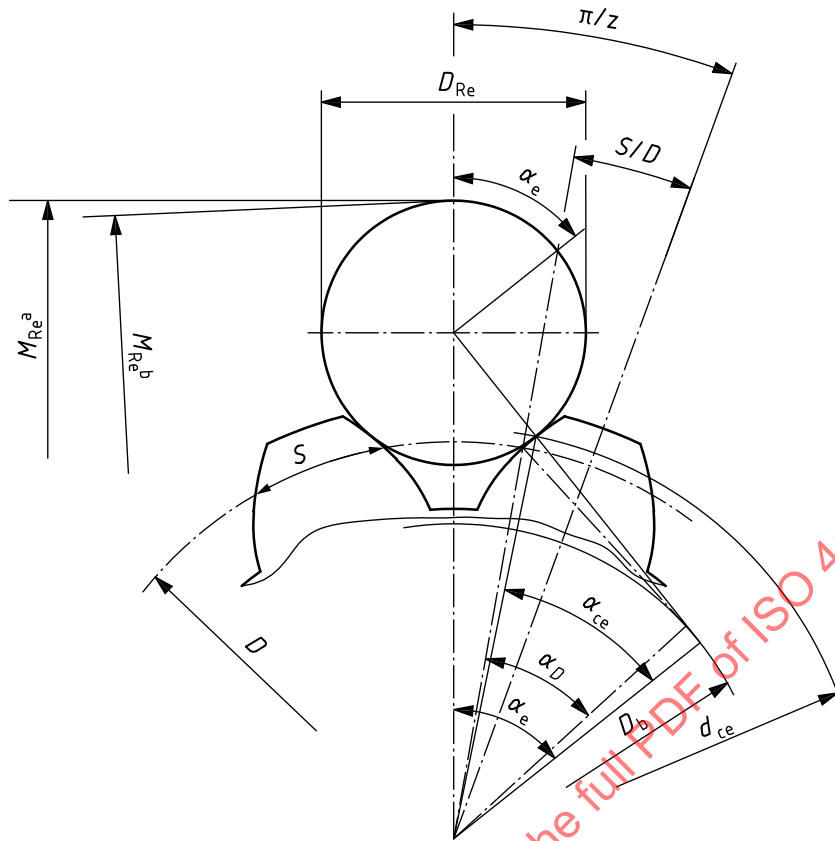
8.6 Calculation of dimensions for ball or pin inspection (part and gauge inspection)

8.6.1 Exact calculation

8.6.1.1 Measurement over two balls or pins — External splines (M_{Re})

See [Figure 8](#).

S is the actual circular tooth thickness to be checked.



- a For z even.
b For z odd.

Figure 8 — Measurement over balls or pins

D_{Re} is the pin diameter — see value in inspection dimension tables.

$$\text{inv} \alpha_e = \frac{S}{D} + \left(\text{inv} \alpha_D + \frac{D_{Re}}{D_b} \frac{\pi}{z} \right) \quad (11)$$

give α_e in degrees, to 5 decimal places¹⁾

For z even:

$$M_{Re} = \frac{D_b}{\cos \alpha_e} + D_{Re} \quad (12)$$

1) Decimal degrees, for use with computers.

For z odd:

$$M_{Re} = \frac{D_b \cdot \cos \frac{90^\circ}{z}}{\cos \alpha_e} + D_{Re} \quad (13)$$

$$\tan \alpha_{ce} = \tan \alpha_e - \frac{D_{Re}}{D_b} \quad (14)$$

$$d_{ce} = \frac{D_b}{\cos \alpha_{ce}} \quad (15)$$

8.6.1.2 Measurement between two pins — Internal splines (M_{Ri})

See [Figure 9](#).

E is the actual circular space width to be checked.

D_{Ri} is the pin diameter — see value in inspection dimension tables.

$$\text{inv} \alpha_i = \frac{E}{D} + \left(\text{inv} \alpha_D - \frac{D_{Ri}}{D_b} \right) \quad (16)$$

give α_i in degrees, to five decimal places²⁾

For z even:

$$M_{Ri} = \frac{D_b}{\cos \alpha_i} - D_{Ri} \quad (17)$$

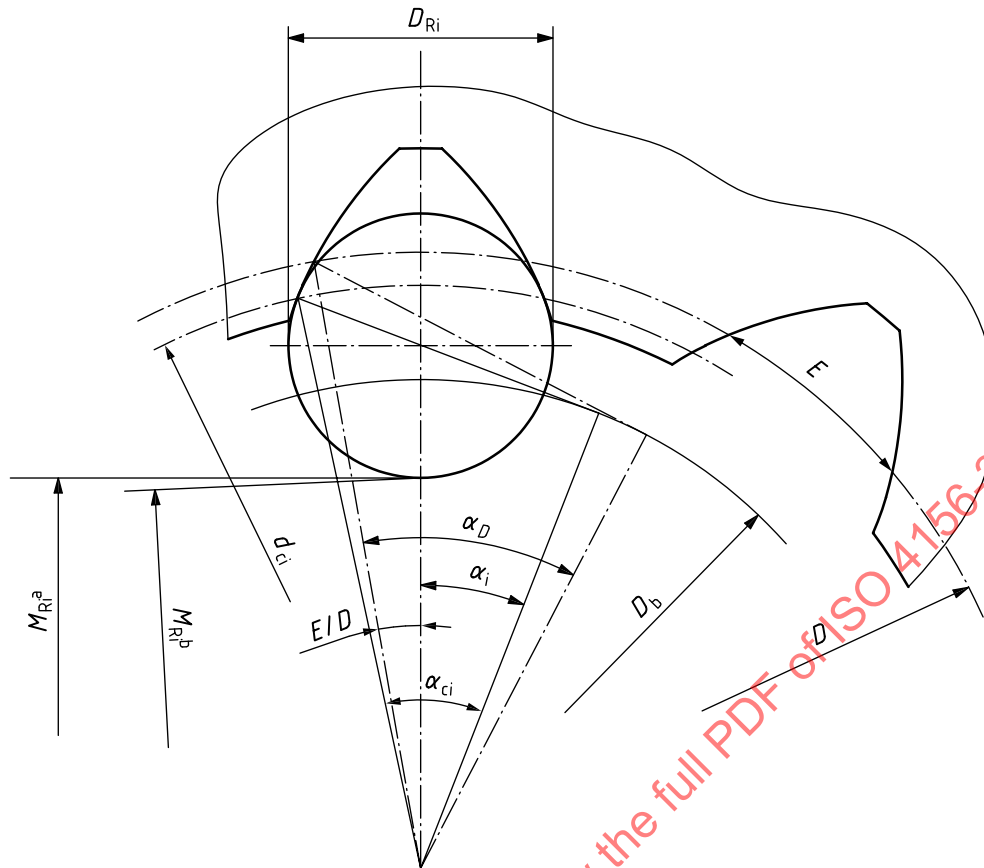
For z odd:

$$M_{Ri} = \frac{D_b \cdot \cos \frac{90^\circ}{z}}{\cos \alpha_i} - D_{Ri} \quad (18)$$

$$\tan \alpha_{ci} = \tan \alpha_i + \frac{D_{Ri}}{D_b} \quad (19)$$

$$d_{ci} = \frac{D_b}{\cos \alpha_{ci}} \quad (20)$$

2) Decimal degrees, for use with computers.



- a For z even.
- b For z odd.

Figure 9 — Measurement between balls or pins

8.6.2 Approximation factor

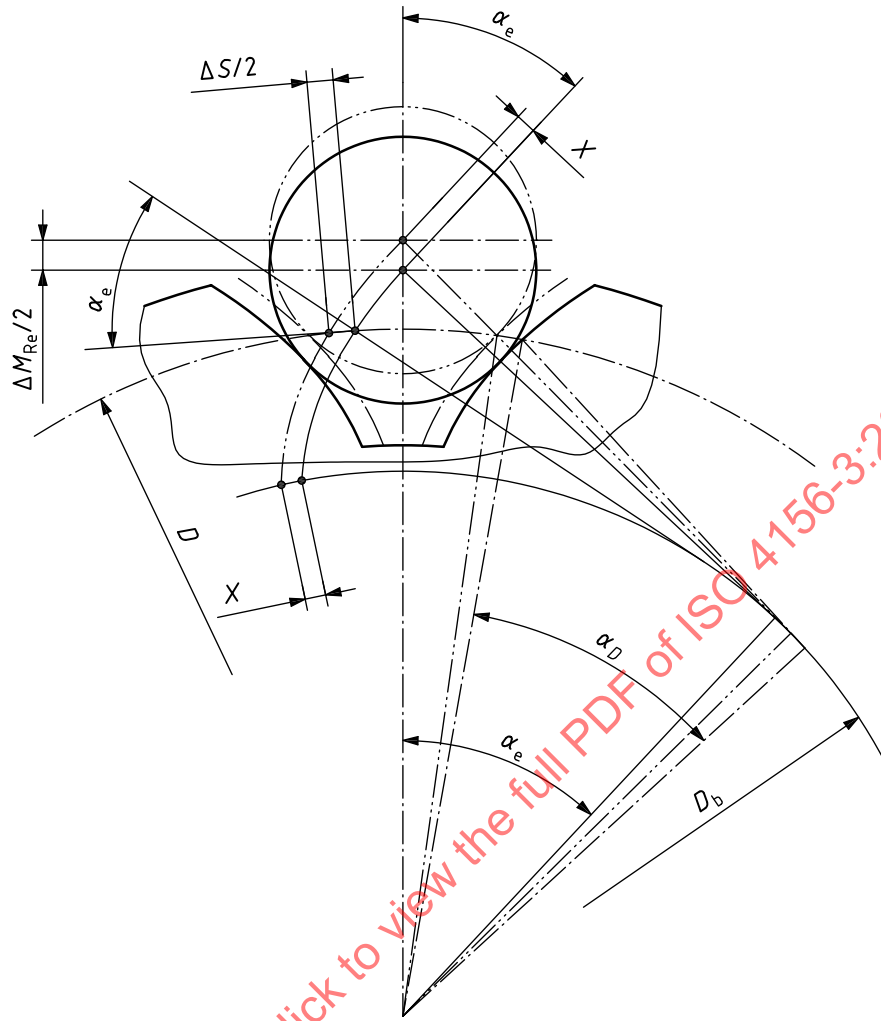
8.6.2.1 General

The approximation factor (K_e for external splines, K_i for internal splines) is the variation of inspection dimensions with respect to the variation of corresponding tooth thicknesses or space widths (see ISO 4156-1).

The use of factors K_e or K_i leads the values of inspection dimensions, which are all the more accurate since the thickness or space width to be checked are closer to the actual thickness values ($S_{\min}$) or the maximum actual space width values ($E_{\max}$) of tolerance class 7 of fit considered.

8.6.2.2 Calculation of the approximation factor K_e

The parameters for the calculation of the approximation factor K_e are shown in [Figure 10](#).

Figure 10 — Calculation of K_e

Approximate:

$$X = \frac{M_{Re}}{2} \sin \alpha_e \quad (21)$$

$$\frac{\Delta S}{2} = \frac{X}{\cos \alpha_D} = \frac{\Delta M_{Re} \sin \alpha_e}{2 \cos \alpha_D} \quad (22)$$

For an even number of teeth:

$$K_e = \frac{\Delta M_{Re}}{\Delta S} = \frac{\cos \alpha_D}{\sin \alpha_e} \quad (23)$$

For an odd number of teeth:

$$K_e = \frac{\cos \alpha_D}{\sin \alpha_e} \cos \frac{90^\circ}{z} \quad (24)$$

For the calculation of α_e , see 8.6.1.1 and take S as the minimum actual tooth thickness (S_{min}) of tolerance class 7 and fundamental deviation considered.

8.6.2.3 Calculation of the approximation factor K_i

The parameters for the calculation of the approximation factor K_i are shown in [Figure 11](#).

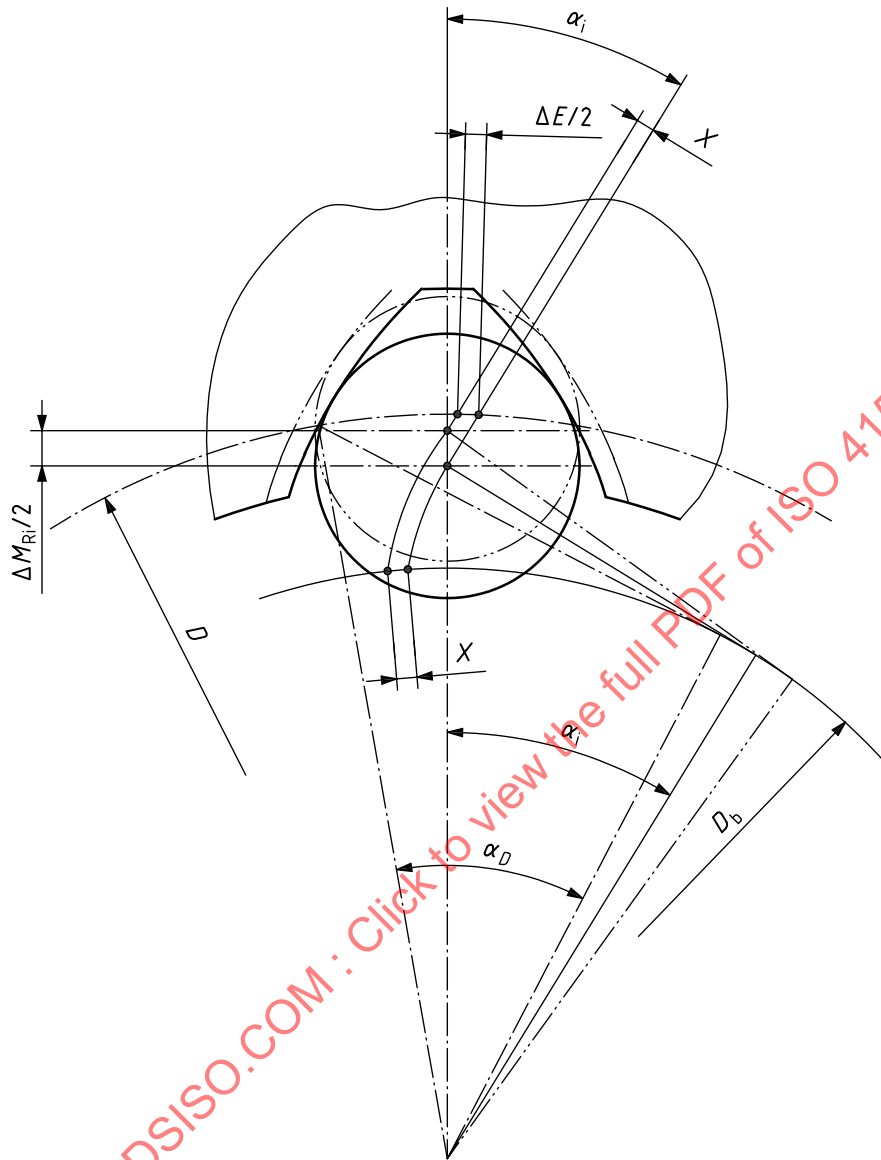


Figure 11 — Calculation of K_i

Approximate:

$$X = \frac{\Delta M_{Ri}}{2} \sin \alpha_i \quad (25)$$

$$\frac{\Delta E}{2} = \frac{X}{\cos \alpha_d} = \frac{\Delta M_{Ri} \cdot \sin \alpha_i}{2 \cdot \cos \alpha_D} \quad (26)$$

For an even number of teeth:

$$K_i = \frac{\Delta M_{Ri}}{\Delta E} = \frac{\cos \alpha_D}{\sin \alpha_i} \quad (27)$$

For an odd number of teeth:

$$K_1 = \frac{\cos \alpha_D}{\sin \alpha_i} \cdot \cos \frac{90^\circ}{z} \quad (28)$$

For the calculation of α_i , see 8.6.1.2 and take E as the basic space width.

9 Measurement over k teeth — External splines (W)

9.1 Calculation of W

The parameters for the calculation of W are shown in Figure 12.

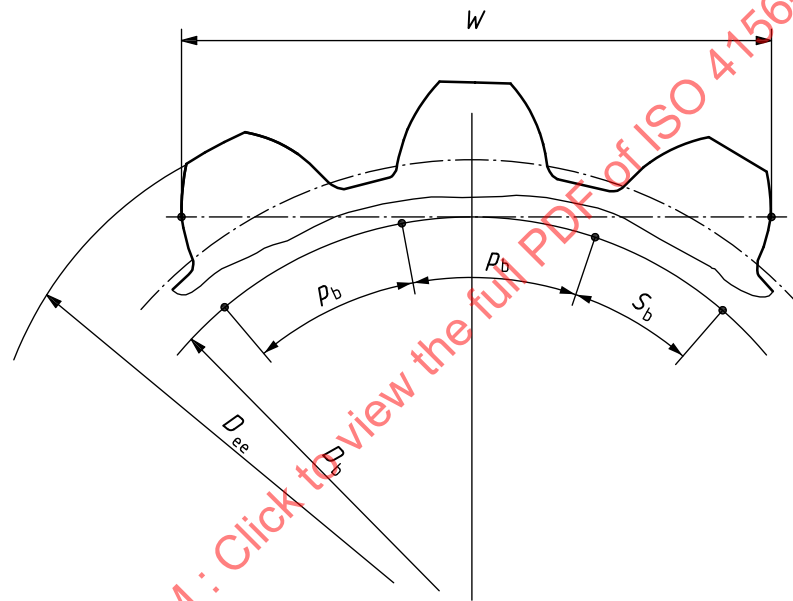


Figure 12 — Calculation of W

$$W = (k-1)p_b + S_b \quad (29)$$

where

k is the number of teeth considered (see inspection dimension tables);

p_b is the base pitch = $\pi \cdot m \cdot \cos \alpha_D$;

S_b is the circular base thickness = $S \cdot \cos \alpha_D + D_b \cdot \text{inv} \alpha_D$.

For the calculation of W , use S as the tooth thickness of the tolerance class chosen for the fit considered.

9.2 Choice of k

For the minimum and maximum tangential dimensions shown in Figures 13 and 14, respectively, the choice of the value of k depends on the following conditions.

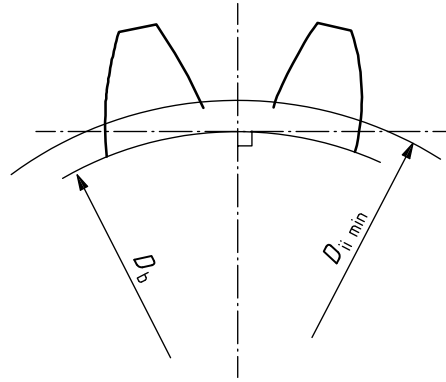


Figure 13 — Minimum tangential dimension

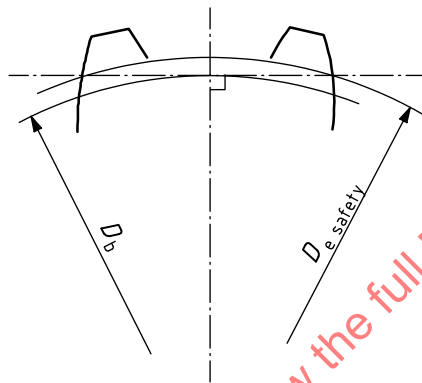


Figure 14 — Maximum tangential dimension

$$W_{\min} = \sqrt{D_{ii \min}^2 - D_b^2} \quad (30)$$

$$W_{\max} = \sqrt{D_{e \text{ safety}}^2 - D_b^2} \quad (31)$$

$$\begin{aligned} \Delta_{\text{safety}} &= 0,4 \cdot m \text{ for module } 0,25 \\ &= 0,3 \cdot m \text{ for module } 0,5 \text{ to } 4 \\ &= 0,2 \cdot m \text{ for module } 5 \text{ to } 10 \end{aligned}$$

$$D_{e \text{ safety}} = D_{ee \max} - \Delta_{\text{safety}}$$

$$\frac{W_{\max} - S_b}{p_b} = k_p \quad (32)$$

Check that $p_b \cdot k_p + S_b \geq W_{\min}$ and that $D_{ii \min} < \sqrt{W^2 + D_b^2} < D_{ee \max}$.

If these conditions are satisfied, then $k = k_p + 1$; otherwise, it is impossible to take a dimension over k teeth (k shall be rounded to the nearest integer number). For the calculation of k_p and $W_{\min}$, use S as the minimum actual thickness ($S_{\min}$) of tolerance class 7 of the tolerance considered.

10 Gauges

10.1 Generalities

10.1.1 Conditions of use of gauges

10.1.1.1 GO gauge

GO composite plug and ring gauges shall enter or pass over the complete spline length. Composite spline gauges shall be used without excessive force to prevent damage or distortion to the component or gauge. In case of disagreement, the composite gauge shall be accorded precedence in the acceptance or rejection of a part. If there are two gauges available and both are within the gauge tolerances, the gauge which fits the part shall be accorded precedence.

If a part is rejected by the composite GO gauge, the gauge itself cannot provide the reason. The reason can only be identified by the measurement of the actual tooth thickness or space width using pins or balls, and the analytical inspection of total pitch deviation, total profile deviation and total helix deviation.

10.1.1.2 NO GO sector gauge

NO GO gauges shall not enter or pass over the component in any angular position. Inspection shall be carried out in at least three angular positions as equally distributed as possible.

10.1.1.3 NO GO composite gauge

NO GO composite gauges shall not enter or pass over the component.

10.1.2 Limiting dimensions of use for gauges

The ease of use of gauges is limited by gauge weight and dimensions.

Parts with a pitch diameter $D \leq 180$ mm can normally be checked by using gauges.

Parts with a pitch diameter $D > 180$ mm can also be checked by using gauges if agreed between the customer and the supplier.

10.1.3 Handles of spline gauges

Plug gauges of pitch diameter $D < 50$ mm may be integral.

10.1.4 Number of teeth for sector NO GO gauges

The number of teeth on sector NO GO gauges is given in [Table 6](#).

Table 6 — Number of teeth on sector NO GO gauges

Total number of product teeth, z	$6 \leq z \leq 30$	$30 < z \leq 44$	$44 < z \leq 58$	$58 < z \leq 72$	$72 < z \leq 86$	$86 < z \leq 100$	$z > 100$
Number of teeth in each sector	2	3	4	5	6	7	$0,075z$

10.2 Length of measuring part of gauges

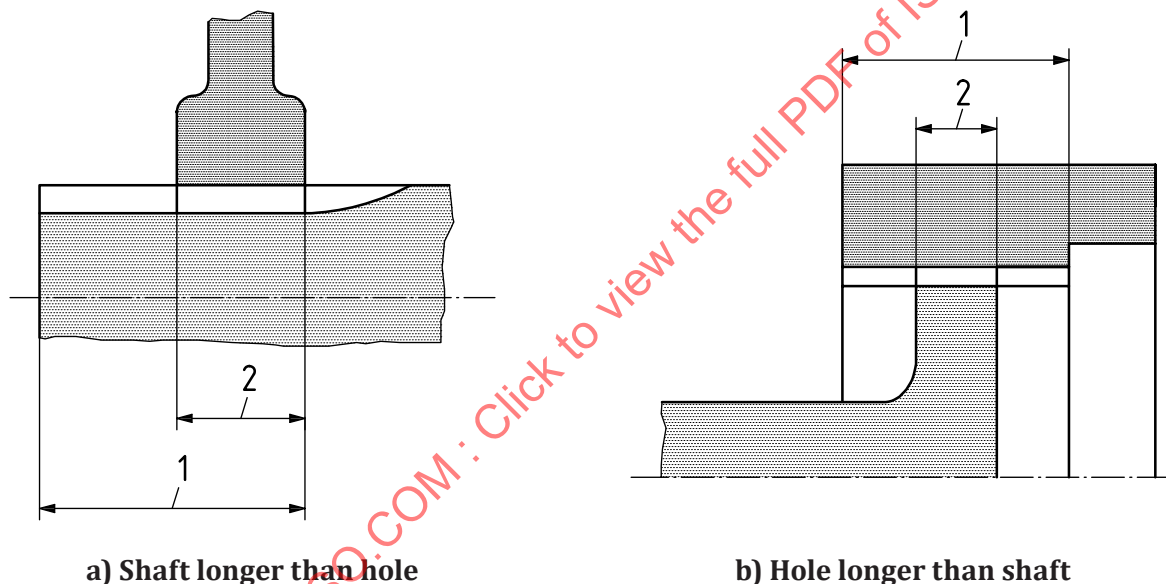
10.2.1 Influence of the active spline length and of the length of engagement

Since check gauges are often shorter than the parts to be checked, the active length and length of engagement (see [Figure 15](#)) can influence the maximum permissible alignment of splines (parallelism deviation of the splines with respect to the axis).

If the length of engagement is less than or equal to half the pitch diameter, and if the active length is equal to the length of engagement, alignment deviations of splines can generally, unless otherwise specified, be included in the total tolerances ($T + \lambda$) and checked simultaneously by limit gauges.

In the case where the length of engagement is greater than half the pitch diameter and the active length is greater than or equal to the length of engagement, it might be necessary to prescribe spline alignment tolerances independent of the total tolerance ($T + \lambda$): these tolerances may optionally be checked separately by analytical inspection.

In particular, if spline alignment tolerances are specified, they should generally be proportionally all the smaller since the active length or the length of engagement or both will be greater.



Key

- 1 length of engagement
- 2 active spline length

Figure 15 — Active length and length of engagement

10.2.2 GO or NO GO gauges

In the case where the length of engagement is greater than 1,5 times the value given in [Table 7](#), the active length of the GO composite splines plug or ring gauge should be increased. A gauge length of 75 % of the length of engagement is usually satisfactory. This shall be subject to prior agreement between purchaser and manufacturer.

NOTE GO and NO GO spline gauges can include a non-measuring part (plain cylindrical part or chamfer) intended for making gauge entrance easier.

Table 7 — Measuring part of spline gauges — Minimum length

Dimensions in millimetres

Pitch diameter D of splines	Minimum length of spline gauges			
	GO plug	NO GO plug	GO ring	NO GO ring
$1 \leq D \leq 7$	6	4	8	6
$7 < D \leq 12$	8	6	10	8
$12 < D \leq 17$	12	8	10	8
$17 < D \leq 22$	16	10	16	12
$22 < D \leq 30$	20	12	16	12
$30 < D \leq 40$	25	15	20	15
$40 < D \leq 50$	30	18	20	15
$50 < D \leq 70$	30	20	25	20
$70 < D \leq 120$	35	25	25	20
$120 < D \leq 150$	40	25	30	25
$150 < D \leq 180$	40	25	30	25

10.2.3 Master plug gauges

All of the following elements shall be taken into account in determining the length of the measuring part of the master plug gauges:

- a lead length corresponding to the minimum length of the measuring part of the checked ring;
- a checking length, function of the mating side taper of the master plug gauge and of the range of the dimensional tolerance of the checked ring;
- a wear length, function of the side taper of the master plug gauge and of the range of the wear tolerance of the checked ring.

10.2.4 Spline gauges of pitch diameters $D > 180$ mm

For spline gauges having a pitch diameter $D > 180$ mm it is advisable to choose a measuring length equal to

- 30 % of the pitch diameter for GO gauges;
- 20 % of the pitch diameter for NO GO gauges.

10.3 Manufacturing tolerances for spline gauges

The practical use and the relationship of manufacturing tolerances to wear tolerances have shown the necessity to slightly change the tolerances in this document in a way which does not affect the compatibility with gauges according to ISO 4156:1981. Wear tolerance limits for NO GO gauges having half of the wear allowance of GO gauges have been added to this document. See Tables 8, 9 and 10.

Table 8 — Gauge positions and tolerances

Calibre	Position	Tolerance	Wear limit
NO GO sector plug gauge	$E_{\max}$	$\pm H/2$	$E_{\max} - W$
NO GO composite plug gauge	$E_{v \max}$	$\pm H/2$	$E_{v \max} - W$
GO composite plug gauge	$E_{v \min} + Z$	$\pm H/2$	$E_{v \min} - Y$
GO composite ring gauge	$S_{v \max} - Z$	$\pm H/2$	$S_{v \max} + Y$
NO GO composite ring gauge	$S_{v \min}$	$\pm H/2$	$S_{v \min} + W$

Table 8 (continued)

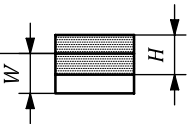
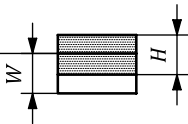
Calibre	Position	Tolerance	Wear limit
NO GO sector ring gauge	$S_{\min}$	$\pm H/2$	$S_{\min} + W$

Table 9 — Values of gauge tolerances

Pitch diameter D mm	Tol.	Plug gauges				Rings			
		Tooth thickness S mm				Space width E mm			
		$S \leq 3$	$3 < S \leq 6$	$6 < S \leq 10$	$10 < S \leq 18$	$E \leq 3$	$3 < E \leq 6$	$6 < E \leq 10$	$10 < E \leq 18$
		Tolerance values μm							
$D \leq 3$	H	2				2			
	Z	4				4			
	Y	1				1,5			
	W	3				3			
$3 < D \leq 10$	H	2,5				2,5			
	Z	4				4			
	Y	1,25				2			
	W	3				4			
$10 < D \leq 18$	H	3	3			3	3		
	Z	4	5			4	5		
	Y	1,5	1,5			2,5	2,5		
	W	4	4			4	5		
$18 < D \leq 30$	H	4	4	4		4	4	4	
	Z	4	5	6		4	5	6	
	Y	2	2	2		3	3	3	
	W	4	5	5		5	5	6	
$30 < D \leq 50$	H	4	4	4	4	4	4	4	4
	Z	4	5	6	8	4	5	6	8
	Y	2	2	2	2	3,5	3,5	3,5	3,5
	W	4	5	5	6	5	5	6	7
$50 < D \leq 80$	H	5	5	5	5	5	5	5	5
	Z	4	5	6	8	4	5	6	8
	Y	2,5	2,5	2,5	2,5	4	4	4	4
	W	4	5	6	7	5	6	6	7
$80 < D \leq 120$	H	6	6	6	6	6	6	6	6
	Z	4	5	6	8	4	5	6	8
	Y	3	3	3	3	5	5	5	5
	W	5	6	6	7	6	7	7	8
$120 < D \leq 180$	H	8	8	8	8	8	8	8	8
	Z	4	5	6	8	4	5	6	8
	Y	4	4	4	4	6	6	6	6
	W	6	7	7	8	7	8	8	9

Spline gauges with a pitch diameter > 180 mm should be created in steps similar to those above.

Table 10 — Positions of gauge tolerances

Piece	Standard method	Alternative method A	Alternative method B	Taper master plug
Internal space width	NO GO sector plug	NO GO sector plug		Taper master plugs with taper on one flank for ring gauges   
$E_{\max}$				
T				
$E_{v \max}$				
$E_{\min \text{ aux}}$				
T_v				
λ				
$E_{v \min}$				
$C_{v \min}$				
$S_{v \max}$				
λ				
T_v				
$S_{\max \text{ aux}}$				
$S_{v \min}$				
τ				
$S_{\min}$				
External tooth thickness	NO GO sector ring	NO GO sector ring		

10.4 Values of deviation allowances of spline gauges

The deviations of form checked for spline gauges, see [Table 11](#), are the same as those checked on corresponding parts, i.e:

- total pitch deviation;
- total profile deviation;
- total helix deviation.

NOTE GO spline gauges can have a plain cylindrical diameter to facilitate the inspection of form deviations. The runout of this cylinder to the pitch diameter is shown in [Table 11](#). These values are also valid for the runout of the major diameter of plug gauges and the minor diameter of ring gauges to the pitch diameter.

Table 11 — Deviation allowances for spline gauges

Pitch diameter D	Total profile deviation F_α	Total pitch variation F_p	Total helix deviation for a measuring length of part F_β		Radial run-out	
			$F_\beta \leq 25 \text{ mm}$	$F_\beta > 25 \text{ mm}$	Ring	Plug
mm	μm					
$1 \leq D \leq 100$	5	5	3	5	10	7
$100 < D \leq 150$	5	8	3	5	15	10
$150 < D \leq 180$	5	10	—	5	15	10
Spline gauges with a pitch diameter > 180 mm should be created in steps similar to those above.						

10.5 Inspection of gauges

10.5.1 Damage

Inspection method: visual inspection of all spline flanks and important diameters. Damage and rust are not allowed.

10.5.2 Marking

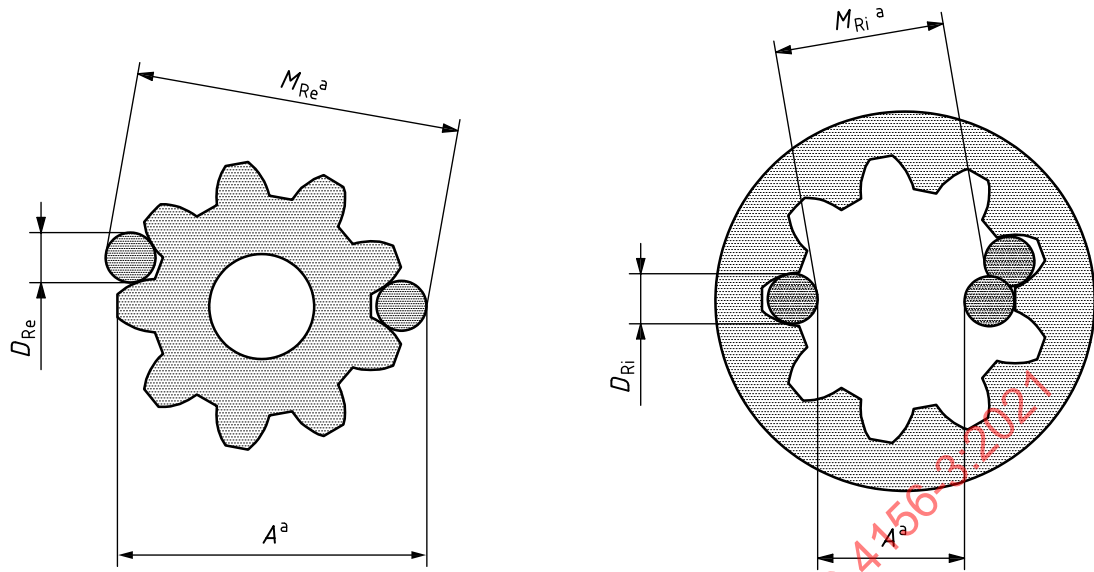
Inspection method: visual inspection. The marking shall be durable, complete and correct (see [10.6.4](#)).

10.5.3 Major diameter of plug gauges and minor diameter of ring gauges

Inspection method: 2-point measurement for even numbers of teeth, radial measurements for odd numbers of teeth as shown in [Figure 16](#).

NOTE 1 In the case of external and internal splines, it is desirable that one of the balls/pins be in a common space for both measurements.

NOTE 2 If several measurements are taken in various positions, then due to manufacturing variations a variable result will be obtained.



a Measured.

Figure 16 — Inspection of major diameter (plug gauges) and minor diameter (ring gauges)

Major diameter:

$$D_{ee} = 2 \left[A - \left(\frac{0,5(M_{Re} - D_{Re})}{\cos \frac{90^\circ}{z}} + \frac{D_{Re}}{2} \right) \right] \quad (33)$$

Minor diameter:

$$D_{ii} = 2 \left[A + D_{Ri} - \left(\frac{0,5(M_{Ri} + D_{Ri})}{\cos \frac{90^\circ}{z}} - \frac{D_{Ri}}{2} \right) \right] \quad (34)$$

10.5.4 Form diameter

Inspection method: involute inspection machine or attribute-GO gauges.

10.5.5 Tooth thickness of plug gauges

Inspection methods: measurement over 2 pins. Measurements shall be taken at 0° and 90° at each end and in the middle of the pin length. Pins need to be rubbed in order to avoid friction and microdirt. Measuring pins have a tolerance (see [Table 5](#)) which can affect the measurement over pins. To allow for this, the true calibrated pin diameter shall be used.

10.5.6 Space width of ring gauges

For ring gauges, the requirements of [10.5.5](#) are applicable. Ring gauges are inspected with pins and gauge blocks. The true size of a ring gauge is achieved when the gauge block can be moved axially with minimum resistance and has no radial movement.

Taper master plugs for ring gauges may also be used for size inspection. Due to the combined form deviations of ring and master plug, when ring gauges are fitted to taper masters, they are larger than

those manufactured to a dimension between pins. Master plug gauges are tapered on one side of all teeth and can be checked by measurement over pins in well defined planes.

10.5.7 Form deviations

Inspection methods: gear-testing machines. The profile and helix deviation shall be measured in at least 3 equally spaced angular positions on left and right flanks. For composite gauges, the total pitch deviation and the pitch diameter runout shall also be inspected.

10.5.8 Gauge wear inspection

An inspection period shall be chosen to guarantee that gauges remain within their wear limit. A spline gauge is considered to be worn out when the space width or tooth thickness exceeds the specified wear limit, or one of the form deviations exceeds 1,5 times the allowed tolerance.

10.5.9 Inspection certificates

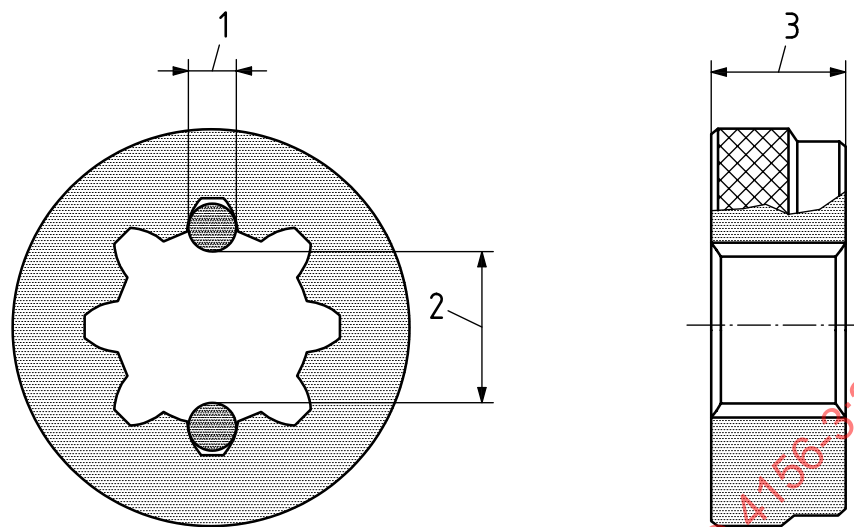
When inspection certificates for spline gauges are required, such certificates shall only be accepted when graphs of the form deviations are provided. Graphs of involute profile shall indicate the form diameter.

10.6 Dimensions, designation and marking of gauges

10.6.1 Inspection of external splines

10.6.1.1 GO composite ring gauge

The external splines are inspected using a GO composite ring gauge as shown in [Figure 17](#), with dimensions as given in [Table 12](#).

**Key**

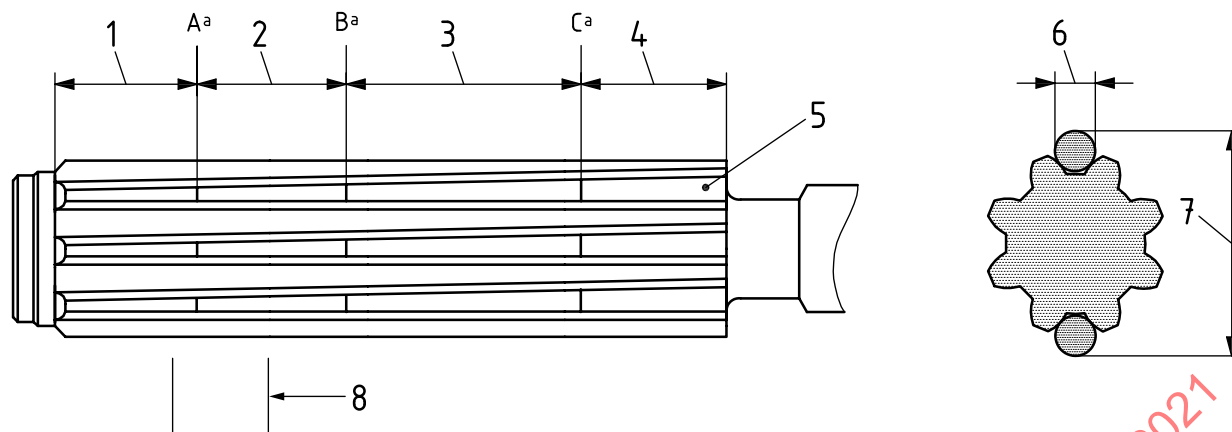
- 1 pin diameter
- 2 size between pins
- 3 gauge length

Figure 17 — GO composite ring gauge**Table 12 — Dimensions and tolerances for GO composite ring gauges**

Gauge dimension	Formula	Tolerance	Where fitted to taper master
Number of teeth	xx		
Module	xx		
Pressure angle	xx		
Pitch diameter	xx.xxxx		
Base diameter	xx.xxxx		
Major diameter	$D_{ee\ max} + 0,3m$	min.	
Form diameter	$D_{ee\ max} + 0,2m$	min.	
Minor diameter	$D_{Fe\ max}$	K7 ^a	
Space width new	$S_{v\ max} - Z$	$\pm H/2$	$(S_{v\ max} - Z)$ ref.
Space width wear limit	$S_{v\ max} + Y$		$(S_{v\ max} + Y)$ ref.
Pin diameter	See 8.5.2		
Size between pins new	See 8.6.1.2		Refer to taper master
Size between pins wear limit	See 8.6.1.2		Refer to taper master
Form deviations	See Table 11		
^a See ISO 286-1.			

10.6.1.2 Tapered tooth master plug gauge for GO composite ring gauge

A tapered tooth master plug gauge for a GO composite ring gauge is shown in [Figure 18](#) and its dimensions are given in [Table 13](#).

**Key**

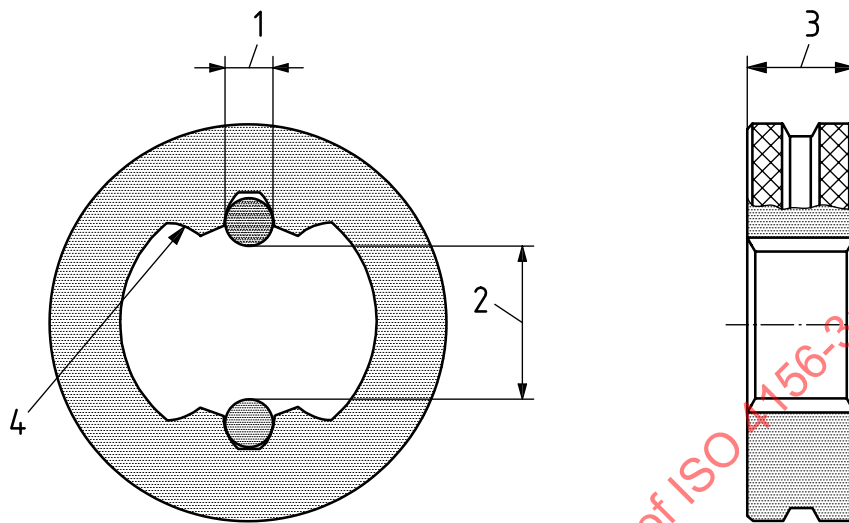
- 1 lead length/ring gauge length
- 2 manufacturing tolerance of ring
- 3 ring wear tolerance
- 4 oversize zone
- 5 taper on one flank of all teeth
- 6 pin diameter
- 7 size over pins
- 8 front face of new ring gauge
- ^a Lines marked at major diameter (position to be determined by calibration).

Figure 18 — Tapered tooth master plug gauge for GO composite ring gauge**Table 13 — Dimensions and tolerances for master plug gauges for GO composite ring gauges**

Gauge dimension	Formula	Tolerance
Number of teeth	xx	
Module	xx	
Pressure angle	xx	
Pitch diameter	xx.xxxx	
Base diameter	xx.xxxx	
Major diameter	$D_{ee\ min} - 0,2m$	$h8^a$
Form diameter	$D_{Fe\ max} - 0,1m$	max.
Minor diameter	$D_{Fe\ max} - 0,2m$	max.
Tooth thickness A	$S_{v\ max} - Z - H/2$	
Tooth thickness B	$S_{v\ max} - Z + H/2$	
Tooth thickness C	$S_{v\ max} + Y$	
Taper on one flank	0,02 %	min.
Pin diameter	See 8.5.1	
Size over pins A	See 8.6.1.1	
Size over pins B	See 8.6.1.1	
Size over pins C	See 8.6.1.1	
Form deviations	See Table 11	
^a See ISO 286-1.		

10.6.1.3 NO GO sector ring gauge

The external splines are inspected using a NO GO sector ring gauge as shown in Figure 19, with dimensions as given in Table 14.



Key

- 1 pin diameter
- 2 size between pins
- 3 gauge length
- 4 relieved outer surface

Figure 19 — NO GO sector ring gauge

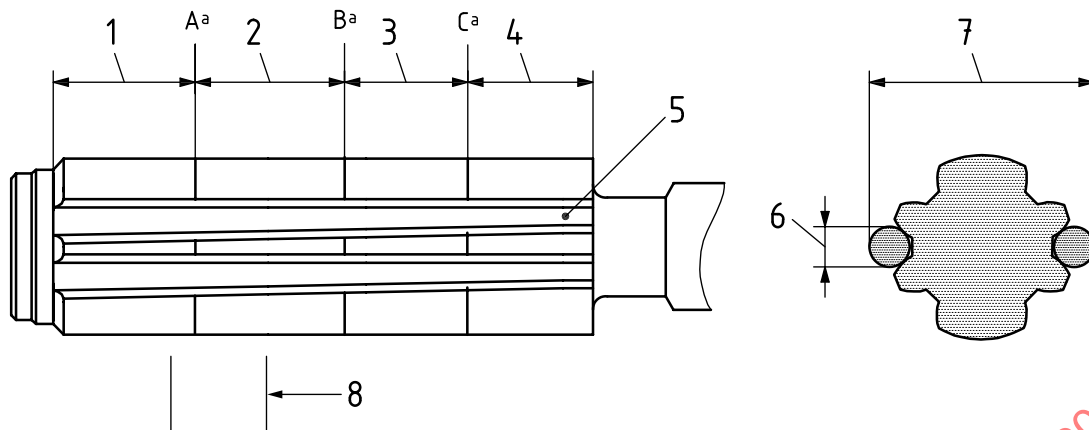
Table 14 — Dimensions and tolerances for NO GO sector ring gauges

Gauge dimension	Formula	Tolerance	Where fitted to taper master
Number of teeth	(z) x+x see Table 6		
Module	xx		
Pressure angle	xx		
Pitch diameter	xx.xxxx		
Base diameter	xx.xxxx		
Major diameter	$D_{ee\ max} + 0,3m$	min.	
Form diameter	$D_{ee\ max} + 0,2m$	min.	
Minor diameter	$(D + 2D_{Fe\ max})/3$	JS8 ^a	
Space width new	S_{min}	$\pm H/2$	(S_{min}) ref.
Space width wear limit	$S_{min} + W$		($S_{min} + W$) ref.
Pin diameter	See 8.5.2		
Size between pins new	See 8.6.1.2		Refer to taper master
Size between pins wear limit	See 8.6.1.2		Refer to taper master
Form deviations	See Table 11		

^a See ISO 286-1.

10.6.1.4 Tapered tooth master plug gauge for NO GO sector ring gauge

A tapered tooth master plug gauge for a NO GO sector ring gauge is shown in Figure 20 and its dimensions are given in Table 15.

**Key**

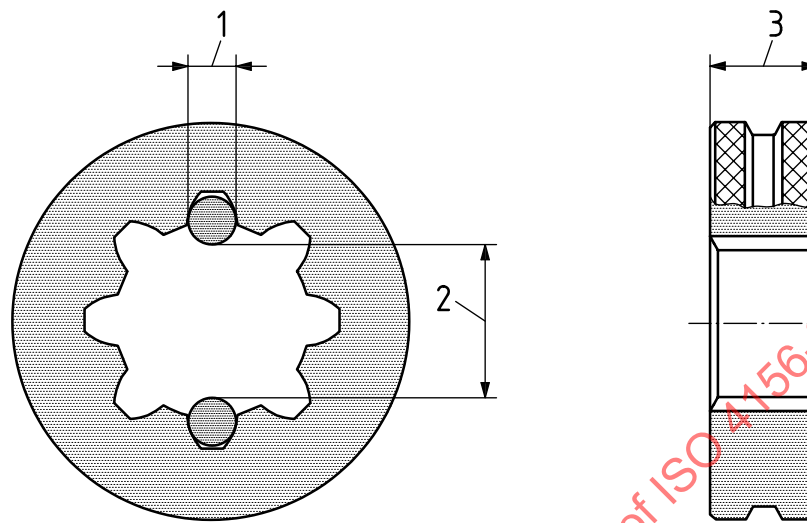
- 1 lead length/ring gauge length
- 2 manufacturing tolerance of ring
- 3 ring wear tolerance
- 4 oversize zone
- 5 taper on one flank of all teeth
- 6 pin diameter
- 7 size over pins
- 8 front face of new ring gauge
- ^a Lines marked at major diameter (position to be determined by calibration).

Figure 20 — Tapered tooth master plug gauge for NO GO two-sector ring gauge**Table 15 — Dimensions and tolerances for master plug gauges for NO GO sector ring gauges**

Gauge dimension	Formula	Tolerance
Number of teeth	(z) x+x see Table 6	
Module	xx	
Pressure angle	xx	
Pitch diameter	xx.xxxx	
Base diameter	xx.xxxx	
Major diameter	$D_{ee\ min} - 0,2m$	$h8^a$
Form diameter	$(D + 2D_{Fe\ max})/3 - 0,1m$	max.
Minor diameter	$(D + 2D_{Fe\ max})/3 - 0,2m$	max.
Tooth thickness A	$S_{min} - H/2$	
Tooth thickness B	$S_{min} + H/2$	
Tooth thickness C	$S_{min} + W$	
Taper on one flank	0,02 %	min.
Pin diameter	See 8.5.1	
Size over pins A	See 8.6.1.1	
Size over pins B	See 8.6.1.1	
Size over pins C	See 8.6.1.1	
Form deviations	See Table 11	
^a See ISO 286-1.		

10.6.1.5 NO GO composite ring gauge

The external splines are inspected using a NO GO composite ring gauge as shown in [Figure 21](#), with dimensions as given in [Table 16](#).



Key

- 1 pin diameter
- 2 size between pins
- 3 gauge length

Figure 21 — NO GO composite ring gauge

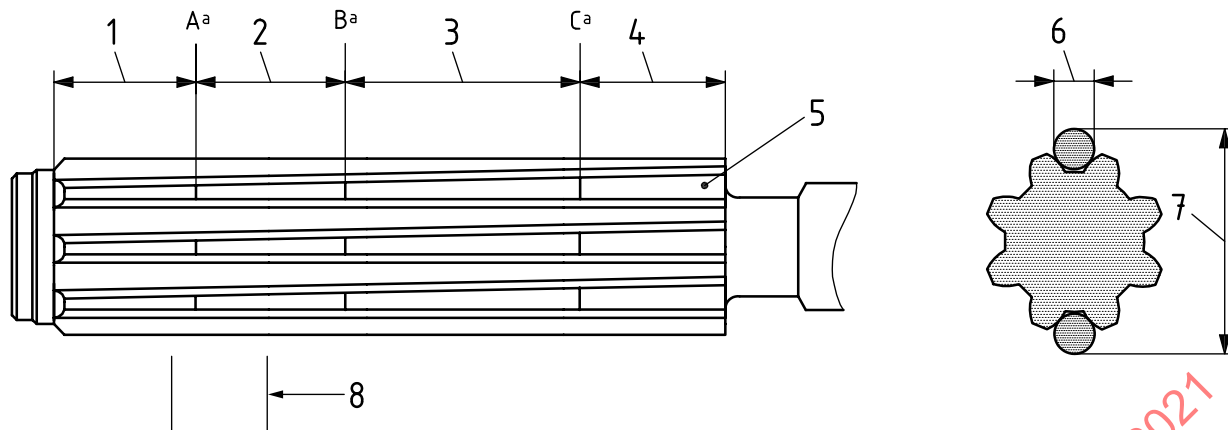
Table 16 — Dimensions and tolerances for NO GO composite ring gauges

Gauge dimension	Formula	Tolerance	Where fitted to taper master
Number of teeth	xx		
Module	xx		
Pressure angle	xx		
Pitch diameter	xx.xxxx		
Base diameter	xx.xxxx		
Major diameter	$D_{ee\ max} + 0,3m$	min.	
Form diameter	$D_{ee\ max} + 0,2m$	min.	
Minor diameter	$(D + 2D_{Fe\ max})/3$	JS8 ^a	
Space width new	$S_{v\ min}$	$\pm H/2$	$(S_{v\ min})$ ref.
Space width wear limit	$S_{v\ min} + W$		$(S_{v\ min} + W)$ ref.
Pin diameter	See 8.5.2		
Size between pins new	See 8.6.1.2		Refer to taper master
Size between pins wear limit	See 8.6.1.2		Refer to taper master
Form deviations	See Table 11		

^a See ISO 286-1.

10.6.1.6 Tapered tooth master plug gauge for NO GO composite ring gauge

A tapered tooth master plug gauge for a NO GO composite ring gauge is shown in [Figure 22](#) and its dimensions are given in [Table 17](#).

**Key**

- 1 lead length/ring gauge length
- 2 manufacturing tolerance of ring
- 3 ring wear tolerance
- 4 oversize zone
- 5 taper on one flank of all teeth
- 6 pin diameter
- 7 size over pins
- 8 front face of new ring gauge
- ^a Lines marked at major diameter (position to be determined by calibration).

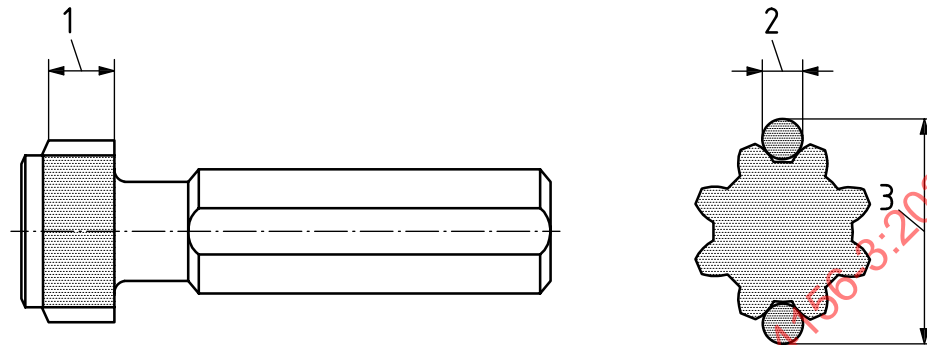
Figure 22 — Tapered tooth master plug gauge for NO GO composite ring gauge**Table 17 — Dimensions and tolerances for master plug gauges for NO GO composite ring gauges**

Gauge dimension	Formula	Tolerance
Number of teeth	xx	
Module	xx	
Pressure angle	xx	
Pitch diameter	xx.xxxx	
Base diameter	xx.xxxx	
Major diameter	$D_{ee\ min} - 0,2m$	$h8^a$
Form diameter	$(D + 2D_{Fe\ max})/3 - 0,1m$	max.
Minor diameter	$(D + 2D_{Fe\ max})/3 - 0,2m$	max.
Tooth thickness A	$S_{v\ min} - H/2$	
Tooth thickness B	$S_{v\ min} + H/2$	
Tooth thickness C	$S_{v\ min} + W$	
Taper on one flank	0,02 %	min.
Pin diameter	See 8.5.1	
Size over pins A	See 8.6.1.1	
Size over pins B	See 8.6.1.1	
Size over pins C	See 8.6.1.1	
Form deviations	See Table 11	
^a See ISO 286-1.		

10.6.2 Inspection of internal splines

10.6.2.1 GO composite plug gauge

The internal splines are inspected using a GO composite plug gauge as shown in [Figure 23](#), with dimensions as given in [Table 18](#).



Key

- 1 gauge length
- 2 pin diameter
- 3 size over pins

Figure 23 — GO composite plug gauge

Table 18 — Dimensions and tolerances for GO composite plug gauges

Gauge dimension	Formula	Tolerance
Number of teeth	xx	
Module	xx	
Pressure angle	xx	
Pitch diameter	xx.xxxx	
Base diameter	xx.xxxx	
Major diameter	$D_{Fi \min}$	k7 ^a
Form diameter	$D_{ii \min} - 0,2m$	max.
Minor diameter	$D_{ii \min} - 0,3m$	max.
Tooth thickness new	$E_{v \min} + Z$	$\pm H/2$
Tooth thickness wear limit	$E_{v \min} - Y$	
Pin diameter	See 8.5.1	
Size over pins new	See 8.6.1.1	
Size over pins wear limit	See 8.6.1.1	
Form deviations	See Table 11	
^a See ISO 286-1.		

10.6.2.2 NO GO sector plug gauge

The internal splines are inspected using a NO GO sector plug gauge as shown in [Figure 24](#), with dimensions as given in [Table 19](#).