
**Earth-moving machinery — Dumpers —
Terminology and commercial
specifications**

*Engins de terrassement — Tombereaux — Terminologie et
spécifications commerciales*

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Foreword

ISO (the International Organization for Standardization) is a worldwide federation of national standards bodies (ISO member bodies). The work of preparing International Standards is normally carried out through ISO technical committees. Each member body interested in a subject for which a technical committee has been established has the right to be represented on that committee. International organizations, governmental and non-governmental, in liaison with ISO, also take part in the work. ISO collaborates closely with the International Electrotechnical Commission (IEC) on all matters of electrotechnical standardization.

International Standards are drafted in accordance with the rules given in the ISO/IEC Directives, Part 2.

The main task of technical committees is to prepare International Standards. Draft International Standards adopted by the technical committees are circulated to the member bodies for voting. Publication as an International Standard requires approval by at least 75 % of the member bodies casting a vote.

Attention is drawn to the possibility that some of the elements of this document may be the subject of patent rights. ISO shall not be held responsible for identifying any or all such patent rights.

ISO 7132 was prepared by Technical Committee ISO/TC 127, *Earth-moving machinery*, Subcommittee SC 4, *Commercial nomenclature, classification and rating*.

This third edition cancels and replaces the second edition (ISO 7132:1990), which has been technically revised.

Earth-moving machinery — Dumpers — Terminology and commercial specifications

1 Scope

This International Standard establishes a terminology for, and the content of, commercial literature specifications for self-propelled dumpers (including compact dumpers), as defined in ISO 6165, used in earth moving.

2 Normative references

The following referenced documents are indispensable for the application of this document. For dated references, only the edition cited applies. For undated references, the latest edition of the referenced document (including any amendments) applies.

ISO 3450, *Earth-moving machinery — Braking systems of rubber-tyred machines — Systems and performance requirements and test procedures*

ISO 5010, *Earth-moving machinery — Rubber-tyred machines — Steering requirements*

ISO 6014:1986, *Earth-moving machinery — Determination of ground speed*

ISO 6016:1998, *Earth-moving machinery — Methods of measuring the masses of whole machines, their equipment and components*

ISO 6165, *Earth-moving machinery — Basic types — Vocabulary*

ISO 6483:1980, *Earth-moving machinery — Dumper bodies — Volumetric rating*

ISO 6746-1, *Earth-moving machinery — Definitions of dimensions and codes — Part 1: Base machine*

ISO 7457:1997, *Earth-moving machinery — Determination of turning dimensions of wheeled machines*

ISO 9249:1997, *Earth-moving machinery — Engine test code — Net power*

3 Terms and definitions

For the purposes of this document, the terms and definitions given in ISO 6165 and the following apply.

3.1 General

3.1.1

dumper

self-propelled crawler or wheeled machine, with an open body, which transports and dumps or spreads material, loading being performed either by means external to the dumper or by self-loading equipment

3.1.2

base machine

machine with a cab or canopy and operator-protective structures (if required), without equipment or attachments but possessing the necessary mountings for such equipment and attachments

3.1.3

equipment

set of components mounted onto the base machine which allows an attachment to perform its design function

3.1.4

self-loading equipment

an integral mounted, bucket-supporting structure and linkage permanently fitted to a compact dumper enabling it to fill its own open body with material

NOTE See 4.1.5.

3.1.5

attachment

assembly of components that can be mounted onto the base machine or equipment for a specific use

3.1.6

component

part of an assembly or of a base machine, equipment or an attachment

3.2 Performance

3.2.1

tractive force rimpull

force available between the tyre and the ground to propel the dumper

3.2.1.1

tractive force with direct drive transmission

tractive force calculated or measured at the maximum engine torque in each forward gear

NOTE The maximum pull could be limited by mass and traction conditions.

3.2.1.2

tractive force rimpull with powershift transmission [electric drive] [hydrostatic drive]

tractive force rimpull given by the calculated or measured pull versus machine speed curves in each forward gear range

NOTE The maximum pull could be limited by mass and traction conditions.

3.2.2

empty body dump and return time

full movement cycle time of a body, door or ejector without load, at the rated engine speed

3.2.3

payload

manufacturer's rated mass that can be carried by the machine

4 Base machine

NOTE The information on the base machine parameters is provided in the referenced figures.

4.1 Types of dumper

4.1.1 Method of dumping

— Rear dump: see Figure 1.

— Bottom dump: see Figure 2.

- Side dump: see Figure 3.
- Front dump: see Figure 4.
- Rotating dump: see Figure 5.
- High dump: see Figure 6.
- Slewing dump: see Figure 7.

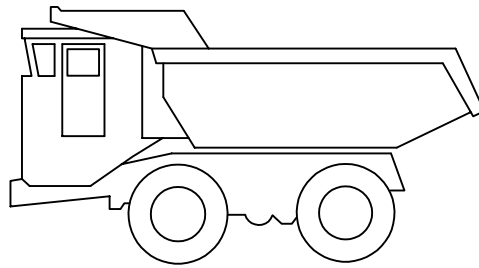


Figure 1 — Rear dump

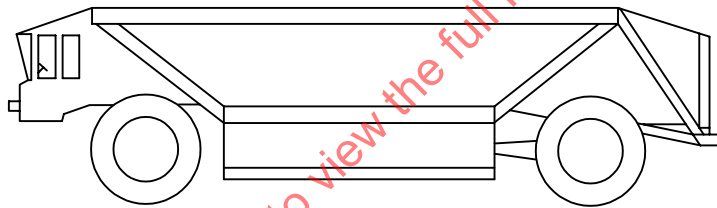


Figure 2 — Bottom dump

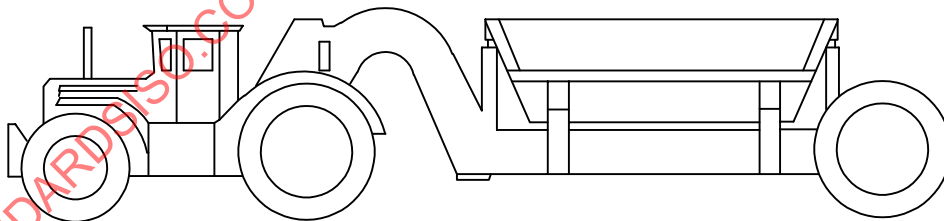


Figure 3 — Side dump

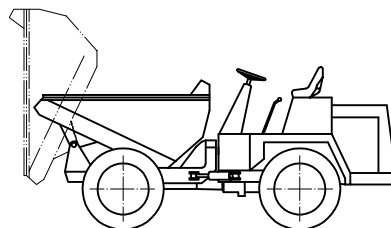


Figure 4 — Front dump

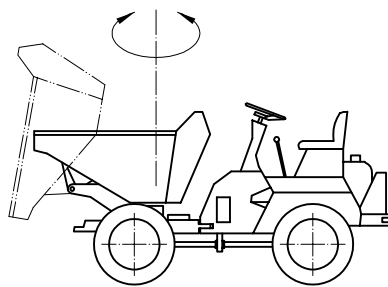


Figure 5 — Rotating dump

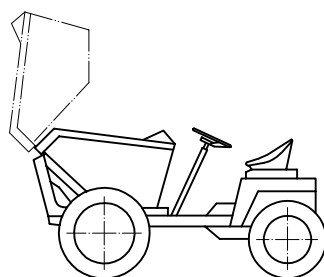


Figure 6 — High dump

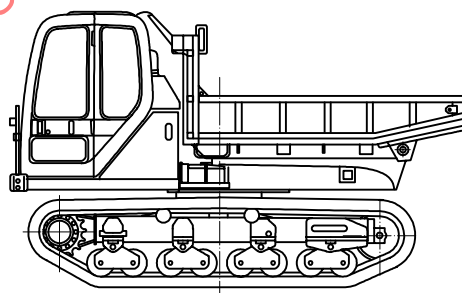
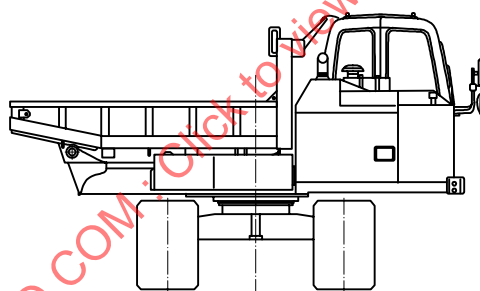
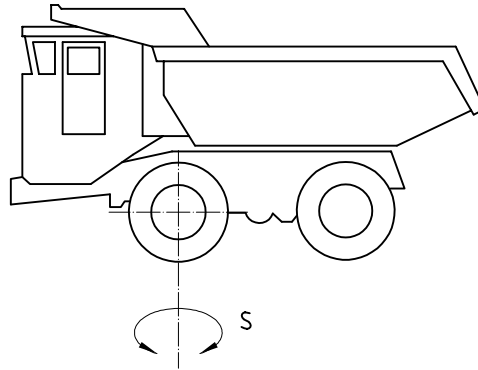


Figure 7 — Slewing dump

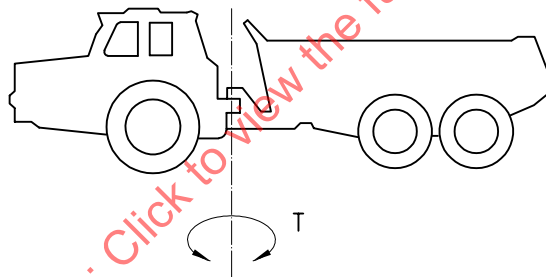
4.1.2 Steering system

- Front-wheel steer: see Figure 8.
- Articulated steer: see Figure 9.
- Rear-wheel steer: see Figure 10.

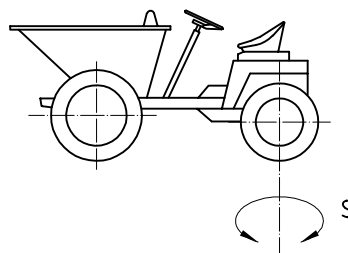
- All-wheel steer: see Figure 11.
- Crawler skid steer: see Figure 12.
- Wheel skid steer: see Figure 13.

**Key**

S steerable wheels

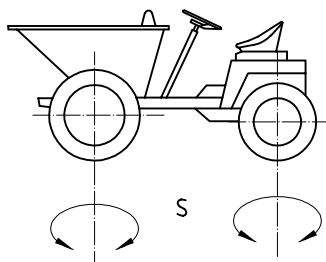
Figure 8 — Front-wheel steer**Key**

T turning centre

Figure 9 — Articulated steer**Key**

S steerable wheels

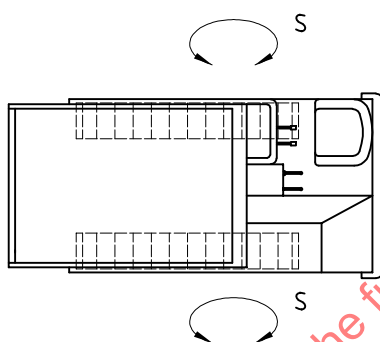
Figure 10 — Rear-wheel steer



Key

S steerable wheels

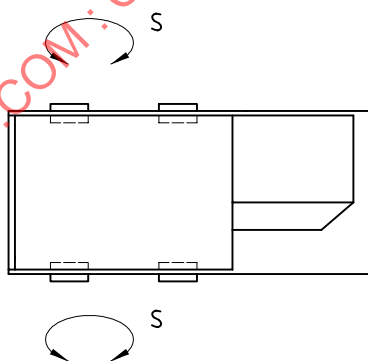
Figure 11 — All-wheel steer



Key

S steerable track

Figure 12 — Crawler skid steer



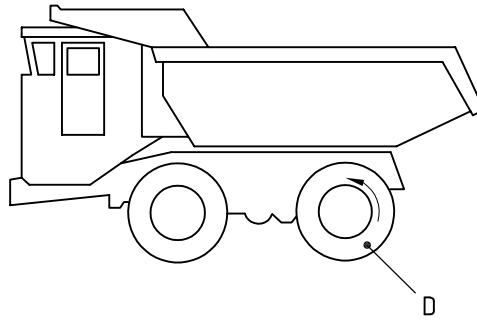
Key

S steerable wheels

Figure 13 — Wheel skid steer

4.1.3 Drive system

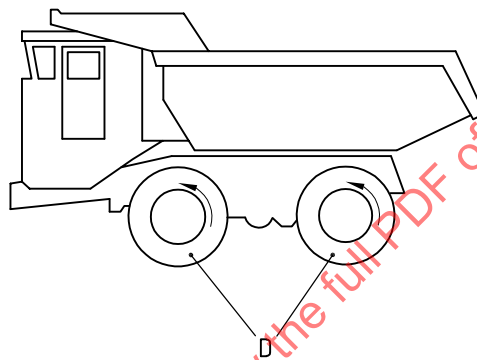
- Rear-wheel drive: see Figure 14.
- All-wheel drive: see Figure 15.
- Centre-axle drive: see Figure 16.
- Crawler drive: see Figure 17.



Key

D drive wheels

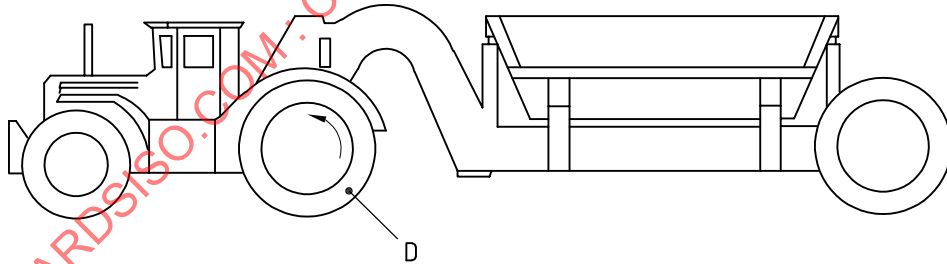
Figure 14 — Rear-wheel drive



Key

D drive wheels

Figure 15 — All-wheel drive



Key

D drive wheels

Figure 16 — Centre-axle drive

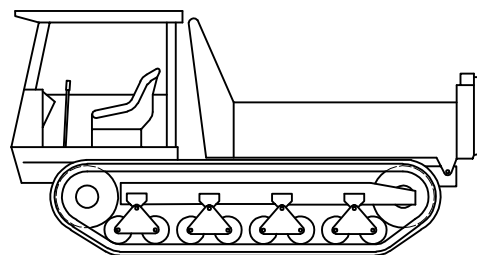


Figure 17 — Crawler drive

4.1.4 Number of axles

- Two axles: see Figure 18.
- Three axles: see Figure 19.
- More than three axles: see Figure 20.

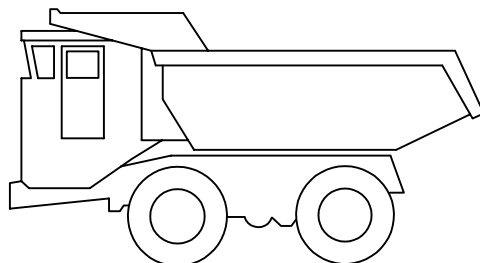


Figure 18 — Two axles

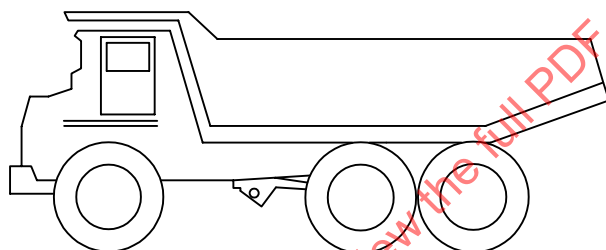


Figure 19 — Three axles

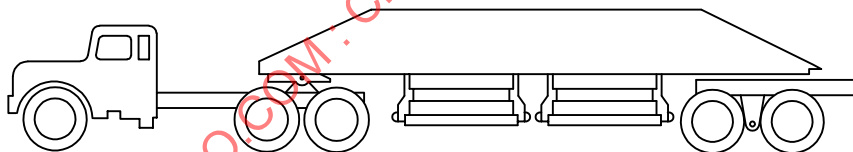


Figure 20 — More than three axles

4.1.5 Method of self-loading

- Body loading: see Figure 21.
- Shovel loading: see Figure 22.

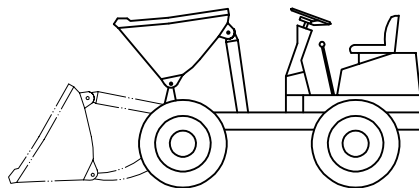


Figure 21 — Body loading

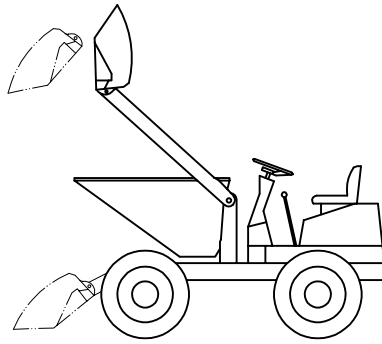


Figure 22 — Shovel loading

4.1.6 Operator position

- Rear operator position: see Figure 23.
- Front operator position: see Figure 24.
- Reversible operator position: see Figure 25.

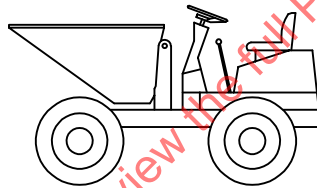


Figure 23 — Rear operator position

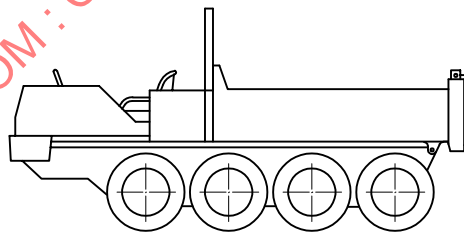


Figure 24 — Front operator position

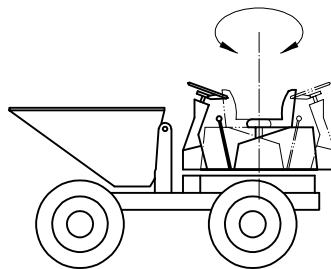
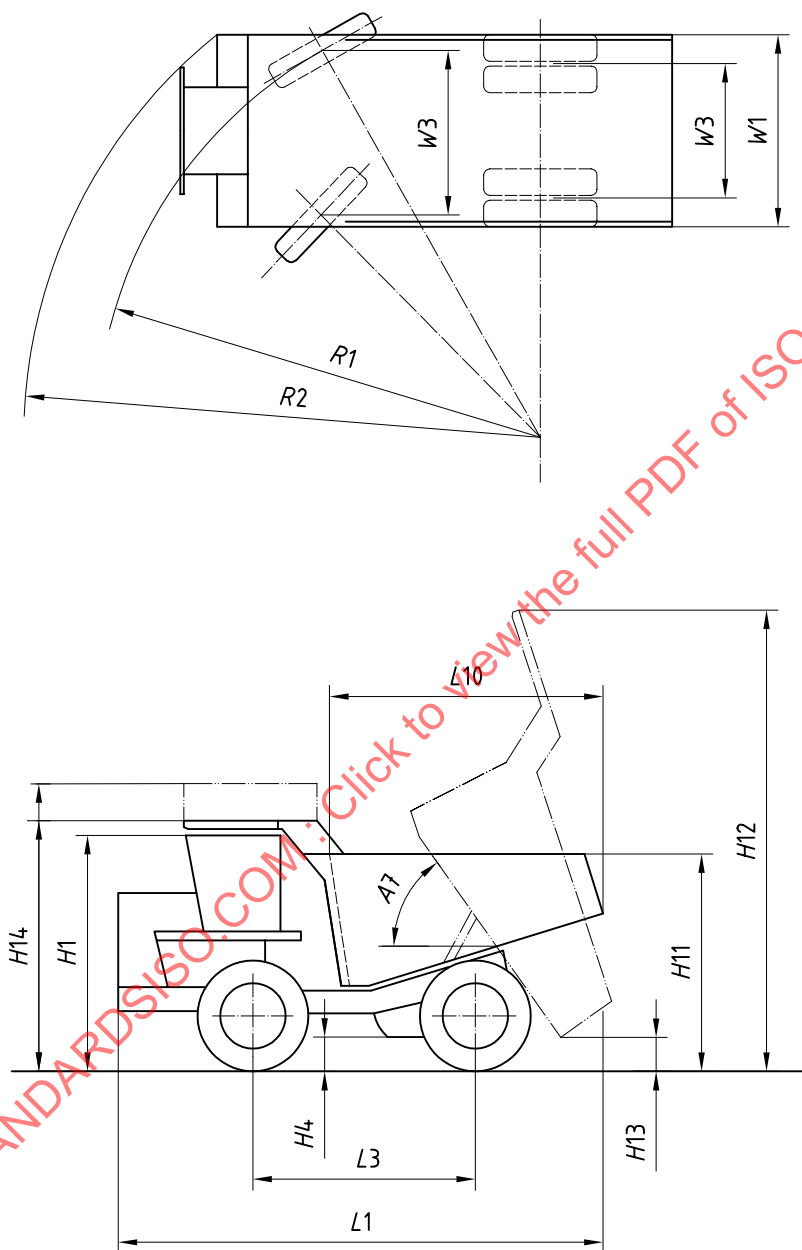


Figure 25 — Reversible operator position

4.2 Dimensions (see ISO 6746-1)

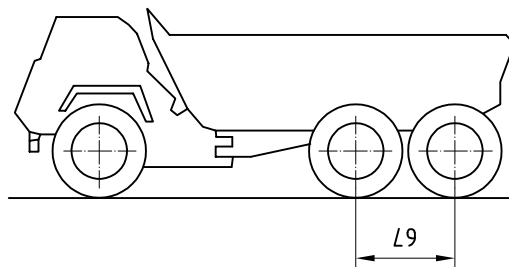
4.2.1 Dumpers

See Figure 26. For additional definitions of dimensions and their terms and codes related to dumpers, see Annex A.

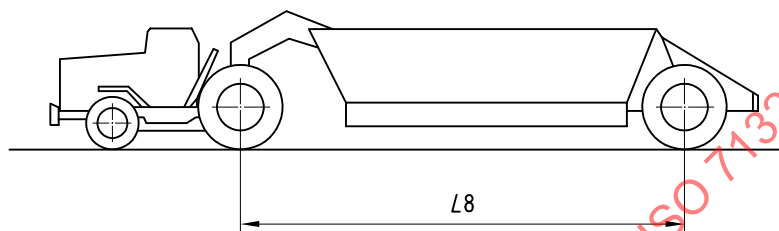


a) Rigid frame

Figure 26 — Dimensions of base machine — Dumper



b) Tandem



c) Trailer

Figure 26 — Dimensions of base machine — Dumper

4.2.2 Compact dumpers

See Figures 27, 28, 29, 30 and 31. For definitions of dimensions and their terms and codes, see Annex A. For additional dimensions and codes strictly related to compact dumpers, see Annex B.

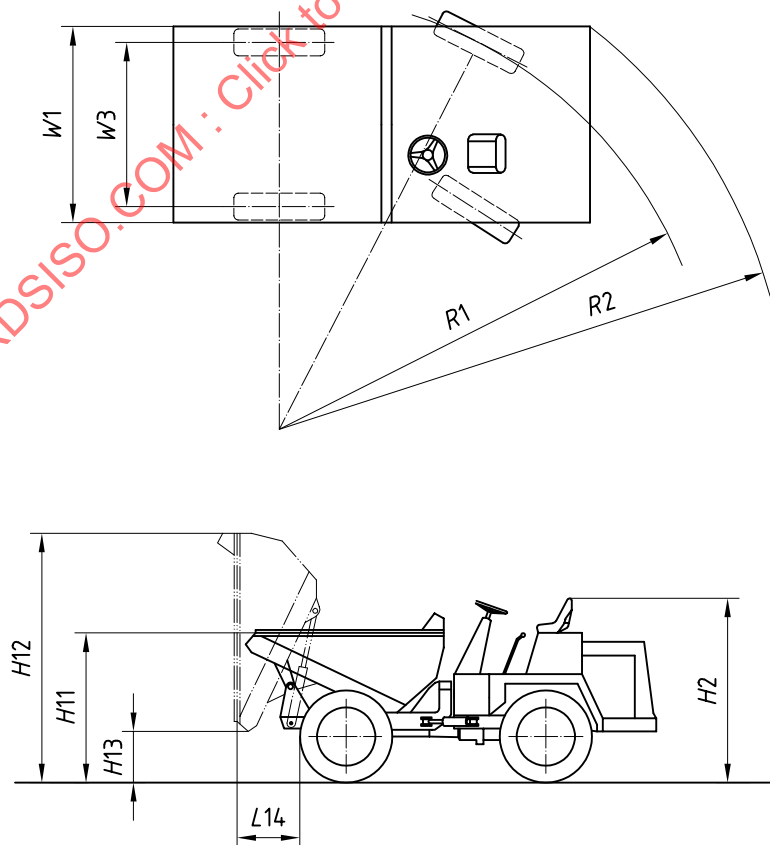


Figure 27 — Dimensions of wheeled compact dumper — Four-wheel

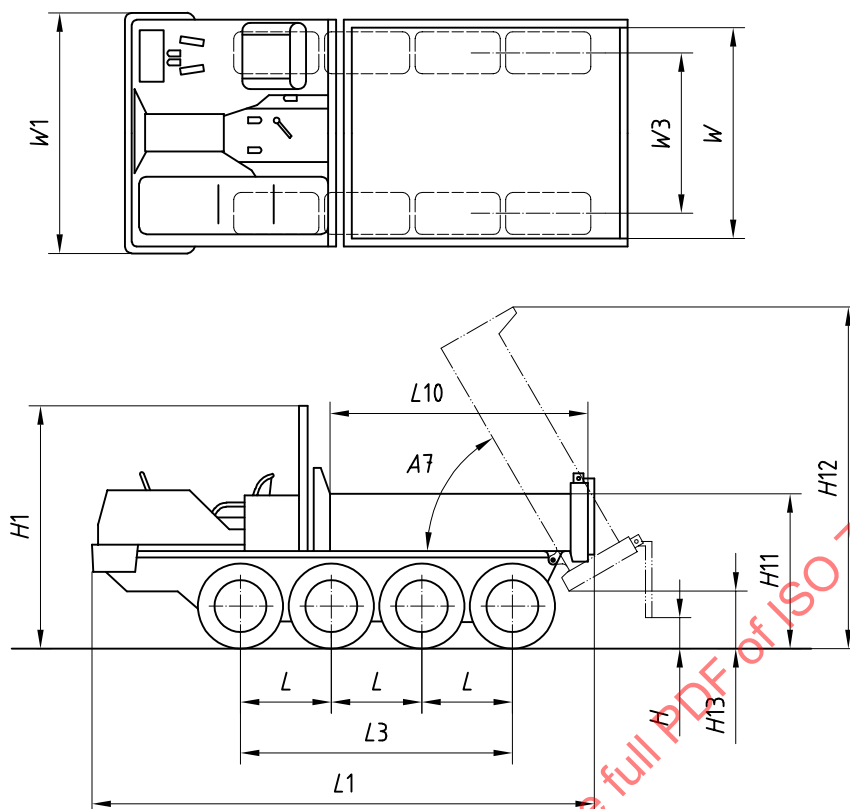


Figure 28 — Dimensions of wheeled compact dumper — Eight-wheel

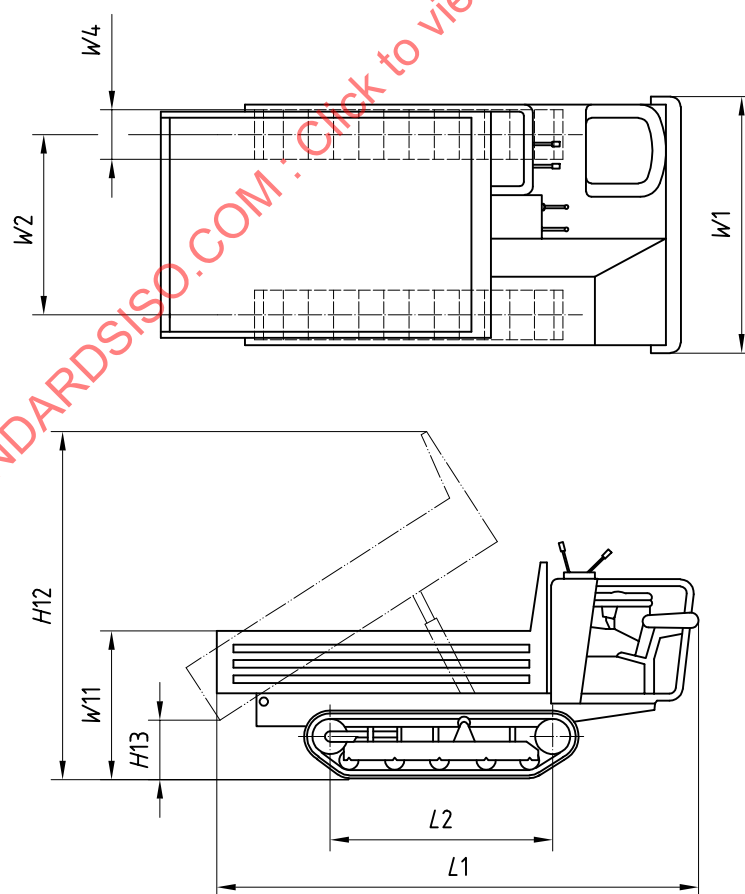


Figure 29 — Dimensions of crawler compact dumper — Rear operator position

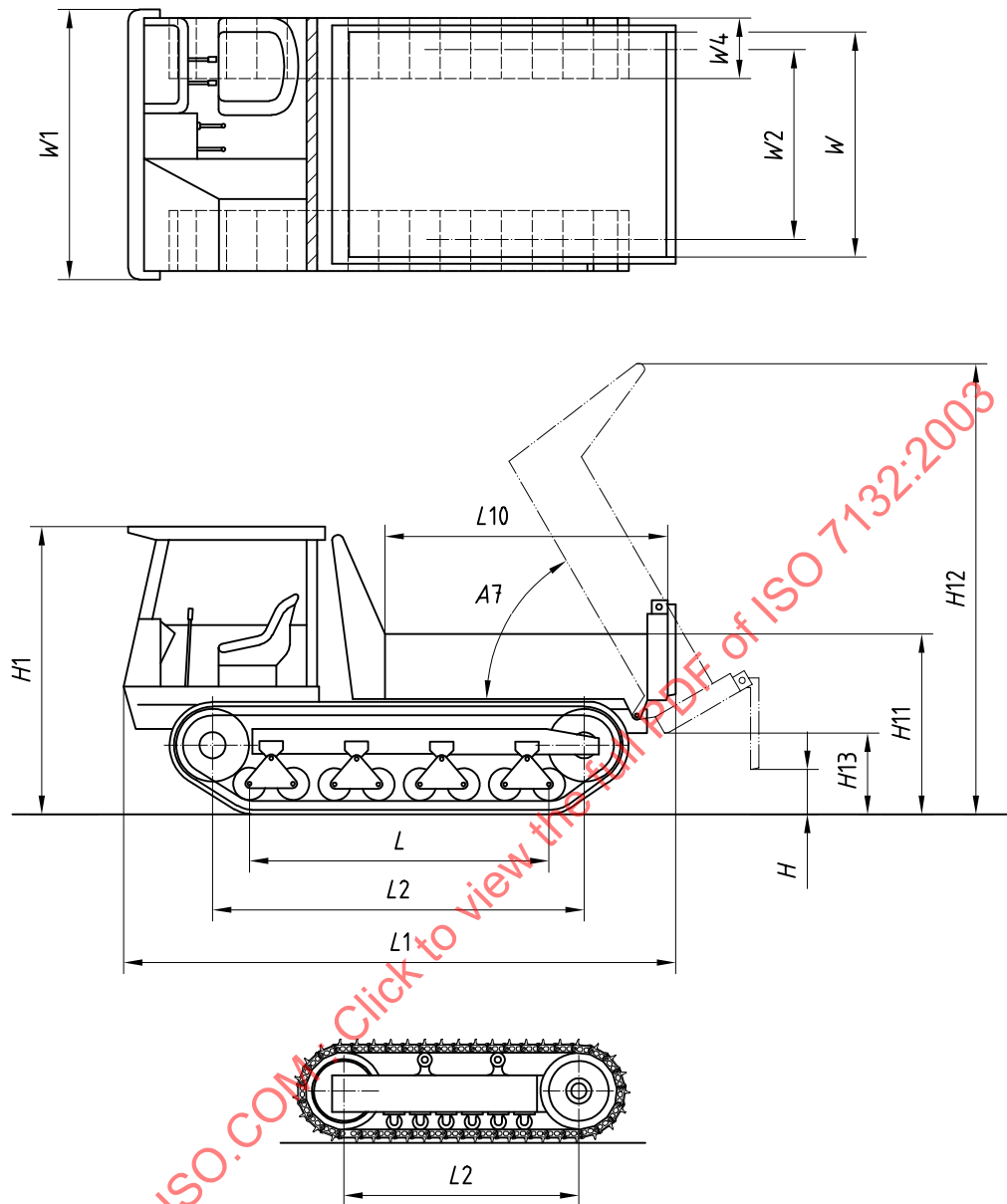


Figure 30 — Dimensions of crawler compact dumper — Front operator position

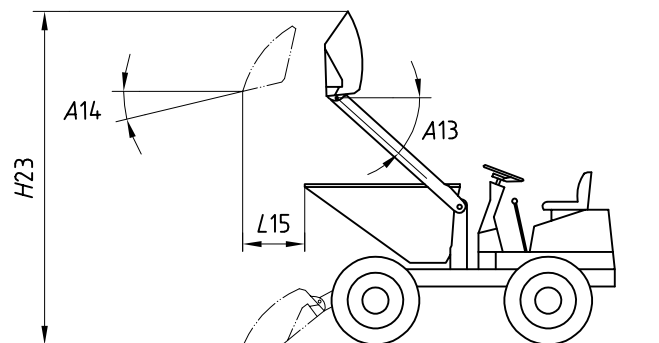


Figure 31 — Dimensions of self-loading compact dumper

4.3 Masses

See ISO 6016.

4.4 Component nomenclature

- Two-axle rear dump: see Figure 32.
- Two- and four-wheel tractor: see Figure 33.
- Trailing units: see Figure 34.
- Wheeled compact dumpers: see Figures 35 and 36.
- Crawler compact dumpers: see Figures 37 and 38.

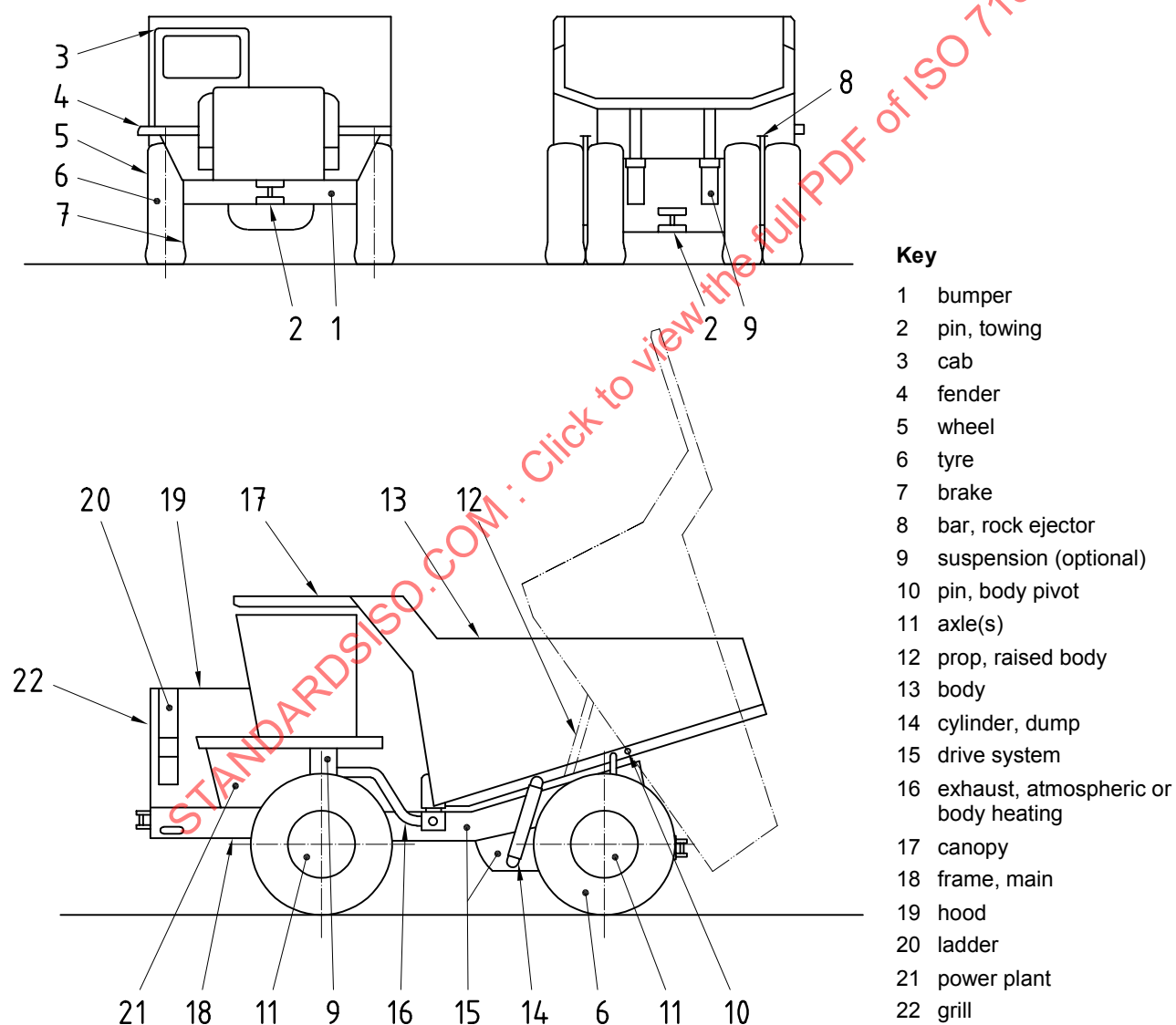
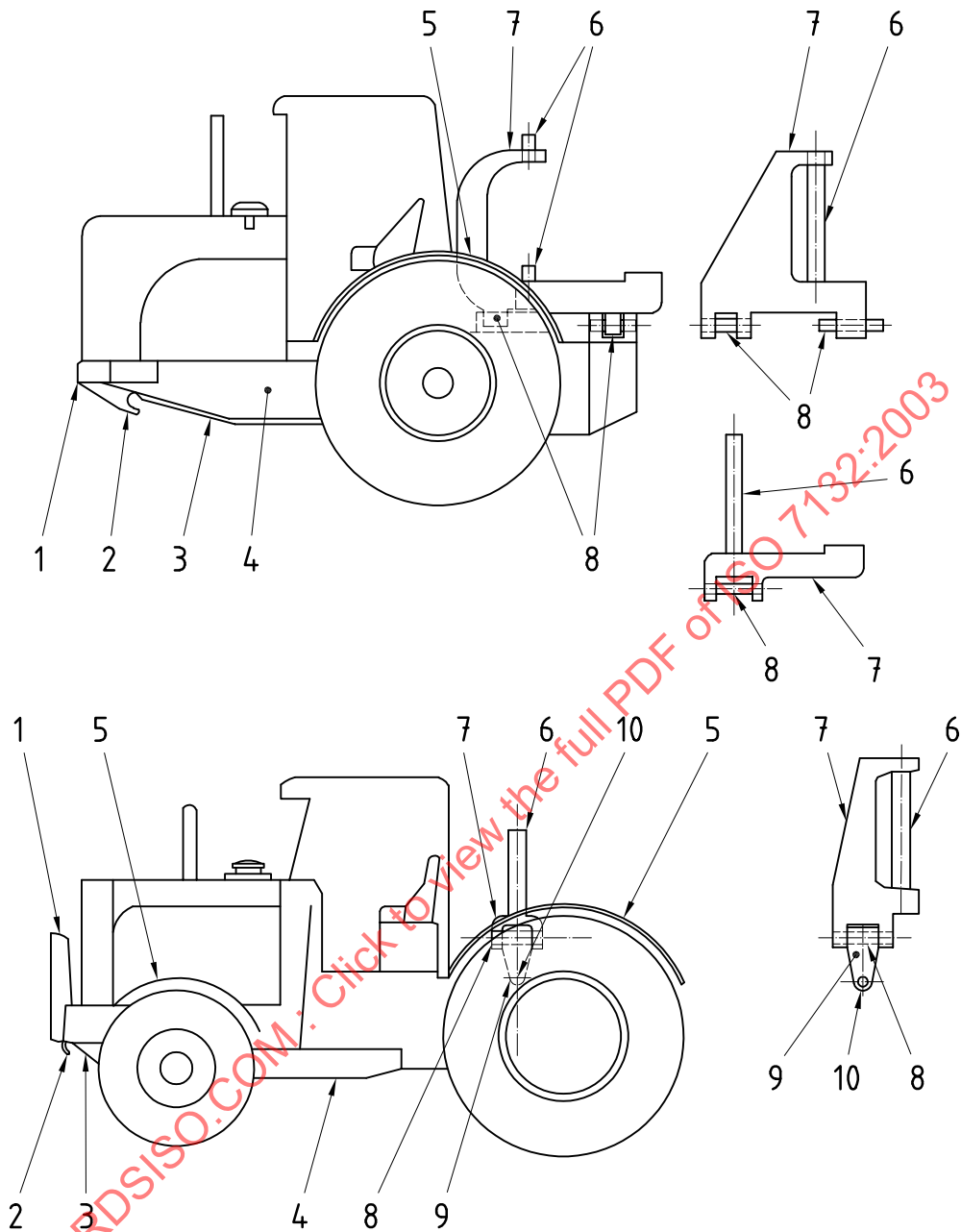
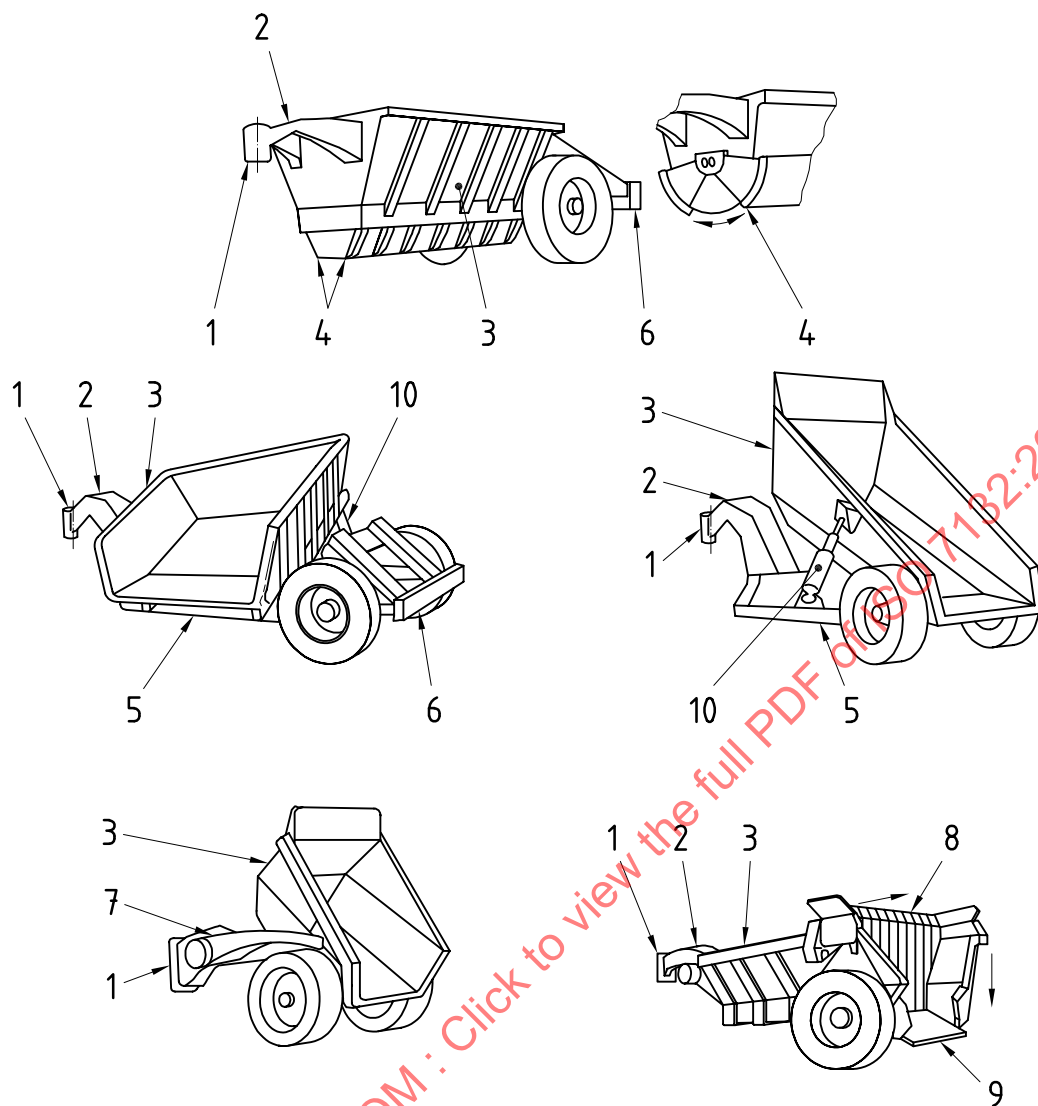


Figure 32 — Component nomenclature — Two-axle rear dump

**Key**

- | | |
|-----------------|----------------------------|
| 1 bumper | 6 kingpin, hitch |
| 2 hook, pull | 7 hitch |
| 3 guard, bottom | 8 pin, oscillating pivot |
| 4 frame, main | 9 yoke, hitch |
| 5 fender | 10 pin, fore and aft pivot |

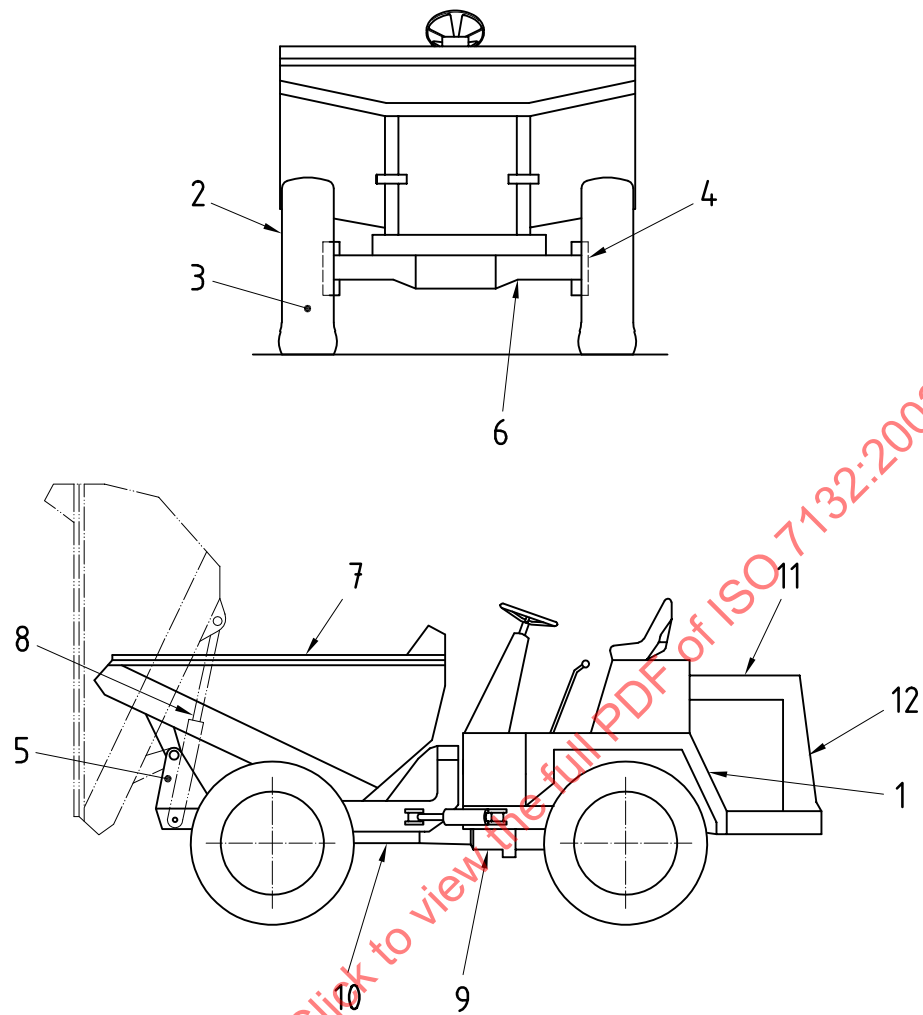
Figure 33 — Component nomenclature — Two- and four-wheel tractors



Key

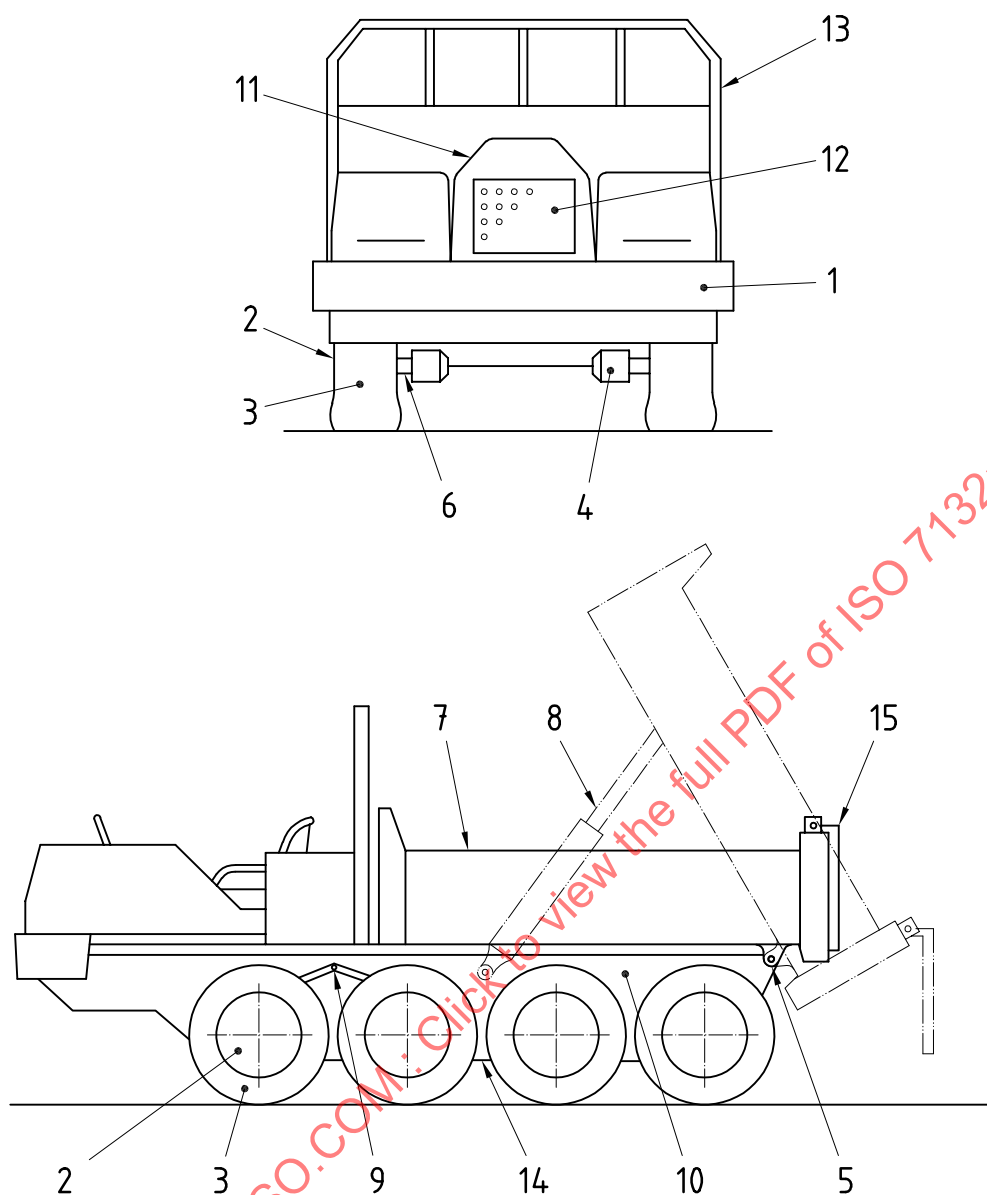
- | | |
|--------------------|-------------------|
| 1 housing, kingpin | 6 bumper |
| 2 gooseneck | 7 frame, draft |
| 3 body | 8 ejector |
| 4 doors | 9 tailgate |
| 5 frame, main | 10 cylinder, dump |

Figure 34 — Component nomenclature — Trailing units

**Key**

- | | |
|-------------------|----------------|
| 1 fender | 7 body |
| 2 wheel | 8 cylinder |
| 3 tyre | 9 drive system |
| 4 brake | 10 frame, main |
| 5 pin, body pivot | 11 hood |
| 6 axle(s) | 12 power plant |

Figure 35 — Component nomenclature — Two-axle wheeled compact dumpers



Key

- | | |
|-------------------|----------------------|
| 1 bumper | 9 drive system |
| 2 wheel | 10 frame, main |
| 3 tyre | 11 hood |
| 4 brake | 12 power plant |
| 5 pin, body pivot | 13 guard |
| 6 axle | 14 case, chain drive |
| 7 body | 15 tailgate |
| 8 cylinder, dump | |

Figure 36 — Component nomenclature — More-than-three-axle, wheeled compact dumpers

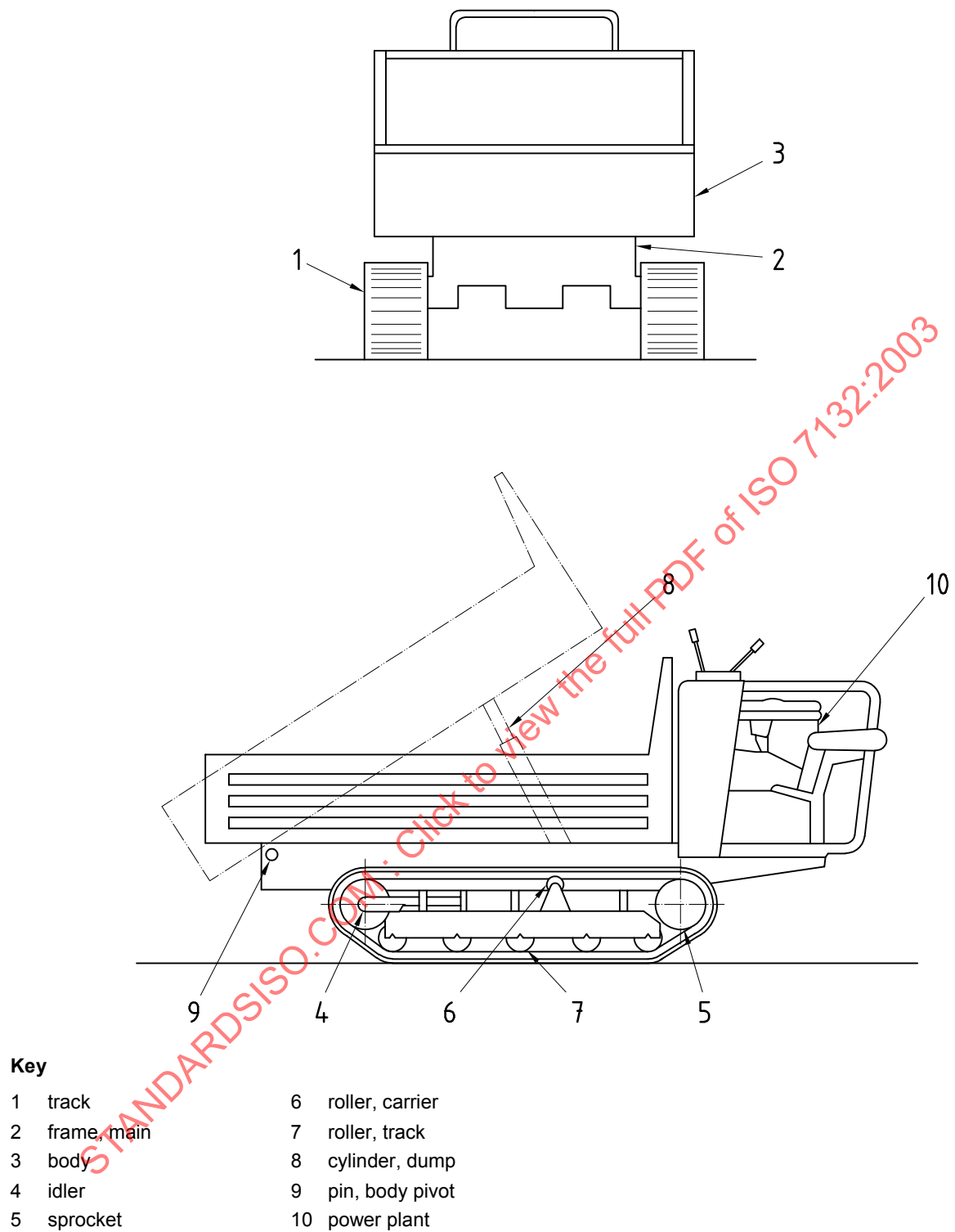


Figure 37 — Component nomenclature — Crawler compact dumpers without canopy

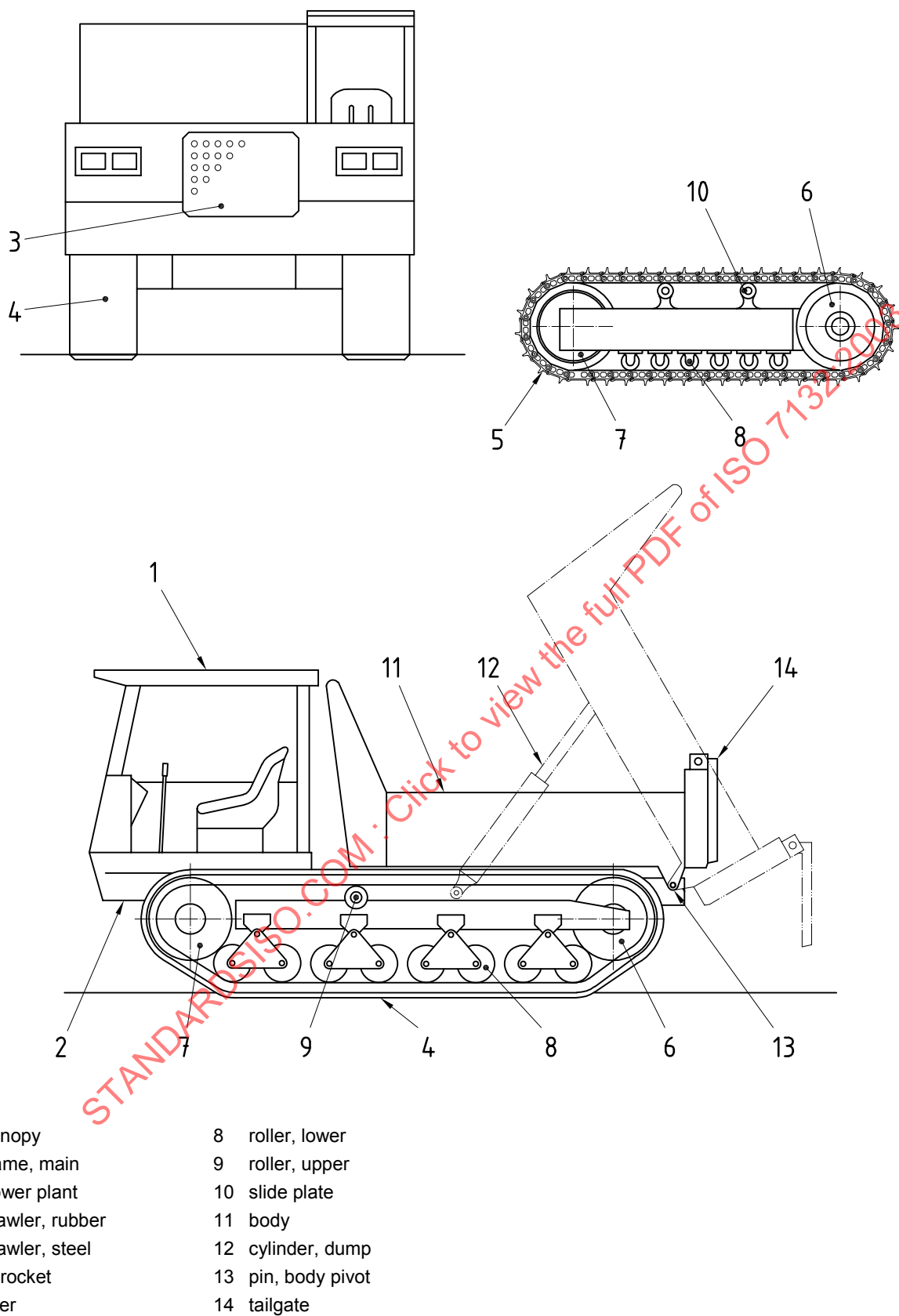


Figure 38 — Component nomenclature — Crawler dumpers with canopy

5 Performance characteristics

The following performance characteristics are used in connection with dumpers: the International Standard indicates further characteristics and test methods as appropriate; the term number refers to the term as defined in this International Standard.

- a) ISO net power (engine): see ISO 9249.
- b) Maximum travel speed: see ISO 6014.
- c) Tractive force rimpull (3.2.1):
 - 1) Tractive force with direct drive transmission (3.2.1.1);
 - 2) Tractive force rimpull with powershift transmission, electric drive or hydrostatic drive (3.2.1.2).
- d) Empty body dump and return time (3.2.2).
- e) Steering capability
 - 1) Turning radius: see ISO 7457.
 - 2) Machine clearance diameter: see ISO 7457.
- f) Braking performance: based on requirements given in ISO 3450.
- g) Payload (3.2.3).

6 Commercial literature specifications (SI units)

6.1 Engine

Specify the characteristics:

- a) manufacturer and model;
- b) compression-ignition (diesel) or spark-ignition;
- c) type of cycle (two- or four-stroke);
- d) naturally aspirated, mechanically supercharged, or turbo-charged, with or without aftercooling;
- e) number of cylinders;
- f) bore;
- g) stroke;
- h) displacement;
- i) cooling system (air or water cooled);
- j) type of fuel;
- k) power, flywheel net: at r/min;
- l) torque, maximum: at r/min;
- m) starter type;
- n) electrical system: V.

6.2 Transmission

Specify the type, for example:

- manual shift with flywheel clutch;
- power shift with torque converter;
- hydrostatic;
- electric;
- number of gear speeds, forward and reverse;
- travel speeds (forward and reverse).

A graph of rimpull versus speed should be shown.

6.3 Drive axle(s)

Specify the type, for example:

- steerable;
- fixed, oscillating and/or suspended;
- hydrostatic;
- electric;
- bevel gear and pinion;
- differential — standard, non-slip, limited slip or lock-up;
- planetary final drive.

6.4 Steering

6.4.1 Type

Specify type in accordance with ISO 5010, for example:

- articulated frame;
- front-wheel steer;
- rear-wheel steer;
- all-wheel steer;
- crawler skid steer;
- boosted, manual, hydrostatic;
- emergency steer method.

6.4.2 Performance

Specify:

- turning radius:, left and right;
- machine clearance diameter:

6.5 Brakes

6.5.1 Service brakes

Specify, for example:

- type (drum, disc, wet or dry);
- actuating system type (mechanical, air, hydraulic, electrical, combination, etc.).

6.5.2 Parking brake

Specify type.

6.5.3 Secondary brake

Specify type.

6.5.4 Retarding brake

Specify:

- type;
- actuating system.

6.5.5 Brake performance

Specify in accordance with ISO 3450.

6.6 Tyres

Specify:

- size and type;
- ply rating;
- rim size.

6.7 Hydraulic system

6.7.1 Empty body dump and return time

Specify:

- pump flow: at pressure and engine rated r/min;
- relief valve opening pressure: